

GRAPHIC OPERATION TERMINAL

GOT2000 Series

Connection Manual (Non-Mitsubishi Products 1)

For GT Works3 Version1



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|---|--|
| ■ IAI ROBOT CONTROLLER | ■ SHINKO TECHNOS INDICATING CONTROLLER |
| ■ AZBIL (former YAMATAKE) CONTROL EQUIPMENT | ■ CHINO CONTROLLER |
| ■ OMRON PLC | ■ TOSHIBA MACHINE PLC |
| ■ OMRON TEMPERATURE CONTROLLER | ■ TOSHIBA PLC |
| ■ KEYENCE PLC | ■ PANASONIC SERVO AMPLIFIER |
| ■ KOYO EI PLC | ■ PANASONIC INDUSTRIAL DEVICES |
| ■ JTEKT PLC | ■ SUNX PLC |
| ■ SHARP PLC | |

● SAFETY PRECAUTIONS ●

(Always read these precautions before using this equipment.)

Before using this product, please read this manual and the relevant manuals introduced in this manual carefully and pay full attention to safety to handle the product correctly.

The precautions given in this manual are concerned with this product.

In this manual, the safety precautions are ranked as "WARNING" and "CAUTION".




WARNING

Indicates that incorrect handling may cause hazardous conditions, resulting in death or severe injury.



CAUTION

Indicates that incorrect handling may cause hazardous conditions, resulting in medium or slight personal injury or physical damage.

Note that the  caution level may lead to a serious accident according to the circumstances. Always follow the instructions of both levels because they are important to personal safety.

Please save this manual to make it accessible when required and always forward it to the end user.

[DESIGN PRECAUTIONS]



WARNING

- Some failures of the GOT, communication unit or cable may keep the outputs on or off.
Some failures of a touch panel may cause malfunction of the input objects such as a touch switch.
An external monitoring circuit should be provided to check for output signals which may lead to a serious accident. Not doing so can cause an accident due to false output or malfunction.
 - Do not use the GOT as the warning device that may cause a serious accident.
An independent and redundant hardware or mechanical interlock is required to configure the device that displays and outputs serious warning.
Failure to observe this instruction may result in an accident due to incorrect output or malfunction.
 - When the GOT backlight has a failure, the GOT status will be as follows. Failure to observe this instruction may result in an accident due to incorrect output or malfunction.
 - GT27, GT25, GT23
When the GOT backlight has a failure, the POWER LED blinks (orange/blue) and the display section dims. In such a case, the input by the touch switch(s) is disabled.
 - GT21
When the GOT backlight has a failure, the display section dims. In such a case, the input by the touch switches is disabled.
- Even if the display section dims on the liquid crystal of the GOT, the input by the touch switch(s) may remain enabled. This may cause a malfunction of the touch switch.
- For example, if an operator assumes that the display section has dimmed because of the screen save function and touches the display section to cancel the screen save, a touch switch may be activated.
- The GOT backlight failure can be checked with a system signal of the GOT.

[DESIGN PRECAUTIONS]

WARNING

- The display section of the GOT is an analog-resistive type touch panel.
When multiple points of the display section are touched simultaneously, an accident may occur due to incorrect output or malfunction.
 - GT27
Do not touch three points or more simultaneously on the display section. Doing so may cause an accident due to an incorrect output or malfunction.
 - GT25, GT23, GT21
Do not touch two points or more simultaneously on the display section. Doing so may operate the switch located around the center of the touched point, or may cause an accident due to an incorrect output or malfunction.
- When programs or parameters of the controller (such as a PLC) that is monitored by the GOT are changed, be sure to reset the GOT, or turn on the unit again after shutting off the power as soon as possible.
Not doing so can cause an accident due to false output or malfunction.
- If a communication fault (including cable disconnection) occurs during monitoring on the GOT, communication between the GOT and PLC CPU is suspended and the GOT becomes inoperative.
For bus connection (GT27, GT25 Only) : The CPU becomes faulty and the GOT becomes inoperative.
For other than bus connection : The GOT becomes inoperative.
A system where the GOT is used should be configured to perform any significant operation to the system by using the switches of a device other than the GOT on the assumption that a GOT communication fault will occur.
Not doing so can cause an accident due to false output or malfunction.

[DESIGN PRECAUTIONS]



CAUTION

- Do not bundle the control and communication cables with main-circuit, power or other wiring. Run the above cables separately from such wiring and keep them a minimum of 100mm apart. Not doing so noise can cause a malfunction.
- Do not press the GOT display section with a pointed material as a pen or driver. Doing so can result in a damage or failure of the display section.
- When a GOT2000 series model and a GOT1000 series model are on an Ethernet network, do not set the IP address 192.168.0.18 for the GOTs and the controllers on this network. Doing so can cause IP address duplication at the GOT startup, adversely affecting the communication of the device with the IP address 192.168.0.18. The operation at the IP address duplication depends on the devices and the system.
- Turn on the controllers and the network devices to be ready for communication before they communicate with the GOT. Failure to do so can cause a communication error on the GOT.
- When the GOT is subject to shock or vibration, or some colors appear on the screen of the GOT, the screen of the GOT might flicker.

[MOUNTING PRECAUTIONS]



WARNING

- Be sure to shut off all phases of the external power supply used by the system before mounting or removing the GOT main unit to/from the panel. Not doing so can cause the unit to fail or malfunction.
- Be sure to shut off all phases of the external power supply used by the system before mounting or removing the option unit onto/from the GOT. (GT27, GT25 Only)

[MOUNTING PRECAUTIONS]

CAUTION

- Use the GOT in the environment that satisfies the general specifications described in this manual. Not doing so can cause an electric shock, fire, malfunction or product damage or deterioration.
- When mounting the GOT to the control panel, tighten the mounting screws in the specified torque range with a Phillips-head screwdriver No.2.
 - GT27, GT25, GT23
Specified torque range (0.36 N•m to 0.48 N•m)
 - GT21
Specified torque range (0.20 N•m to 0.25 N•m)Undertightening can cause the GOT to drop, short circuit or malfunction.
Overtightening can cause a drop, short circuit or malfunction due to the damage of the screws or the GOT.
- When mounting a unit on the GOT, tighten the mounting screws in the following specified torque range.
 - GT27, GT25
When loading the communication unit or option unit other than wireless LAN unit to the GOT, fit it to the connection interface of the GOT and tighten the mounting screws in the specified torque range (0.36 N•m to 0.48 N•m) with a Phillips-head screwdriver No.2.
When loading the wireless LAN unit to the GOT, fit it to the side interface of GOT and tighten the mounting screws in the specified torque range (0.10 N•m to 0.14 N•m) with a Phillips-head screwdriver No.1.
When the GOT is installed vertically, its side interface is positioned on the bottom.
To prevent the falling of the wireless LAN communication unit from the side interface, install or remove the unit while holding it with hands.
 - GT21
When mounting the SD card unit on the GOT, fit it to the side of the GOT and tighten the tapping screws in the specified torque range (0.3 N•m to 0.6 N•m) with a Phillips-head screwdriver No.2.
Under tightening can cause the GOT to drop, short circuit or malfunction.
Overtightening can cause a drop, failure or malfunction due to the damage of the screws or unit.
- When closing the USB environmental protection cover, fix the cover to the GOT by pushing the [PUSH] mark on the latch firmly to comply with the protective structure.(GT27, GT25 Only)
- Remove the protective film of the GOT.
When the user continues using the GOT with the protective film, the film may not be removed.
In addition, for the models equipped with the human sensor function, using the GOT with the protective film may cause the human sensor not to function properly
- Operate and store the GOT in environments without direct sunlight, high temperature, dust, humidity, and vibrations.
- When using the GOT in the environment of oil or chemicals, use the protective cover for oil.
Failure to do so may cause failure or malfunction due to the oil or chemical entering into the GOT.

[WIRING PRECAUTIONS]

WARNING

- Be sure to shut off all phases of the external power supply used by the system before wiring.
Failure to do so may result in an electric shock, product damage or malfunctions.

[WIRING PRECAUTIONS]

CAUTION

- Make sure to ground the FG terminal and LG terminal of the GOT power supply section to the protective ground conductors dedicated to the GOT with a ground resistance of 100 Ω or less. (GT21 does not have the LG terminal.)
- When tightening the terminal screws, use a Phillips-head screwdriver No.2.
- Tighten the terminal screws of the GOT power supply section in the following specified torque range.
 - GT27, GT25, GT23
Specified torque range (0.5 N•m to 0.8 N•m)
- For a terminal processing of a wire to the GOT power supply section, use the following terminal.
 - GT27, GT25, GT23
Use applicable solderless terminals for terminal processing of a wire and tighten them with the specified torque.
Not doing so can cause a fire, failure or malfunction.
 - GT21
Connect a stranded wire or a single wire directly, or use a rod terminal with an insulation sleeve.
- Correctly wire the GOT power supply section after confirming the rated voltage and terminal arrangement of the product.
Not doing so can cause a fire or failure.
- Tighten the terminal screws of the GOT power supply section in the following specified torque range.
 - GT27, GT25, GT23
Specified torque range (0.5 N•m to 0.8 N•m)
 - GT21
Specified torque range (0.22 N•m to 0.25 N•m)
- Exercise care to avoid foreign matter such as chips and wire offcuts entering the GOT.
Not doing so can cause a fire, failure or malfunction.
- The module has an ingress prevention label on its top to prevent foreign matter, such as wire offcuts, from entering the module during wiring.
Do not peel this label during wiring. Before starting system operation, be sure to peel this label because of heat dissipation. (GT27, GT25 Only)
- Plug the communication cable into the GOT interface or the connector of the connected unit, and tighten the mounting screws and the terminal screws in the specified torque range.
Undertightening can cause a short circuit or malfunction.
Overtightening can cause a short circuit or malfunction due to the damage of the screws or unit.
- Plug the QnA/ACPU/Motion controller (A series) bus connection cable by inserting it into the connector of the connected unit until it "clicks".
After plugging, check that it has been inserted snugly.
Not doing so can cause a malfunction due to a contact fault. (GT27, GT25 Only)

[TEST OPERATION PRECAUTIONS]

WARNING

- Before performing the test operations of the user creation monitor screen (such as turning ON or OFF bit device, changing the word device current value, changing the settings or current values of the timer or counter, and changing the buffer memory current value), read through the manual carefully and make yourself familiar with the operation method.
During test operation, never change the data of the devices which are used to perform significant operation for the system.
False output or malfunction can cause an accident.

[STARTUP/MAINTENANCE PRECAUTIONS]

WARNING

- When power is on, do not touch the terminals.
Doing so can cause an electric shock or malfunction.
- Correctly connect the battery connector.
Do not charge, disassemble, heat, short-circuit, solder, or throw the battery into the fire.
Doing so will cause the battery to produce heat, explode, or ignite, resulting in injury and fire.
- Before starting cleaning or terminal screw retightening, always switch off the power externally in all phases.
Not switching the power off in all phases can cause a unit failure or malfunction.
Undertightening can cause a short circuit or malfunction.
Overtightening can cause a short circuit or malfunction due to the damage of the screws or unit.

[STARTUP/MAINTENANCE PRECAUTIONS]



CAUTION

- Do not disassemble or modify the unit.
Doing so can cause a failure, malfunction, injury or fire.
- Do not touch the conductive and electronic parts of the unit directly.
Doing so can cause a unit malfunction or failure.
- The cables connected to the unit must be run in ducts or clamped.
Not doing so can cause the unit or cable to be damaged due to the dangling, motion or accidental pulling of the cables or can cause a malfunction due to a cable connection fault.
- When unplugging the cable connected to the unit, do not hold and pull from the cable portion.
Doing so can cause the unit or cable to be damaged or can cause a malfunction due to a cable connection fault.
- Do not drop the module or subject it to strong shock. A module damage may result.
- Do not drop or give an impact to the battery mounted to the unit.
Doing so may damage the battery, causing the battery fluid to leak inside the battery.
If the battery is dropped or given an impact, dispose of it without using.
- Before touching the unit, always touch grounded metals, etc. to discharge static electricity from human body, etc.
Not doing so can cause the unit to fail or malfunction.
- Use the battery manufactured by Mitsubishi Electric Corporation.
Use of other batteries may cause a risk of fire or explosion.
- Dispose of used battery promptly.
Keep away from children. Do not disassemble and do not dispose of in fire.
- Be sure to shut off all phases of the external power supply before replacing the battery or using the dip switch of the terminating resistor.
Not doing so can cause the unit to fail or malfunction by static electricity.

[TOUCH PANEL PRECAUTIONS]



CAUTION

- For the analog-resistive film type touch panels, normally the adjustment is not required.
However, the difference between a touched position and the object position may occur as the period of use elapses.
When any difference between a touched position and the object position occurs, execute the touch panel calibration.
- When any difference between a touched position and the object position occurs, other object may be activated.
This may cause an unexpected operation due to incorrect output or malfunction.

[PRECAUTIONS WHEN THE DATA STORAGE IS IN USE]

WARNING

- If the SD card is removed from drive A of the GOT while being accessed by the GOT, the GOT may stop processing data for about 20 seconds.
The GOT cannot be operated during this period.
The functions that run in the background including a screen updating, alarm, logging, scripts, and others are also interrupted.
Remove the SD card after checking the following items.
 - GT27, GT25, GT23
After checking the light off of SD card access LED, remove the SD card.
 - GT21
After disabling SD card access on the utility screen of the GOT and checking that the SD card access LED is off, remove the SD card.

CAUTION

- If the data storage is removed from the GOT while being accessed by the GOT, the data storage and files may be damaged.
Before removing the data storage from the GOT, check the SD card access LED, system signal, or others to make sure that the data storage is not accessed.
- Turning off the GOT while it accesses the SD card results in damage to the SD card and files.
- When using the GOT with an SD card inserted, check the following items.
 - GT27, GT25, GT23
When inserting a SD card into the GOT, make sure to close the SD card cover.
Failure to do so causes the data not to be read or written.
 - GT21
When using an SD card connected to the SD card unit or the GOT, enable the SD card access in the GOT utility in advance.
Failure to do so causes the data not to be read or written.
- When removing the SD card from the GOT, make sure to support the SD card by hand as it may pop out.
Failure to do so may cause the SD card to drop from the GOT, resulting in a failure or break.
- When inserting a USB device into a USB interface of the GOT, make sure to insert the device into the interface firmly.
Failure to do so may cause the USB device to drop from the GOT, resulting in a failure or break.
- Before removing the USB device from the GOT, follow the procedure for removal on the utility screen of the GOT.
After the successful completion dialog is displayed, remove the USB device by hand carefully.
Failure to do so may cause the USB device to drop from the GOT, resulting in a failure or break.

[PRECAUTIONS FOR REMOTE CONTROL]



WARNING

- Remote control is available through a network by using GOT functions, including theSoftGOT-GOT link function, the remote personal computer operation function, the VNC server function, and the GOT Mobile function.

If these functions are used to perform remote control of control equipment, the field operator may not notice the remote control, possibly leading to an accident.

In addition, a communication delay or interruption may occur depending on the network environment, and remote control of control equipment cannot be performed normally in some cases. Before using the above functions to perform remote control, fully grasp the circumstances of the field site and ensure safety.

[DISPOSAL PRECAUTIONS]



CAUTION

- When disposing of this product, treat it as industrial waste.
When disposing of batteries, separate them from other wastes according to the local regulations. (Refer to the GOT2000 Series User's Manual (Hardware) for details of the battery directive in the EU member states.)

[TRANSPORTATION PRECAUTIONS]



CAUTION

- When transporting lithium batteries, make sure to treat them based on the transport regulations. (Refer to the GOT2000 Series User's Manual (Hardware) for details of the regulated models.)
- Make sure to transport the GOT main unit and/or relevant unit(s) in the manner they will not be exposed to the impact exceeding the impact resistance described in the general specifications of this manual, as they are precision devices.
Failure to do so may cause the unit to fail.
Check if the unit operates correctly after transportation.
- When fumigants that contain halogen materials such as fluorine, chlorine, bromine, and iodine are used for disinfecting and protecting wooden packaging from insects, they cause malfunction when entering our products.
Please take necessary precautions to ensure that remaining materials from fumigant do not enter our products, or treat packaging with methods other than fumigation (heat method).
Additionally, disinfect and protect wood from insects before packing products.

INTRODUCTION

Thank you for choosing Mitsubishi Graphic Operation Terminal (Mitsubishi GOT).

Read this manual and make sure you understand the functions and performance of the GOT thoroughly in advance to ensure correct use.

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REVISIONS

WARRANTY

List of Manuals for GT Works3

For the manuals related to this product, install the manuals with the drawing software.
If you need a printed manual, consult your local Mitsubishi representative or branch office.

■ 1. List of Manuals for GT Designer3(GOT2000)

(1) Screen drawing software manuals

Manual name	Manual number (Model code)	Format
GT Works3 Version1 Installation Procedure Manual	-	PDF
GT Designer3 (GOT2000) Screen Design Manual	SH-081220ENG (1D7ML9)	PDF, e-Manual
GT Converter2 Version3 Operating Manual for GT Works3	SH-080862ENG (1D7MB2)	PDF
GOT2000 Series MES Interface Function Manual for GT Works3 Version1	SH-081228ENG	PDF

(2) Connection manuals

Manual name	Manual number (Model code)	Format
GOT2000 Series Connection Manual (Mitsubishi Products) For GT Works3 Version1	SH-081197ENG (1D7MJ8)	PDF
GOT2000 Series Connection Manual (Non-Mitsubishi Products 1) For GT Works3 Version1	SH-081198ENG	PDF
GOT2000 Series Connection Manual (Non-Mitsubishi Products 2) For GT Works3 Version1	SH-081199ENG	PDF
GOT2000 Series Connection Manual (Microcomputers, MODBUS/Fieldbus Products, Peripherals) For GT Works3 Version1	SH-081200ENG	PDF

(3) GT SoftGOT2000 manuals

Manual name	Manual number (Model code)	Format
GT SoftGOT2000 Version1 Operating Manual	SH-081201ENG	PDF

(4) GOT2000 manuals

Manual name	Manual number (Model code)	Format
GOT2000 Series User's Manual (Hardware)	SH-081194ENG (1D7MJ5)	PDF, e-Manual
GOT2000 Series User's Manual (Utility)	SH-081195ENG (1D7MJ6)	PDF, e-Manual
GOT2000 Series User's Manual (Monitor)	SH-081196ENG (1D7MJ7)	PDF, e-Manual

POINT

e-Manual

e-Manual refers to the Mitsubishi FA electronic book manuals that can be browsed using a dedicated tool.
















e-Manual has the following features:

- Required information can be cross-searched in multiple manuals.
- Other manuals can be accessed from the links in the manual.
- Hardware specifications of each part can be found from the product figures.
- Pages that users often browse can be bookmarked.

Abbreviations, Generic Terms, the meaning of the icon

The following shows the abbreviations and generic terms used in Help.

1. GOT

Abbreviations and generic terms				Description	Meaning of icon						
					Support	Not support					
GOT2000 Series	GT27	GT27-X	GT2715-X	GT2715-XTBA, GT2715-XTBD		-					
		GT27-S	GT2712-S	GT2712-STBA, GT2712-STWA, GT2712-STBD, GT2712-STWD							
			GT2710-S	GT2710-STBA, GT2710-STBD							
		GT27-V	GT2710-V	GT2710-VTBA, GT2710-VTWA, GT2710-VTBD, GT2710-VTWD							
		GT27-V	GT2708-S	GT2708-STBA, GT2708-STBD							
			GT2708-V	GT2708-VTBA, GT2708-VTBD							
			GT2705-V	GT2705-VTBD							
	GT25	GT25-S	GT2512-S	GT2512-STBA, GT2512-STBD		-					
			GT2512F-S	GT2512F-STNA, GT2512F-STND							
		GT25-V	GT2510-V	GT2510-VTBA, GT2510-VTWA, GT2510-VTBD, GT2510-VTWD							
			GT2510F-V	GT2510F-VTNA, GT2510F-VTND							
			GT2508-V	GT2508-VTBA, GT2508-VTWA, GT2508-VTBD, GT2508-VTWD							
			GT2508F-V	GT2508F-VTNA, GT2508F-VTND							
	GT23	GT23-V	GT2310-V	GT2310-VTBA, GT2310-VTBD		-					
			GT2308-V	GT2308-VTBA, GT2308-VTBD							
				GT21		-					
	GT21	GT21-Q	GT2105-Q	GT2105-QTBDS GT2105-QMBDS		-					
		GT21-R	GT2104-R	GT2104-RTBD		-					
		GT2104-P		GT2104-PMBD		-					
				GT2104-PMBDS		-					
				GT2104-PMBDS2		-					
				GT2104-PMBLS		-					
		GT2103-P		GT2103-PMBD		-					
				GT2103-PMBDS		-					
				GT2103-PMBDS2		-					
				GT2103-PMBLS		-					
	GT SoftGOT2000			GT SoftGOT2000 Version1		-					
GOT1000 Series				GOT1000 Series	-	-					
GOT900 Series				GOT-A900 Series, GOT-F900 Series	-	-					
GOT800 Series				GOT-800 Series	-	-					

■2. Communication unit

Abbreviations and generic terms		Description
Bus connection unit		GT15-QBUS, GT15-QBUS2, GT15-ABUS, GT15-ABUS2, GT15-75QBUSL, GT15-75QBUS2L, GT15-75ABUSL, GT15-75ABUS2L
Serial communication unit		GT15-RS2-9P, GT15-RS4-9S, GT15-RS4-TE
MELSECNET/H communication unit		GT15-J71LP23-25, GT15-J71BR13
CC-Link IE Controller Network communication unit		GT15-J71GP23-SX
CC-Link IE Field Network communication unit		GT15-J71GF13-T2
CC-Link communication unit		GT15-J61BT13
Wireless LAN communication unit		GT25-WLAN
Serial multi-drop connection unit		GT01-RS4-M
Connection conversion adapter		GT10-9PT5S
Field network adapter unit		GT25-FNADP
Ethernet communication unit		GT25-J71E71-100

■3. Option unit

Abbreviations and generic terms		Description
Printer unit		GT15-PRN
Video/RGB unit	Video input unit	GT27-V4-Z (A set of GT16M-V4-Z and GT27-IF1000)
	RGB input unit	GT27-R2, GT27-R2-Z (A set of GT16M-R2-Z and GT27-IF1000)
	Video/RGB input unit	GT27-V4R1-Z (A set of GT16M-V4R1-Z and GT27-IF1000)
	RGB output unit	GT27-ROUT, GT27-ROUT-Z (A set of GT16M-ROUT-Z and GT27-IF1000)
Multimedia unit		GT27-MMR-Z (A set of GT16M-MMR-Z and GT27-IF1000)
Video signal conversion unit		GT27-IF1000
External I/O unit		GT15-DIO, GT15-DIOR
Sound output unit		GT15-SOUT

■4. Option

Abbreviations and generic terms		Description
SD card		NZ1MEM-2GBSD, NZ1MEM-4GBSD, NZ1MEM-8GBSD, NZ1MEM-16GBSD, L1MEM-2GBSD, L1MEM-4GBSD
Battery		GT11-50BAT
Protective sheet		GT27-15PSGC, GT25-12PSGC, GT25-10PSGC, GT25-08PSGC, GT25-05PSGC, GT21-05PSGC, GT21-04RPSGC-UC, GT21-03PSGC-UC, GT21-04PSGC-UC, GT27-15PSCC, GT25-12PSCC, GT25-10PSCC, GT25-08PSCC, GT25-12PSCC-UC, GT25-10PSCC-UC, GT25-08PSCC-UC, GT25-05PSCC, GT21-05PSCC, GT21-04RPSCC-UC, GT21-04PSCC-UC, GT21-03PSCC-UC
Environmental protection sheet		GT25F-12ESGS, GT25F-10ESGS, GT25F-08ESGS
Protective cover for oil		GT20-15PCO, GT20-12PCO, GT20-10PCO, GT20-08PCO, GT25-05PCO, GT21-04RPCO, GT10-30PCO, GT10-20PCO, GT05-50PCO
USB environmental protection cover		GT25-UCOV, GT25-05UCOV
Stand		GT15-90STAND, GT15-80STAND, GT15-70STAND, GT15-60STAND
Attachment		GT15-70ATT-98, GT15-70ATT-87, GT15-60ATT-97, GT15-60ATT-96, GT15-60ATT-87, GT15-60ATT-77

■ 5. Software

(1) Software related to GOT

Abbreviations and generic terms	Description
GT Works3	SW1DND-GTWK3-J, SW1DND-GTWK3-E, SW1DND-GTWK3-C
GT Designer3 Version1	Screen drawing software GT Designer3 for GOT2000/GOT1000 series
GT Designer3	Screen drawing software for GOT2000 series included in GT Works3
GT Designer3 (GOT2000)	
GT Designer3 (GOT1000)	Screen drawing software for GOT1000 series included in GT Works3
GT Simulator3	Screen simulator GT Simulator3 for GOT2000/GOT1000/GOT900 series
GT SoftGOT2000	Monitoring software GT SoftGOT2000 series
GT Converter2	Data conversion software GT Converter2 for GOT1000/GOT900 series
GT Designer2 Classic	Screen drawing software GT Designer2 Classic for GOT900 series
GT Designer2	Screen drawing software GT Designer2 for GOT1000/GOT900 series
DU/WIN	Screen drawing software FX-PCS-DU/WIN for GOT-F900 series

(2) Software related to iQ Works

Abbreviations and generic terms	Description
iQ Works	Abbreviation of iQ Platform compatible engineering environment MELSOFT iQ Works
MELSOFT Navigator	Generic term for integrated development environment software included in the SW DNC-IQWK (iQ Platform compatible engineering environment MELSOFT iQ Works) (□ indicates a version.)
MELSOFT iQ AppPortal	SW□DND-IQAPL-M type integrated application management software (□ indicates a version.)

(3) Other software

Abbreviations and generic terms		Description
GX Works3		SW□DND-GXW3-E (-EA) type programmable controller engineering software (□ indicates a version.)
GX Works2		SW□DNC-GXW2-□ type programmable controller engineering software (□ indicates a version.)
Controller simulator	GX Simulator3	Simulation function of GX Works3
	GX Simulator2	Simulation function of GX Works2
	GX Simulator	SW□D5C-LLT-E (-EV) type ladder logic test tool function software package (SW5D5C-LLT (-V) or later versions) (□ indicates a version.)
GX Developer		SW□D5C-GPPW-E (-EV)/SW□D5F-GPPW (-V) type software package (□ indicates a version.)
GX LogViewer		SW□DNN-VIEWER-E type software package (□ indicates a version.)
PX Developer		SW□D5C-FBDQ-E type FBD software package for process control (□ indicates a version.)
MT Works2		Motion controller engineering environment MELSOFT MT Works2 (SW□DND-MTW2-E) (□ indicates a version.)
MT Developer		SW□RNC-GSV type integrated start-up support software for motion controller Q series (□ indicates a version.)
CW Configurator		C Controller module configuration and monitor tool (SW1DND-RCCPU-E) (□ indicates a version.)
MR Configurator2		SW□DNC-MRC2-E type servo configuration software (□ indicates a version.)
MR Configurator		MRZJW□-SETUP type servo configuration software (□ indicates a version.)
FR Configurator		Inverter setup software (FR-SW□-SETUP-WE) (□ indicates a version.)
NC Configurator2		CNC parameter setting support tool (FCSB1221)
NC Configurator		CNC parameter setting support tool
FX Configurator-FP		Parameter setting, monitoring, and testing software packages for FX3U- 20SSC-H (SW□D5CFXSSCE) (□ indicates a version.)
FX3U-ENET-L Configuration tool		FX3U-ENET-L type Ethernet module setting software (SW1D5-FXENETL-E)
RT ToolBox2		Robot program creation software (3D-11C-WINE)
MX Component		MX Component Version□ (SW□D5C-ACT-E, SW□D5C-ACT-EA) (□ indicates a version.)
MX Sheet		MX Sheet Version□ (SW□D5C-SHEET-E, SW□D5C-SHEET-EA) (□ indicates a version.)
CPU Module Logging Configuration Tool		CPU module logging configuration tool (SW1DNN-LLUTL-E)

■ 6. License key (for GT SoftGOT2000)

Abbreviations and generic terms	Description
License key	GT27-SGTKEY-U

■ 7. Others

Abbreviations and generic terms	Description
IAI	IAI Corporation
AZBIL	Azbil Corporation
OMRON	OMRON Corporation
KEYENCE	KEYENCE CORPORATION
KOYO EI	KOYO ELECTRONICS INDUSTRIES CO., LTD.
JTEKT	JTEKT Corporation
SHARP	Sharp Manufacturing Systems Corporation
SHINKO	Shinko Technos Co., Ltd.
CHINO	CHINO CORPORATION
TOSHIBA	TOSHIBA CORPORATION
TOSHIBA MACHINE	TOSHIBA MACHINE CO., LTD.
PANASONIC	Panasonic Corporation
PANASONIC IDS	Panasonic Industrial Devices SUNX Co., Ltd.
HITACHI IES	Hitachi Industrial Equipment Systems Co., Ltd.
HITACHI	Hitachi, Ltd.
FUJI	FUJI ELECTRIC CO., LTD.
YASKAWA	YASKAWA Electric Corporation
YOKOGAWA	Yokogawa Electric Corporation
RKC	RKC INSTRUMENT INC.
ALLEN-BRADLEY	Allen-Bradley products manufactured by Rockwell Automation, Inc.
CLPA	CC-Link Partner Association
GE	GE Intelligent Platforms, Inc.
HMS	HMS Industrial Networks
LS IS	LS Industrial Systems Co., Ltd.
MITSUBISHI INDIA	Mitsubishi Electric India Pvt. Ltd.
ODVA	Open DeviceNet Vendor Association, Inc.
SCHNEIDER	Schneider Electric SA
SICK	SICK AG
SIEMENS	Siemens AG
PLC	Programmable controller manufactured by each corporation
Control equipment	Control equipment manufactured by each corporation
Temperature controller	Temperature controller manufactured by each corporation
Indicating controller	Indicating controller manufactured by each corporation
Controller	Controller manufactured by each corporation

1. PREPARATORY PROCEDURES FOR MONITORING

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1. PREPARATORY PROCEDURES FOR MONITORING

The following shows the procedures to be taken before monitoring and corresponding reference sections.

- Step 1.** Setting the communication interface
Determine the connection type and channel No. to be used, and perform the communication setting.
- ➡ 1.1 Setting the Communication Interface
 - ➡ Each chapter GOT Side Settings
- Step 2.** Writing the project data and OS
Write the standard monitor OS, communication driver, extended function OS, project data and communication settings onto the GOT.
- ➡ 1.2.1 Writing the project data and OS onto the GOT
- Step 3.** Verifying the project data and OS
Verify the standard monitor OS, communication driver, extended function OS, project data and communication settings are properly written onto the GOT.
- ➡ 1.2.2 Checking the project data and OS writing on GOT
- Step 4.** Attaching the communication unit and connecting the cable
Mount the optional equipment and prepare/connect the connection cable according to the connection type.
- ➡ 1.3 Option Devices for the Respective Connection
 - ➡ 1.4 Connection Cables for the Respective Connection
 - ➡ Each chapter System Configuration
 - ➡ Each chapter Connection Diagram
- Step 5.** Verifying GOT recognizes connected equipment
Verify the GOT recognizes controllers on [Communication Settings] of the Utility.
- ➡ 1.5 Verifying GOT Recognizes Connected Equipment
- Step 6.** Verifying the GOT is monitoring normally
Verify the GOT is monitoring normally using Utility, Developer, etc.
- ➡ 1.6 Checking for Normal Monitoring

1.1 Setting the Communication Interface

Set the communication interface of GOT and the connected equipment.

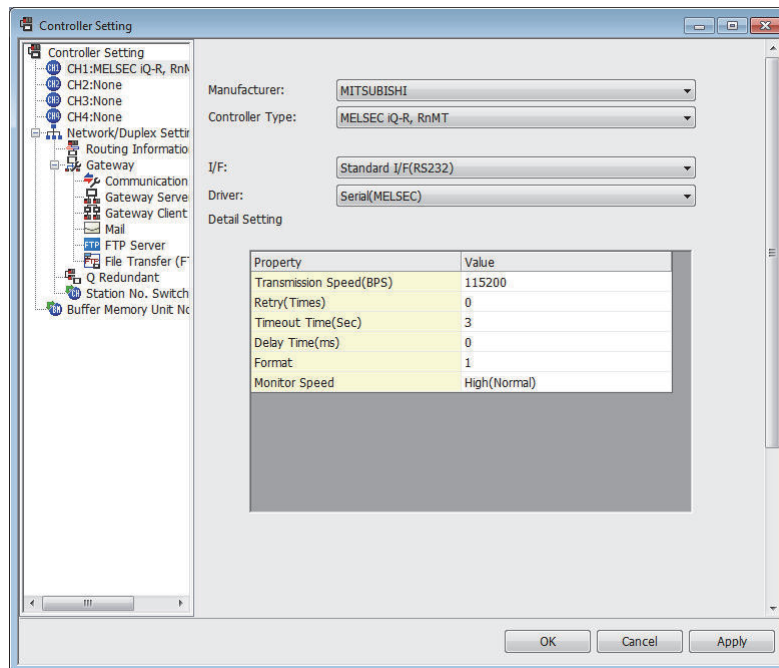
When using the GOT at the first time, make sure to set the channel of communication interface and the communication driver before writing to GOT.

Set the communication interface of the GOT at [Controller Setting] and [I/F Communication Setting] in GT Designer3.

1.1.1 Setting connected equipment (Channel setting)

Set the channel of the equipment connected to the GOT.

■ 1. Setting



Step 1. Select [Common] → [Controller Setting] from the menu.

Step 2. The Controller Setting dialog box appears. Select the channel No. to be used from the list menu.

Step 3. Refer to the following explanations for the setting.

POINT

Channel No.2 to No.4

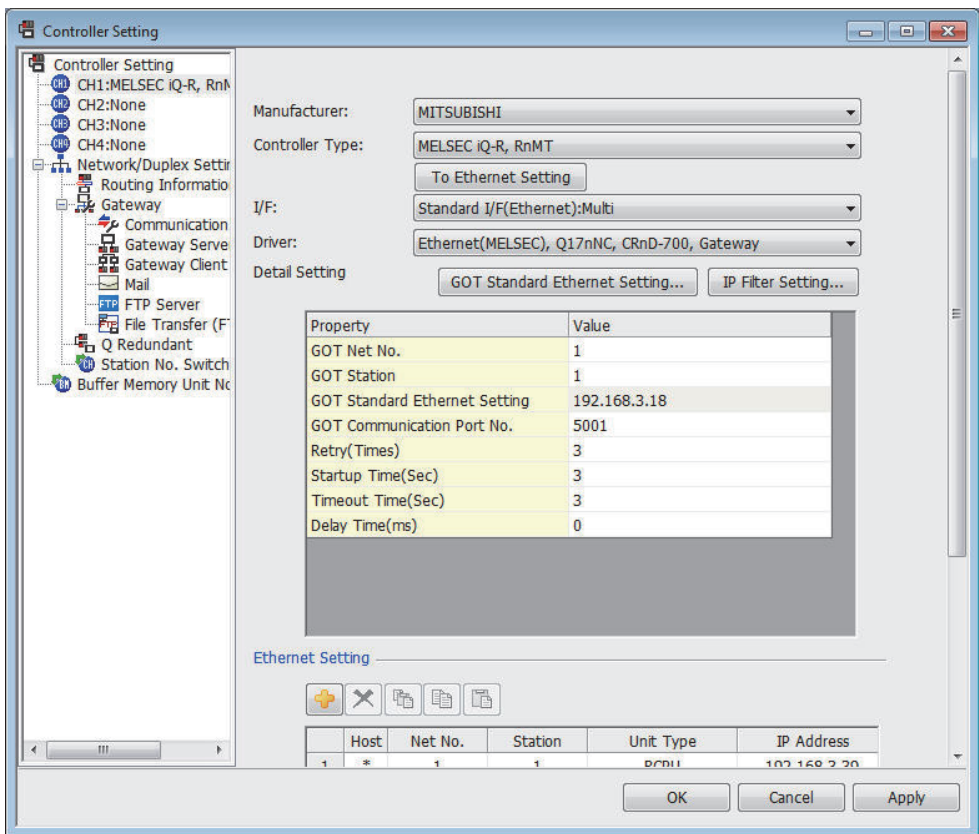
Use the channel No.2 to No.4 when using the Multi-channel function.

For details of the Multi-channel function, refer to the following.

➡ Mitsubishi Products 19. MULTI-CHANNEL FUNCTION

2. Setting item

This section describes the setting items of the Manufacturer, Controller Type, Driver and I/F. When using the channel No.2 to No.4, put a check mark at [Use CH*].



Item	Description
Use CH*	Select this item when setting the channel No.2 to No.4.
Manufacturer	Select the manufacturer of the equipment to be connected to the GOT.
Type	Select the type of the equipment to be connected to the GOT. For the settings, refer to the following. ➡ (2)Setting [Controller Type]
I/F	Select the interface of the GOT to which the equipment is connected. For the settings, refer to the following. ➡ (3)Setting [I/F]
Driver	Select the communication driver to be written to the GOT. For the settings, refer to the following. ➡ (1)Setting [Driver]
Detail Setting	Make settings for the transmission speed and data length of the communication driver. ➡ Refer to each chapter of the equipment to be connected to the GOT.

(1) Setting [Driver]

The displayed items for a driver differ according to the settings [Manufacturer], [Controller Type] and [I/F]. When the driver to be set is not displayed, confirm if [Manufacturer], [Controller Type] and [I/F] are correct. For the settings, refer to the following.

➡ [Setting the communication interface] section in each chapter

(2) Setting [Controller Type]

The types for the selection differs depending on the PLC to be used.
For the settings, refer to the following.

Type	Model name
IAI X-SEL CONTROLLER	XSEL-J
	XSEL-K
	XSEL-KE
	XSEL-KT
	XSEL-KET
	XSEL-P
	XSEL-Q
	XSEL-JX
	XSEL-KX
	XSEL-KTX
	XSEL-PX
	XSEL-QX
	SSEL
	ASEL
	PSEL
IAI ROBO CYLINDER	PCON-C
	PCON-CG
	PCON-CF
	PCON-CY
	PCON-SE
	PCON-PL
	PCON-CA
	PCON-PO
	ACON-C
	ACON-CG
	ACON-CY
	ACON-SE
	ACON-PL
	ACON-PO
	SCON-C
	SCON-CA
	ERC2

Type	Model name
AZBIL SDC/DMC Series	DMC10
	DMC50
	SDC15
	SDC25
	SDC26
	SDC35
	SDC36
	SDC20
	SDC21
	SDC30
	SDC31
	SDC40A
	SDC40B
	SDC40G
	SDC45
	SDC46
	CMS
	CMF015
	CMF050
	CML
	MQV
	MPC
	MVF
	PBC201-VN2
	AUR350C
	AUR450C
	RX
	CMC10B
	AHC2001

Type	Model name
OMRON SYSMAC	CPM1
	CPM1A
	CPM2A
	CPM2C
	CQM1
	CQM1H
	CJ1H
	CJ1G
	CJ1M
	CP1H
	CP1L
	CP1E
	C200HS
	C200H
	C200HX
	C200HG
	C200HE
	CS1H
	CS1G
	CS1D
	C1000H
	C2000H
	CV500
	CV1000
	CV2000
	CVM1
OMRON SYSMAC CS/CJ	CS1H
	CS1G
	CS1D
	CJ1H
	CJ1G
	CJ1M
	CJ2H
	CJ2M
OMRON THERMAC/INPANEL NEO	E5AN
	E5EN
	E5CN
	E5GN
	E5ZN
KEYENCE KV-700/1000/3000/5000	KV-700
	KV-1000
	KV-3000
	KV-5000
	KV-5500

Type	Model name
SHARP JW	JW-21CU
	JW-31CUH
	JW-50CUH
	JW-22CU
	JW-32CUH
	JW-33CUH
	JW-70CUH
	JW-100CUH
	JW-100CU
	Z-512J
TOSHIBA MACHINE Tcmini	TC3-01
	TC3-02
	TC5-02
	TC5-03
	TC6-00
	TC8-00
	TS2000
	TS2100
KOYO KOSTAC/DL	SU-5E
	SU-6B
	SU-5M
	SU-6M
	PZ3
	D2-240
	D2-250-1
	D2-260
	D0-05AA
	D0-05AD
	D0-05AR
	D0-05DA
	D0-05DD
	D0-05DD-D
	D0-05DR
	D0-05DR-D
	D0-06DD1
	D0-06DD2
	D0-06DR
	D0-06DA
	D0-06AR
	D0-06AA
	D0-06DD1-D
	D0-06DD2-D
	D0-06DR-D

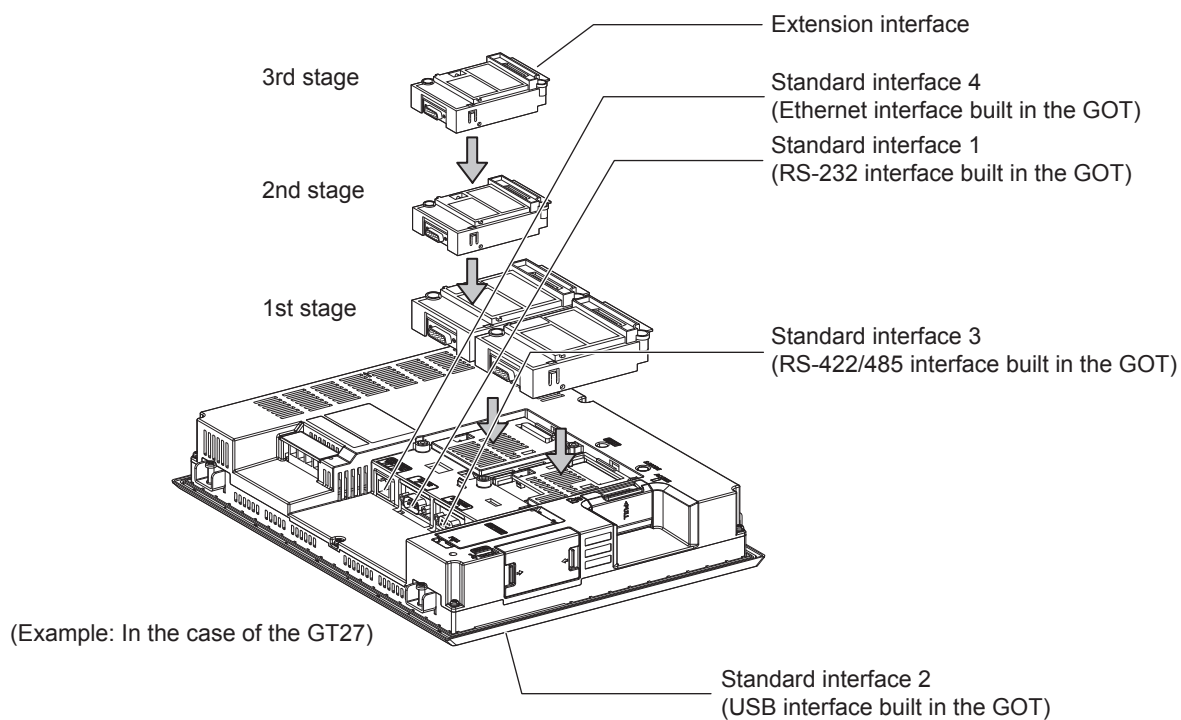
Type	Model name
JTEKT TOYOPUC-PC Series	PC3JG-P-CPU
	PC3JG-CPU
	PC3J-CPU
	PC3JL-CPU
	PC2JC-CPU
	PC2J16P-CPU
	PC2J16PR-CPU
	PC2J-CPU
	PC2JS-CPU
	PC2JR-CPU
CHINO Controllers	LT350
	LT370
	LT450
	LT470
	DZ1000
	DZ2000
	LT230
	LT830
	DB1000
	DB2000
	GT120
TOSHIBA PROSEC T/V Series	T2 (PU224)
	T3
	T3H
	T2E
	T2N
	model 2000(S2)
	model 2000(S2T)
	model 2000(S2E)
	model 3000 (S3)
TOSHIBA Unified Controller nv Series	Controller type1 PU811
PANASONIC MINAS-A4 Series	MINAS A4
	MINAS A4F
	MINAS A4L

Type	Model name
PANASONIC INDUSTRIAL DEVICES SUNX MEWNET-FP Series	FP0-C16CT
	FP0-C32CT
	FP0R
	FP1-C24C
	FP1-C40C
	FP2
	FP2SH
	FP3
	FP5
	FP10(S)
	FP10SH
	FP-M(C20TC)
	FP-M(C32TC)
	FP-Σ
	FP-X
Shinko Technos Controller Series	ACS-13A□/□,□,□, C5
	JCS-33A-□/□□, C5
	JCR-33A-□/□□, C5
	JCD-33A-□/□□, C5
	JCM-33A□/□,□ C5
	JIR-301-M□, C5
	PCD-33A-□/□, C5
	PC935-□/□, C5
	PC955-□/□, C5
	PC935-□/□, C
	PC955-□/□, C
	FCD-13A-□/□, C
	FCD-15A-□/□, C
	FCR-13A-□/□, C
	FCR-15A-□/□, C
	FCR-23A-□/□, C
	FIR-201-M, C
	DCL-33A-□/□,□, C5

(3) Setting [I/F]

The interface differs depending on the GOT to be used.

Set the I/F according to the connection and the position of communication unit to be mounted onto the GOT.



1.1.2 I/F communication setting

This function displays the list of the GOT communication interfaces.
Set the channel and the communication driver to the interface to be used.

■ 1. Setting

Standard I/F Setting		
	CH No.	Driver
I/F-1: RS422/485	1	Serial(MELSEC)
I/F-2: RS232	0	None
I/F-3: USB	9	Host (PC)
I/F-4: Ethernet	0	None

RS232 Setting

☐ Enable the 5V power supply

Extend I/F Setting		
	CH No.	Driver
1st	0	None
2nd	0	None
3rd	0	None
Wireless LAN	0	None

Step 1. Select [Common] → [I/F Communication Setting] from the menu.

Step 2. The I/F Communication Setting dialog box appears. Make the settings with reference to the following explanation.

2. Setting item

The following describes the setting items for the standard I/F setting and extension I/F setting.

When the GT21 series is selected in the GOT type setting

I/F-1: RS422/485/232(Side)
I/F-2: RS232(Back)

Item	Description
Standard I/F setting	Set channel No. and drivers to the GOT standard interfaces.
CH No.	Set the CH No. according to the intended purpose. 0: Not used 1 to 4: Used for connecting a controller of channel No. 1 to 4 set in Setting connected equipment (Channel setting) 5 to 8: Used for barcode function, RFID function, remote personal computer operation function (serial) 9: Used for connecting Host (PC), Ethernet download A: Used for the report function (with a serial printer), hard copy function (with a serial printer), remote personal computer operation function (Ethernet), VNC server function, gateway function, and MES interface function. Multi: Used for multi-channel Ethernet connection
I/F	The communication type of the GOT standard interface is displayed.
Driver	Set the driver for the device to be connected. • None • Host (Personal computer) • Each communication driver for connected devices
Detail Setting	Make settings for the transmission speed and data length of the communication driver. ➡ Refer to each chapter of the equipment to be connected to the GOT.
RS232 Setting	To validate the 5V power supply function in RS232, mark the [Enable the 5V power supply] checkbox. The RS232 setting is invalid when the CH No. of [I/F-1: RS232] is [9]. GT21 is not supported.
Extension I/F setting	Set the communication unit attached to the extension interface of the GOT. GT21 is not supported.
CH No.	Set the CH No. according to the intended purpose. The number of channels differs depending on the GOT to be used. 0: Not used 1 to 4: Used for connecting a controller of channel No. 1 to 4 set in Setting connected equipment (Channel setting) 5 to 8: Used for barcode function, RFID function, remote personal computer operation (serial) A: Used for the video/RGB display function, multimedia function, external I/O function, operation panel function, RGB output function, report function, hard copy function (with a printer), sound output function, gateway function, MES interface function, and wireless LAN connection.

POINT

Channel No., drivers, [RS232 Setting]

(1) Channel No.2 to No.4

Use the channel No.2 to No.4 when using the Multi-channel function.

For details of the Multi-channel function, refer to the following.

➡ Mitsubishi Products 19. MULTI-CHANNEL FUNCTION

(2) Drivers

The displayed items for a driver differ according to the settings [Manufacturer], [Controller Type] and [I/F].

When the driver to be set is not displayed, confirm if [Manufacturer], [Controller Type] and [I/F] are correct.

➡ [Setting the communication interface] section in each chapter

1.1.3 Precautions

■ 1. Precautions for changing model

(1) **When devices that cannot be converted are included.**

When setting of [Manufacturer] or [Controller Type] is changed, GT Designer3 displays the device that cannot be converted (no corresponding device type, or excessive setting ranges) as [??]. In this case, set the device again.

(2) **When the changed Manufacturer or Controller Type does not correspond to the network.**

The network will be set to the host station.

(3) **When the Manufacturer or Controller Type is changed to [None]**

The GT Designer3 displays the device of the changed channel No. as [??]. In this case, set the device again. Since the channel No. is retained, the objects can be reused in other channel No. in a batch by using the [Device Batch Edit], [CH No. Batch Edit] or [Device List].

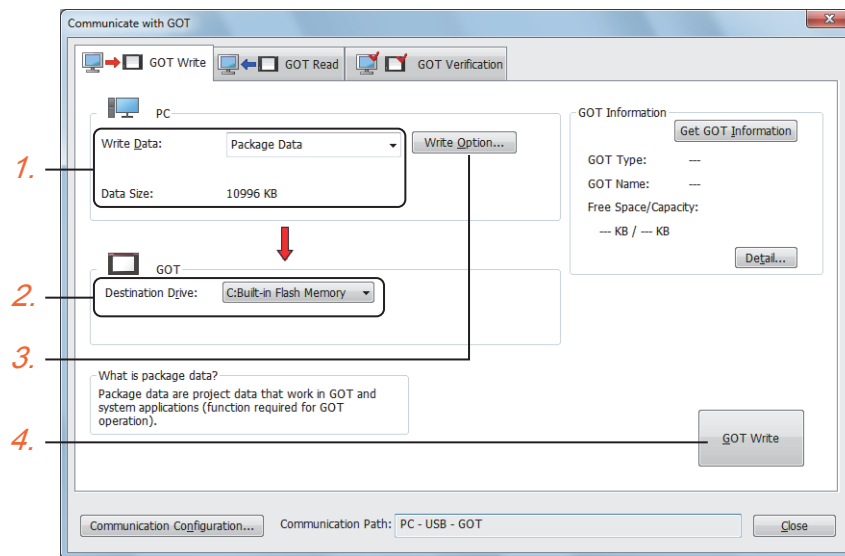
1.2 Writing the Project Data onto the GOT

Write the package data onto the GOT.

For details on writing to GOT, refer to the following manual.

➡ GT Designer3 (GOT2000) Screen Design Manual

1.2.1 Writing the project data and OS onto the GOT

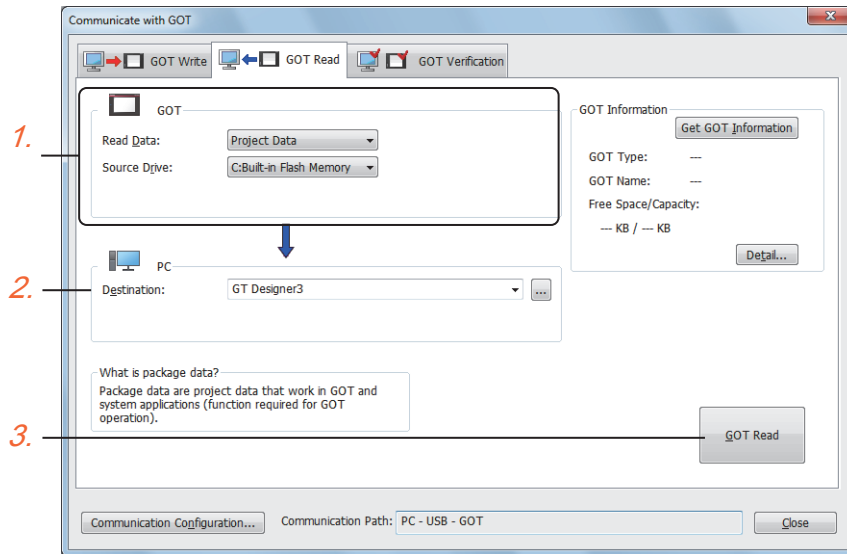


- Step 1.** Select [Package Data] for [Write Data].
The capacity of the transfer data is displayed in [Data Size]. Check that the destination drive has the sufficient available space.
- Step 2.** Select [Destination Drive].
- Step 3.** When the system application or the special data is required to be added to the package data or deleted, click the [Write Option] button and configure the setting in the [Write Option] dialog.
- Step 4.** Click the [GOT Write] button.
- Step 5.** The package data is written to the GOT.

1.2.2 Checking the project data and OS writing on GOT

Confirm if the package data is properly written onto the GOT by reading from GOT using GT Designer3.
For reading from the GOT, refer to the following manual.

⇒ GT Designer3 (GOT2000) Screen Design Manual



Step 1. Set [GOT Side] as follows.

- Select [Project Data] or [Package Data] for [Read Data].
- Select the drive where the project data or the package data is stored for [Source Drive].

Step 2. Set [PC Side].

Set the reading destination of the project for [Destination].

To read the project data to GT Designer3, select [GT Designer3].

(When [Read Data] is [Package Data], the project data cannot be read to GT Designer3.)

To read the project data as a file, click the [...] button to set the saving format and the saving destination of the file.

Step 3. Click the [GOT Read] button.

Step 4. The project is read.

Step 5. Confirm that the project data is written correctly onto the GOT.

1.3 Option Devices for the Respective Connection

The following shows the option devices to connect in the respective connection type.

For the specifications, usage and connecting procedure on option devices, refer to the respective device manual.

1.3.1 Communication module

Product name	Model	Specifications
Bus connection unit	GT15-QBUS	For QCPU (Q mode), motion controller CPU (Q series) Bus connection (1ch) unit standard model
	GT15-QBUS2	For QCPU (Q mode), motion controller CPU (Q series) Bus connection (2ch) unit standard model
	GT15-ABUS	For A/QnACPU, motion controller CPU (A series) Bus connection (1ch) unit standard model
	GT15-ABUS2	For A/QnACPU, motion controller CPU (A series) Bus connection (2ch) unit standard model
	GT15-75QBUSL	For QCPU (Q mode), motion controller CPU (Q series) Bus connection (1ch) unit slim model
	GT15-75QBUS2L	For QCPU (Q mode), motion controller CPU (Q series) Bus connection (2ch) unit slim model
	GT15-75ABUSL	For A/QnACPU, motion controller CPU (A series) Bus connection (1ch) unit slim model
	GT15-75ABUS2L	For A/QnACPU, motion controller CPU (A series) Bus connection (1ch) unit slim model
Serial communication unit	GT15-RS2-9P	RS-232 serial communication unit (D-sub 9-pin (male))
	GT15-RS4-9S	RS-422/485 serial communication unit (D-sub 9-pin (female))
	GT15-RS4-TE	RS-422/485 serial communication unit (terminal block)
MELSECNET/H communication unit	GT15-J71LP23-25	Optical loop unit
	GT15-J71BR13	Coaxial bus unit
MELSECNET/10 communication unit	GT15-J71LP23-25	Optical loop unit (MELSECNET/H communication unit used in the MNET/10 mode)
	GT15-J71BR13	Coaxial bus unit (MELSECNET/H communication unit used in the MNET/10 mode)
CC-Link IE Controller Network communication unit	GT15-J71GP23-SX	Optical loop unit
CC-Link IE Field Network communication unit	GT15-J71GF13-T2	CC-Link IE Field Network (1000BASE-T) unit
CC-Link communication unit	GT15-J61BT13	Intelligent device station unit CC-LINK Ver. 2 compatible
Ethernet communication unit	GT25-J71E71-100	Ethernet (100Base-TX) unit
Wireless LAN communication unit ^{*1}	GT25-WLAN	<ul style="list-style-type: none"> Used for the connection to the IEEE802.11b/g/n compliant, built-in antenna, access point (master unit)^{*2}, station (slave unit), personal computers, tablets, and smartphones. Compliance with Japan Radio Law^{*3}, FCC^{*4}, R&TTE^{*4}, SRRC^{*5}, KC^{*5}

^{*1} Data transfer in wireless LAN communication may not be as stable as that in cable communication.

A packet loss may occur depending on the surrounding environment and the installation location.

Be sure to perform a confirmation of operation before using this product.

^{*2} When a wireless LAN configuration of GT Designer3 the [Operation Mode] is set to [access point], the maximum connection number is a five (recommended).

^{*3} The product with hardware version A or later (manufactured in December 2013) complies with the regulation.

The product with hardware version A can be used only in Japan.

^{*4} The product with hardware version B or later (manufactured from October 2014) complies with the regulation.

The product with hardware version B or later can be used in Japan, the United States, the EU member states, Switzerland, Norway, Iceland, and Liechtenstein.

^{*5} The product with hardware version D or later (manufactured from May 2016) complies with the regulation.

The product with hardware version D or later can be used in Japan, the United States, the EU member states, Switzerland, Norway, Iceland, Liechtenstein, China (excluding Hong Kong, Macao, and Taiwan), and South Korea.

1.3.2 Option unit

Product name	Model	Specifications
Multimedia unit	GT27-MMR-Z	For video input signal (NTSC/PAL) 1 ch, playing movie
Video input unit	GT27-V4-Z	For video input signal (NTSC/PAL) 4 ch
RGB input unit	GT27-R2 GT27-R2-Z	For analog RGB input signal 2 ch
Video/RGB input unit	GT27-V4R1-Z	For video input signal (NTSC/PAL) 4 ch, for analog RGB mixed input signal 1 ch
RGB output unit	GT27-ROUT GT27-ROUT-Z	For analog RGB output signal 1 ch
Sound output unit	GT15-SOUT	For sound output
External I/O unit	GT15-DIOR	For the connection to external I/O device or operation panel (Negative Common Input/Source Type Output)
	GT15-DIO	For the connection to external I/O device or operation panel (Positive Common Input/Sink Type Output)

1.3.3 Conversion cables

Product name	Model	Specifications
RS-485 terminal block conversion modules	FA-LTBGT2R4CBL05	RS-422/485 (Connector) ↔ RS-485 (Terminal block) Supplied connection cable dedicated for the conversion unit
	FA-LTBGT2R4CBL10	
	FA-LTBGT2R4CBL20	

1.3.4 Serial Multi-Drop Connection Unit

Product name	Model	Specifications
Serial multi-drop connection unit	GT01-RS4-M	GOT multi-drop connection module ➡ Mitsubishi Products 18. GOT MULTI-DROP CONNECTION

1.3.5 Field Network Adapter Unit

Product name	Model	Specifications
Field network adapter unit	GT25-FNADP	<p>The field network adapter unit can be used with the following field networks by using the Anybus CompactCom M40 network communication module manufactured by HMS (hereinafter referred to as the communication module).</p> <p>Field networks: PROFIBUS DP-V1 DeviceNet</p> <p>How to incorporate the communication module to the field network adapter unit, and the details of the product name of the communication module, refer to the following manual.</p> <p>➡ GOT2000 Series Field Network Adapter Unit User's Manual</p>

1.3.6 Installing a unit on another unit (Checking the unit installation position)

This section describes the precautions for installing units on another unit.

For the installation method of each unit, refer to the User's Manual for the communication unit and option unit you are using.

For the method for installing a unit on another unit, refer to the following.

■ 1. When using a bus connection unit

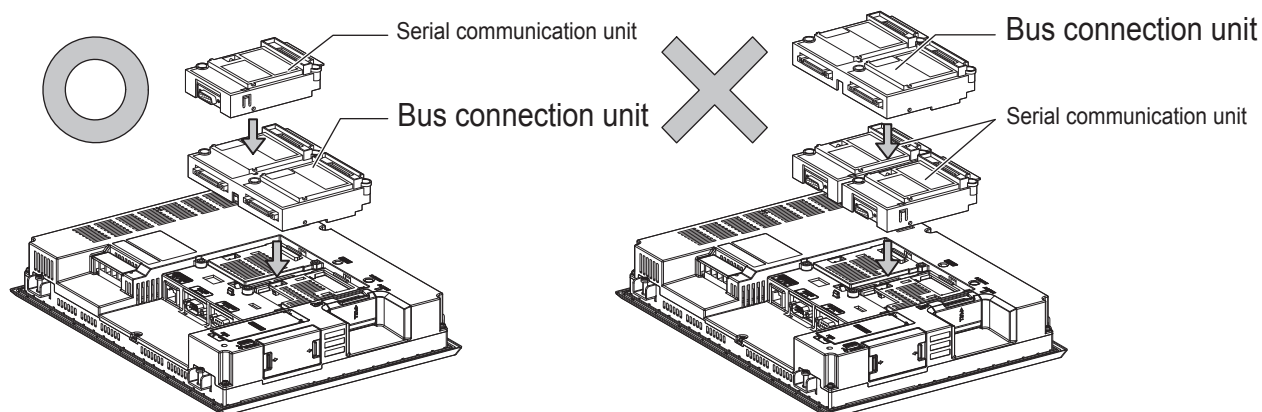
The installation position varies depending on the bus connection unit to be used.

(1) Wide bus units (GT15-75QBUS(2)L, GT15-75ABUS(2)L, GT15-QBUS2, GT15-ABUS2)

Install a bus connection unit in the 1st stage of the extension interface.

If a bus connection unit is installed in the 2nd stage or above, the unit cannot be used.

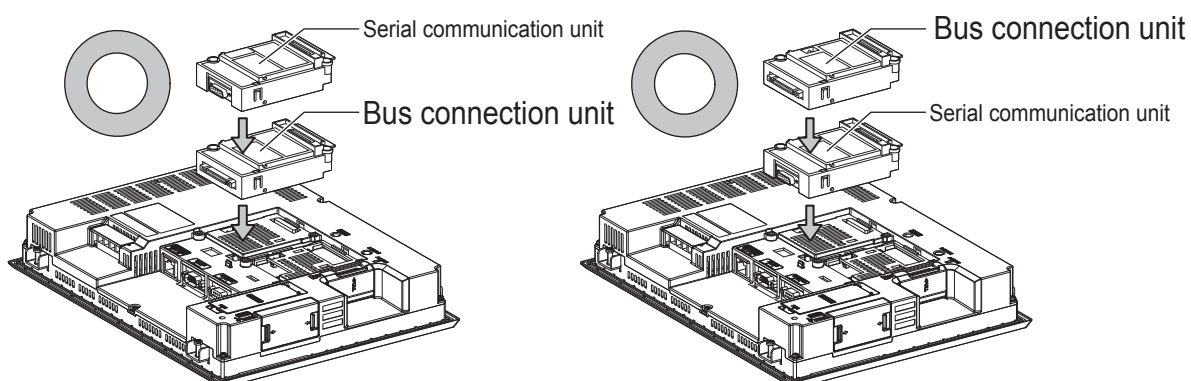
Example: Installing a bus connection unit and serial communication units



(2) Standard size bus connection unit (GT15-QBUS and GT15-ABUS)

A bus connection unit can be installed in any position (1st to 3rd stage) of the extension interface.

Example: Installing a bus connection unit and serial communication units

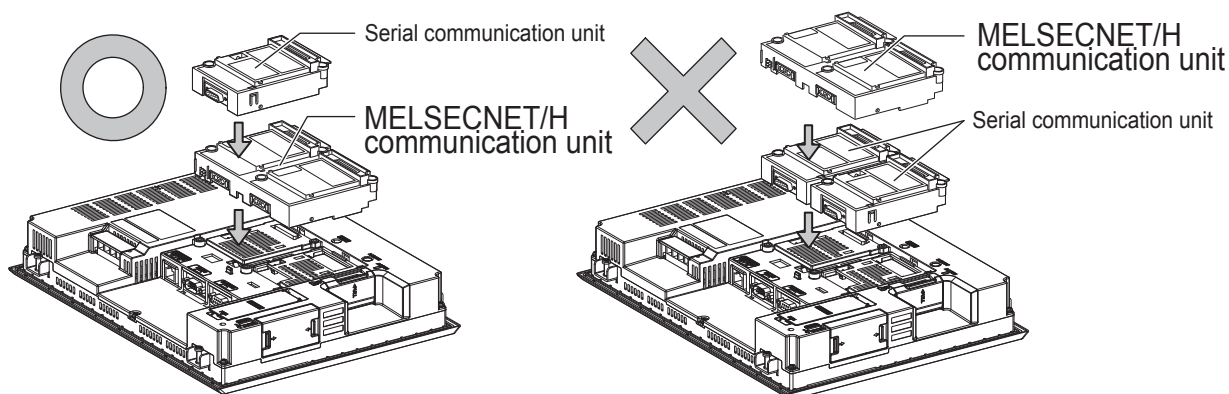


■2. When using a MELSECNET/H communication unit, CC-Link IE Controller Network communication unit, or CC-Link communication unit (GT15-J61BT13)

Install a MELSECNET/H communication unit, CC-Link IE Controller Network communication unit, or CC-Link communication unit in the 1st stage of an extension interface.

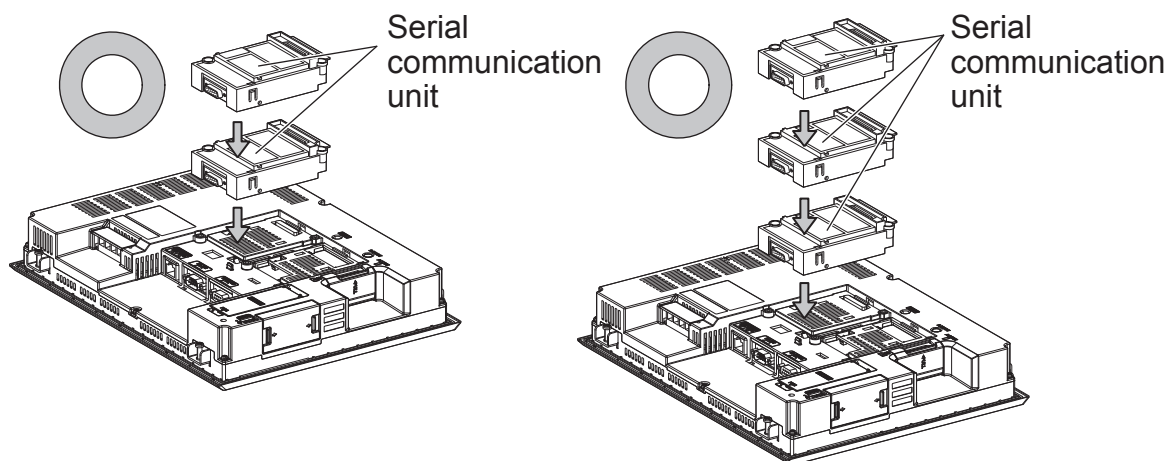
If a bus connection unit is installed in the 2nd stage or above, the unit cannot be used.

Example: When installing a MELSECNET/H communication unit and a serial communication unit



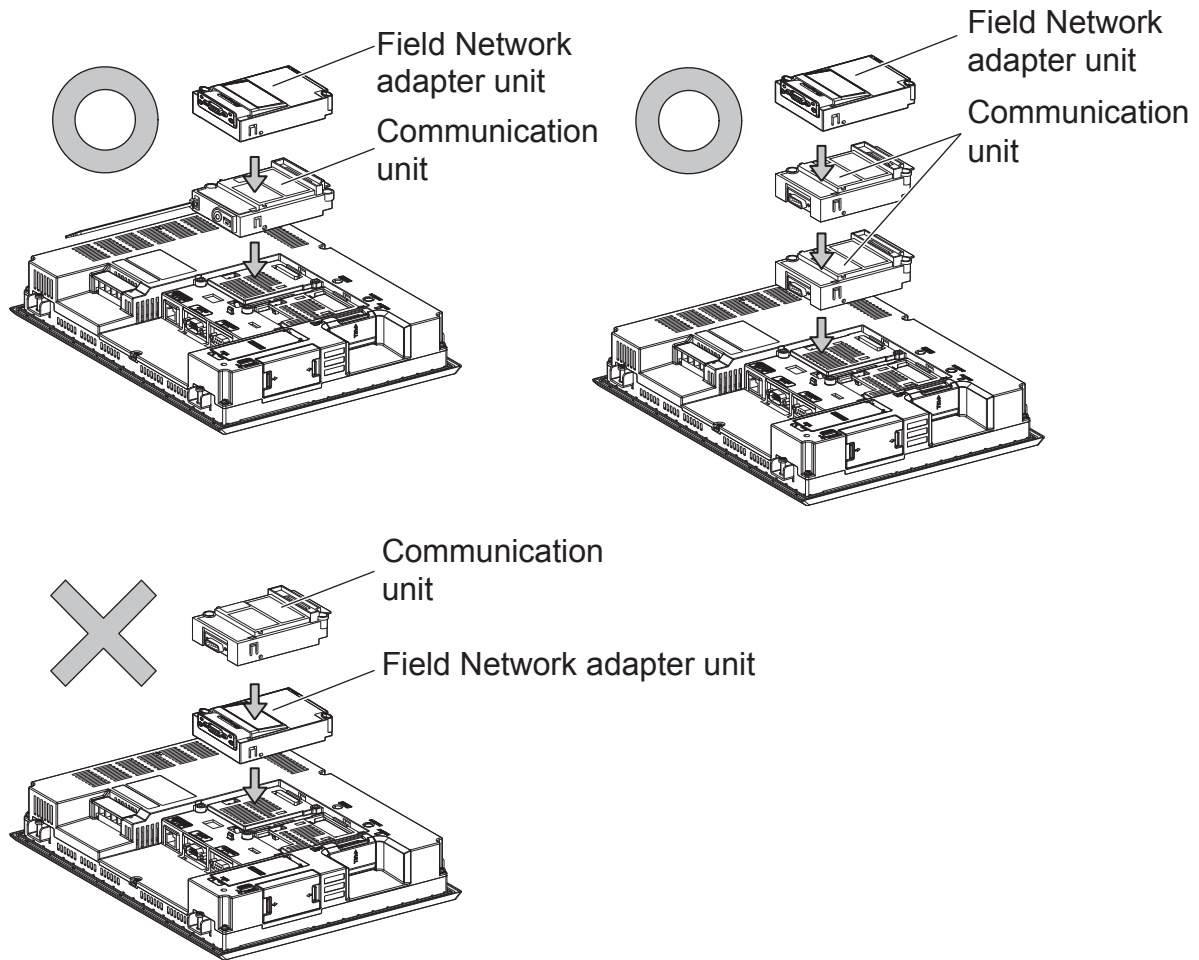
■3. When using a serial communication unit

A serial communication unit can be installed in any position (1st to 3rd stage) of the extension interface.



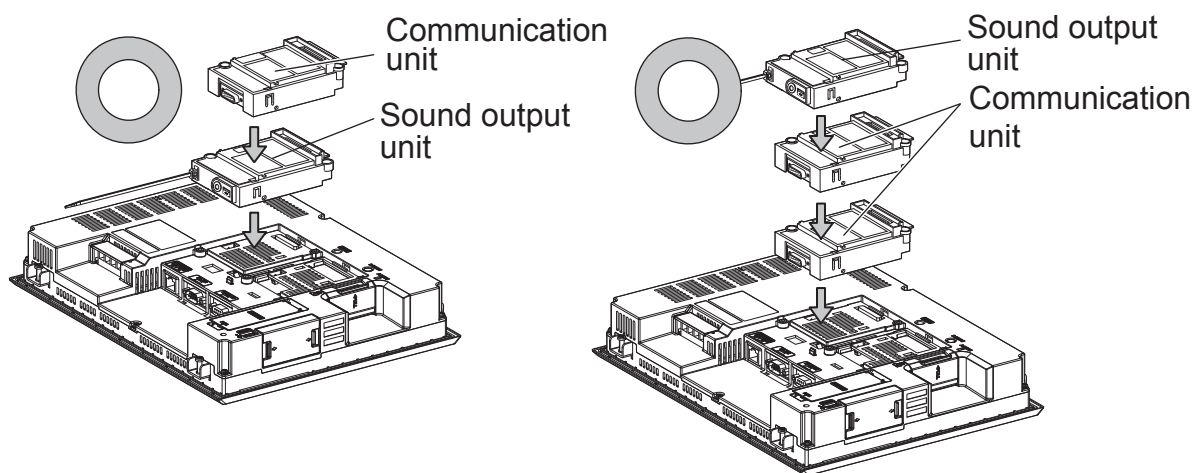
■4. When using a field network adapter unit

A field network adapter unit can be installed in any position (1st to 3rd stage) of the extension interface. However, at the top of the field network adapter unit, you will not be able to mount the each communication unit. Example: Installing a field network adapter unit



■5. When using the sound output unit or external I/O unit

The sound output unit or external I/O unit can be installed in any position (1st to 3rd stage) of the extension interface. Example: When installing a sound output unit



■ 6. When using the video input unit, RGB input unit, video/RGB input unit, RGB output unit, or multimedia unit

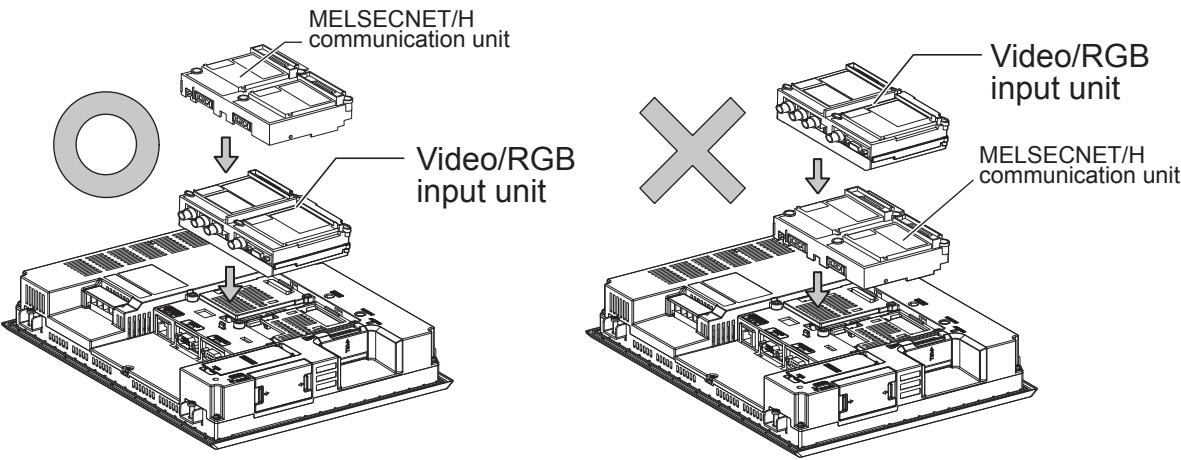
Only either one of the video input unit, RGB input unit, video/RGB input unit, RGB output unit, or multimedia unit can be installed to the GOT.

Install the video input unit, RGB input unit, video/RGB input unit, RGB output unit, or multimedia unit at the 1st stage of the extension interface. These communication units cannot be used if installed in the 2nd or higher stage.

When any of these units is used, the communication units indicated below must be installed in the 2nd stage of the extension interface.

Communication unit	Model
Bus connection unit	GT15-QBUS2, GT15-ABUS2
MELSECNET/H communication unit	GT15-J71LP23-25, GT15-J71BR13
CC-Link IE Controller Network connection	GT15-J71GP23-SX
CC-Link communication unit	GT15-J61BT13

Example: When installing a video input unit and a MELSECNET/H communication unit



1.4 Connection Cables for the Respective Connection

To connect the GOT to a device in the respective connection type, connection cables between the GOT and a device are necessary.

For cables needed for each connection, refer to each chapter for connection.

1.4.1 GOT connector specifications

The following shows the connector specifications on the GOT side.

Refer to the following table when preparing connection cables by the user.

■ 1. RS-232 interface

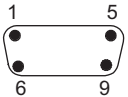
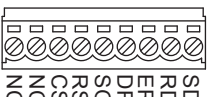
Use the following as the RS-232 interface and the RS-232 communication unit connector on the GOT. For the GOT side of the connection cable, use a connector and connector cover applicable to the GOT connector.

(1) Connector specifications

GOT	Hardware Version	Connector type	Connector model	Manufacturer
GT27 GT25 GT23 GT2105-QTBDS GT2105-QMBDS	-	9-pin D-sub (male) inch screw fixed type	17LE-23090-27(D4C□)	DDK Ltd.
GT15-RS2-9P	-	9-pin D-sub (male) inch screw fixed type	17LE-23090-27(D3CC)	DDK Ltd.
GT01-RS4-M	-			
GT2104-RTBD GT2104-PMBDS2 GT2103-PMBDS2	-	9-pin terminal block*1	MC1.5/9-G-3.5BK	PHOENIX CONTACT Inc

*1 The terminal block (MC1.5/9-ST-3.5 or corresponding product) of the cable side is packed together with the GT2104-RTBD, GT2103-PMBDS2.

(2) Connector pin arrangement

GT27, GT25, GT23, GT15-RS2-9P, GT01-RS4-M	GT2104-RTBD, GT2103-PMBDS2
<p>GOT main part connector see from the front</p>  <p>9-pin D-sub (male)</p>	<p>See from the back of a GOT main part</p>  <p>9-pin terminal block</p>

■ 2. RS-422/485 interface

Use the following as the RS-422/485 interface and the RS-422/485 communication unit connector on the GOT.
For the GOT side of the connection cable, use a connector and connector cover applicable to the GOT connector.

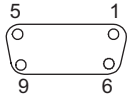
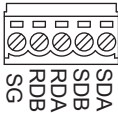
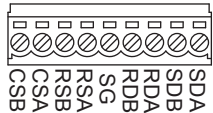
(1) Connector model

GOT	Connector type	Connector model	Manufacturer
GT27 GT25 GT23 GT2105-QTBDS GT2105-QMBDS	9-pin D-Sub (female) M2.6 millimeter screw fixed type	17LE-13090-27(D2AC)	DDK Ltd.
GT2104-PMBD GT2103-PMBD	5-pin terminal block ^{*1}	MC1.5/5-G-3.5BK	PHOENIX CONTACT Inc
GT2104-RTBD GT2104-PMBDS GT2104-PMBLS GT2103-PMBDS GT2103-PMBLS	9-pin terminal block ^{*2}	MC1.5/9-G-3.5BK	PHOENIX CONTACT Inc
GT15-RS4-9S GT01-RS4-M	9-pin D-Sub (female) M2.6 millimeter screw fixed type	17LE-13090-27(D3AC)	DDK Ltd.
GT15-RS4-TE	-	-	SL-SMT3.5/10/90F BOX

*1 The terminal block (MC1.5/5-ST-3.5 or corresponding product) of the cable side is packed together with the GT2103-PMBD.

*2 The terminal block (MC1.5/9-ST-3.5 or corresponding product) of the cable side is packed together with the GT2104-RTBD, GT2103-PMBDS, GT2103-PMBLS.

(2) Connector pin arrangement

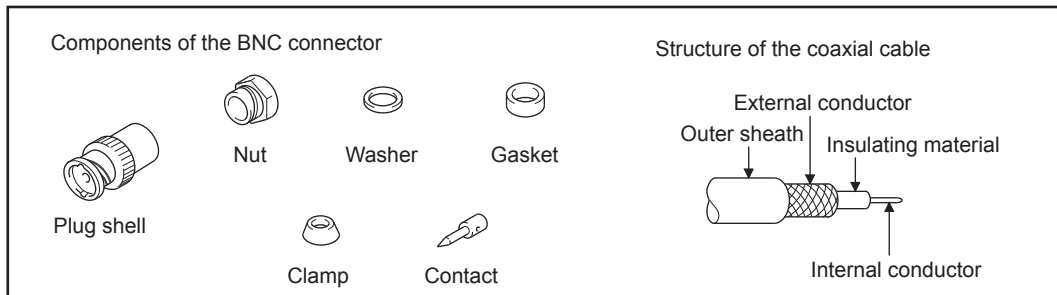
GT27, GT25, GT23, GT2105-QTBDS, GT2105-QMBDS, GT01-RS4-M	GT2104-PMBD, GT2103-PMBD	GT2104-RTBD GT2104-PMBDS GT2104-PMBLS GT2103-PMBDS GT2103-PMBLS
<p>GOT main part connector see from the front</p>  <p>9-pin D-sub (female)</p>	<p>See from the back of a GOT main part</p>  <p>5-pin terminal block</p>	<p>See from the back of a GOT main part</p>  <p>9-pin terminal block</p>

1.4.2 Coaxial cable connector connection method

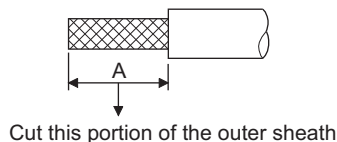
The following describes the method for connecting the BNC connector (connector plug for coaxial cable) and the cable.

CAUTION

- Solder the coaxial cable connectors properly.
Insufficient soldering may result in malfunctions.

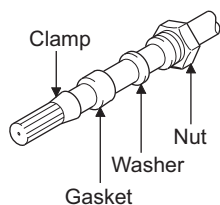


Step 1. Remove the external sheath of the coaxial cable with dimensions as shown below.

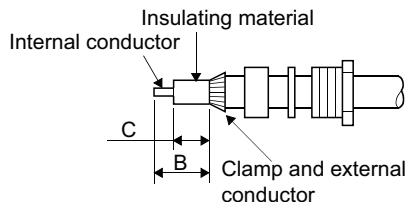


Cable in use	A
3C-2V	15 mm
5C-2V, 5C-2V-CCY	10 mm

Step 2. Pass the nut, washer, gasket, and clamp through the coaxial cable as shown on the left and loosen the external conductor.

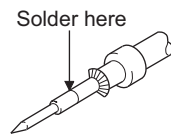


Step 3. Cut the external conductor, insulating material, and internal conductor with the dimensions as shown below. Note that the external conductor should be cut to the same dimension as the tapered section of the clamp and smoothed down to the clamp.

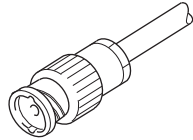


Cable in use	B	C
3C-2V	6 mm	3 mm
5C-2V, 5C-2V-CCY	7 mm	5 mm

Step 4. Solder the contact to the internal conductor.



Step 5. **4.** Insert the connector assembly shown in ### into the plug shell and screw the nut into the plug shell.



Precautions for soldering

Note the following precautions when soldering the internal conductor and contact.

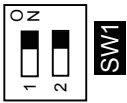
- Make sure that the solder does not bead up at the soldered section.
- Make sure there are no gaps between the connector and cable insulator or they do not cut into each other.
- Perform soldering quickly so the insulation material does not become deformed.

1.4.3 Terminating resistors of GOT

The following shows the terminating resistor specifications on the GOT side.
When setting the terminating resistor in each connection type, refer to the following.

■ 1. RS-422/485 communication unit

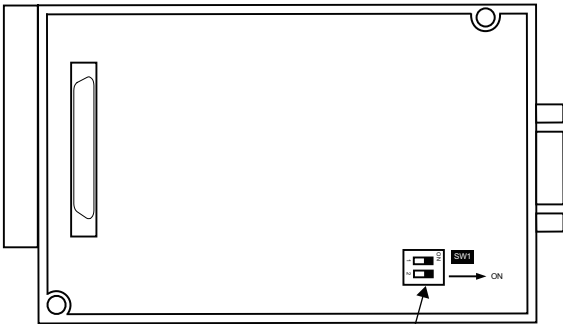
Set the terminating resistor using the terminating resistor setting switch.



Terminating resistor*1	Switch No.	
	1	2
100 OHM	ON	ON
Disable	OFF	OFF

*1 The default setting is "Disable".

- For RS422/485 communication unit



Terminating resistor setting switch

Rear view of RS-422/485 communication unit.

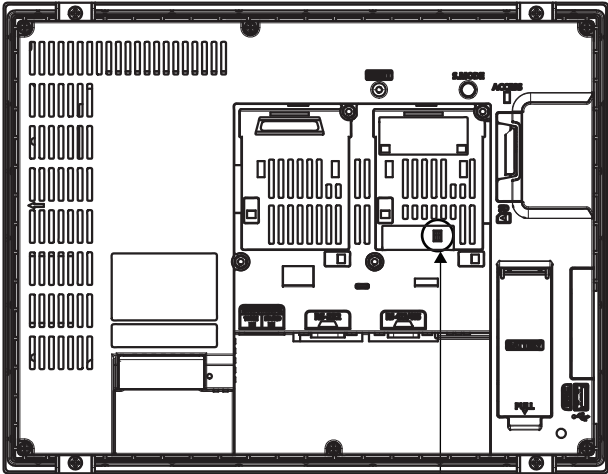
■ 2. GT27

Set the terminating resistor using the terminating resistor setting switch.



Terminating resistor*1	Switch No.	
	1	2
100 OHM	ON	ON
Disable	OFF	OFF

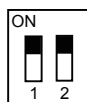
- *1 The default setting is "Disable".
- For GT2710-V



Terminating resistor setting switch
(inside the cover)

■3. GT25

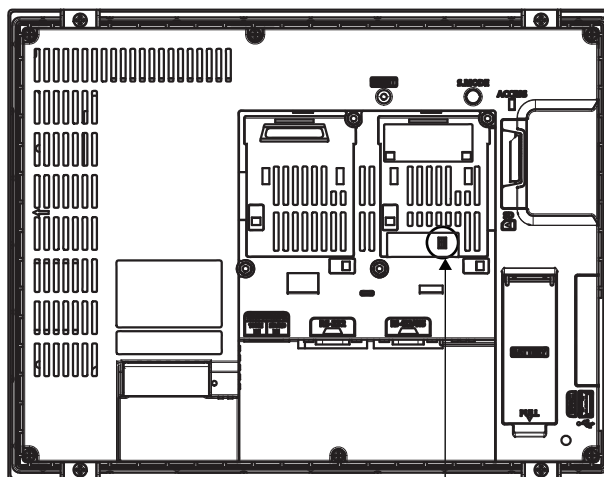
Set the terminating resistor using the terminating resistor setting switch.



Terminating resistor ^{*1}	Switch No.	
	1	2
100 OHM	ON	ON
Disable	OFF	OFF

^{*1} The default setting is "Disable".

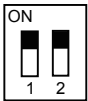
- For GT2510-V



Terminating resistor setting switch
(inside the cover)

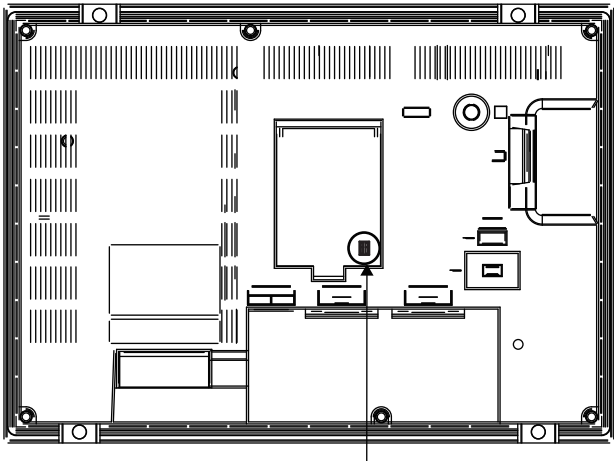
■ 4. GT23

Set the terminating resistor using the terminating resistor setting switch.



Terminating resistor*1	Switch No.	
	1	2
100 OHM	ON	ON
Disable	OFF	OFF

- *1 The default setting is "Disable".
- For GT2310-V

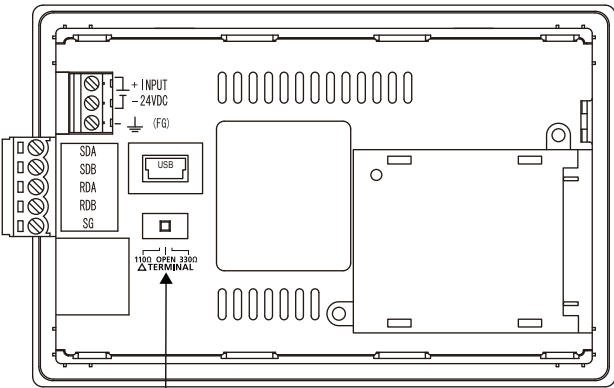


Terminating resistor setting switch
(inside the cover)

■ 5. GT21

Set the terminating resistor using the terminating resistor setting switch.

- For GT2103-PMBD



Terminating resistor selector switch

1.5 Verifying GOT Recognizes Connected Equipment

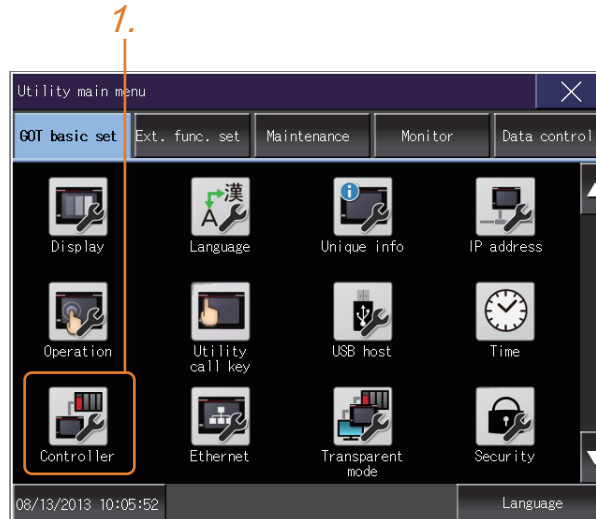
Verify the GOT recognizes controllers on [Communication Settings] of the Utility.

- Channel number of communication interface, communication drivers allocation status
- Communication unit installation status

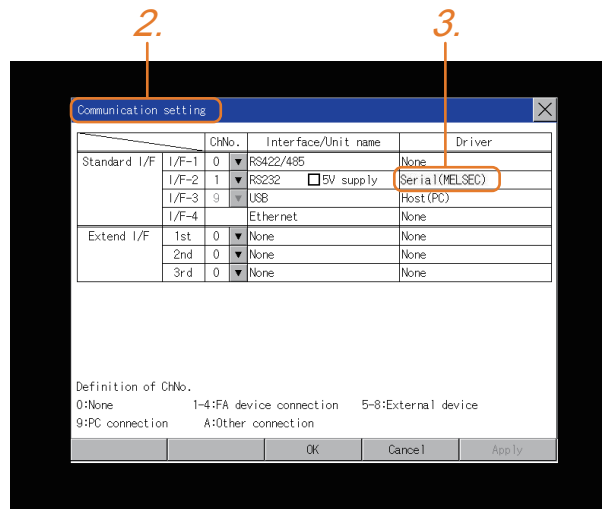
For details on the Utility, refer to the following manual.

➡ GOT2000 Series User's Manual (Utility)

Step 1. After powering up the GOT, touch [GOT basic set] → [Controller] from the Utility.



Step 2. The [Communication Settings] appears.



Step 3. Verify that the communication driver name to be used is displayed in the communication interface box to be used.

Step 4. When the communication driver name is not displayed normally, carry out the following procedure again.

➡ 1.1 Setting the Communication Interface

1.6 Checking for Normal Monitoring

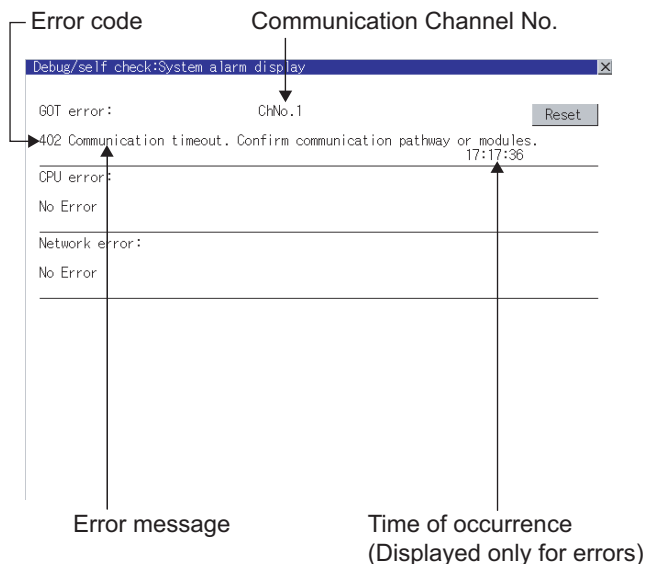
1.6.1 Check on the GOT

■ 1. Check for errors occurring on the GOT

Presetting the system alarm to project data allows you to identify errors occurred on the GOT, PLC CPU, servo amplifier and communications.

For details on the operation method of the GOT Utility screen, refer to the following manual.

➡ GOT2000 Series User's Manual (Utility)



POINT

Alarm popup display

With the alarm popup display function, alarms are displayed as a popup display regardless of whether an alarm display object is placed on the screen or not (regardless of the display screen). Since comments can be flown from right to left, even a long comment can be displayed all.

For details of the alarm popup display, refer to the following manual.

➡ GT Designer3 (GOT2000) Screen Design Manual

■2. Perform an I/O check

Whether the PLC can communicate with the GOT or not can be checked by the I/O check function. If this check ends successfully, it means correct communication interface settings and proper cable connection. Display the I/O check screen by Main Menu.

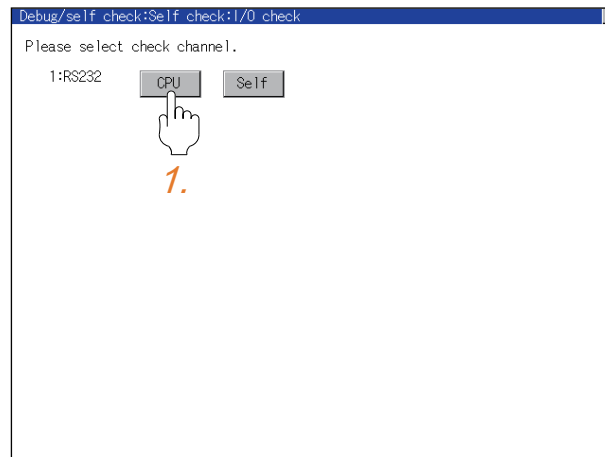
- Display the I/O check screen by [Main menu] → [Self check] → [I/O check].

For details on the I/O check, refer to the following manual:

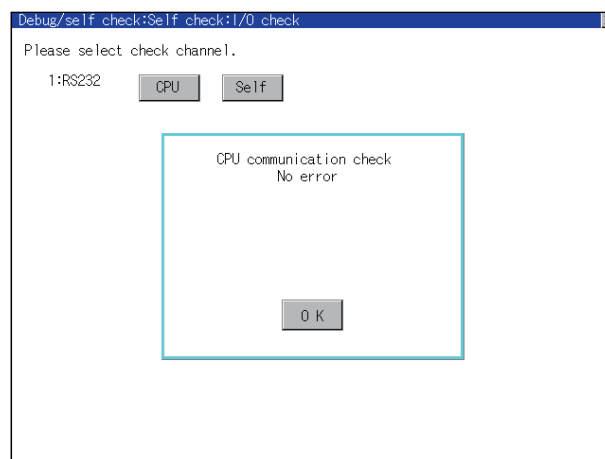
⇒ GOT2000 Series User's Manual (Utility)

Step 1. Touch [CPU] on the I/O check screen.

Touching [CPU] executes the communication check with the connected PLC.



Step 2. When the communication screen ends successfully, the screen on the left is displayed.

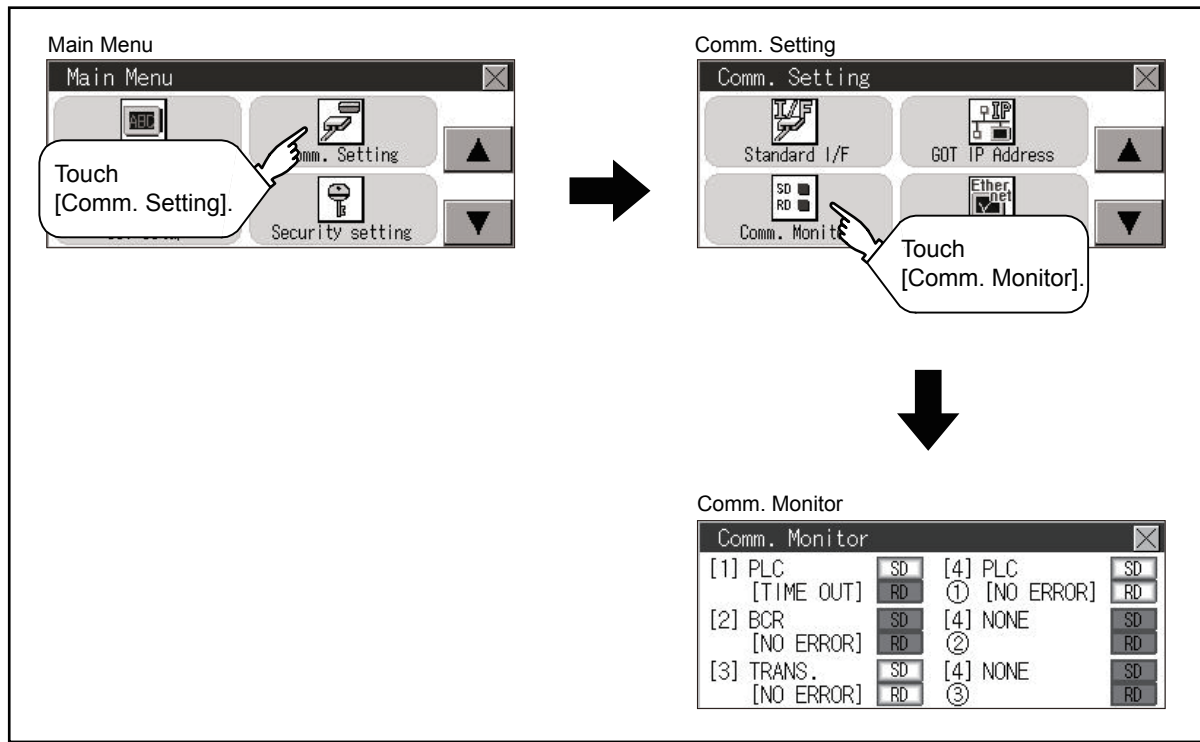


3. Communication monitoring function

The communication monitoring is a function that checks whether the PLC can communicate with the GOT.
If this check ends successfully, it means correct communication interface settings and proper cable connection.
Display the communication monitoring function screen by [Main Menu] → [Comm. Setting] → [Comm. Monitor].
For details on the communication monitoring function, refer to the following manual:

➡ GOT2000 Series User's Manual (Utility)

(Operation of communication monitoring function screen)



1.6.2 Confirming the communication state on the GOT side (For Ethernet connection)

■ 1. Confirming the communication state on Windows®, GT Designer3

(1) When using the Command Prompt of Windows®

Execute a Ping command at the Command Prompt of Windows®.

(a) When normal communication

C:\>Ping 192.168.3.18

Reply from 192.168.3.18: bytes=32 time<1ms TTL=64

(b) When abnormal communication

C:\>Ping 192.168.3.18

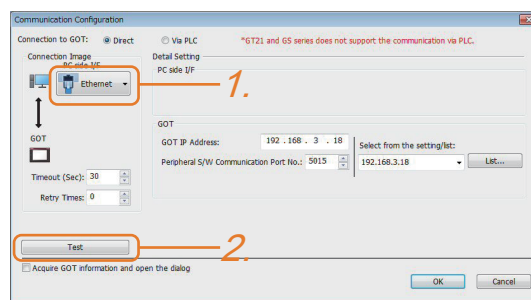
Request timed out.

(2) When using the [Connection Test] of GT Designer3

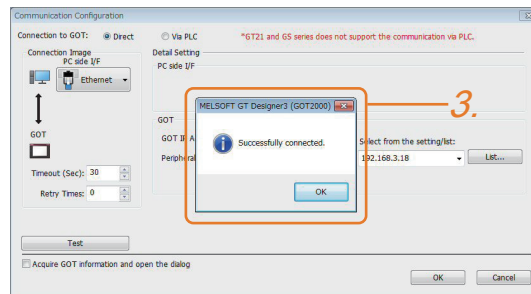
Select [Communication] → [Communication settings] from the menu to display [TEST].

Step 1. Set the [PC side I/F] to the [Ethernet].

Step 2. Specify the [GOT IP Address] of the [Communication Configuration] and click the [Test] button.



Step 3. Check if GT Designer3 has been connected to the GOT.



(3) When abnormal communication

At abnormal communication, check the followings and execute the Ping command or [Connection Test] again.

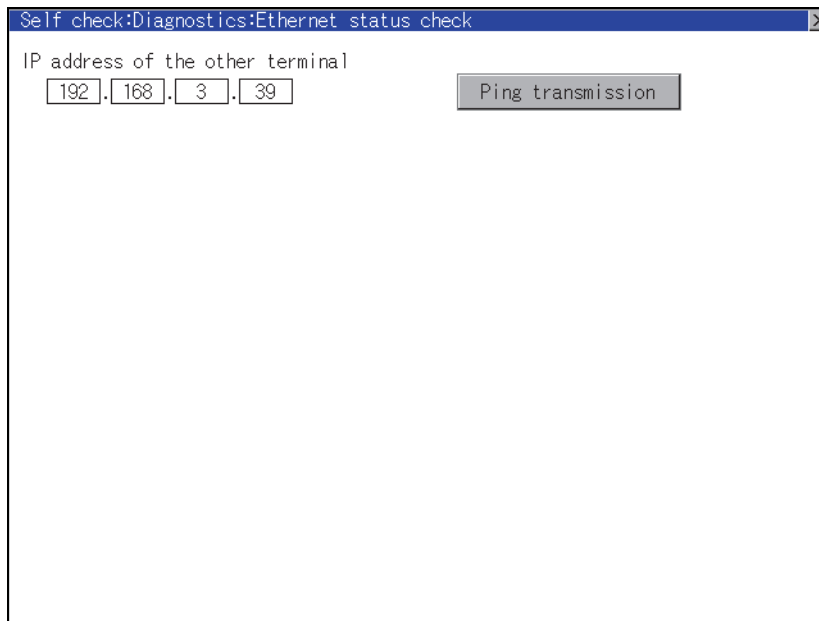
- Mounting condition of Ethernet communication unit
- Cable connecting condition
- Confirmation of [Communication Settings]
- IP address of GOT specified by Ping command

■2. Confirming the communication state on the GOT

[PING Test] can be confirmed by the Utility screen of the GOT.

For details on the operation method of the GOT Utility screen, refer to the following manual.

➡ GOT2000 Series User's Manual (Utility)



1.6.3 Confirming the communication state to each station (Station monitoring function)

The station monitoring function detects the faults (communication timeout) of the stations monitored by the GOT. When detecting the abnormal state, it allocates the data for the faulty station to the GOT special register (GS).

■ 1. No. of faulty stations

(1) Ethernet connection (Except for Ethernet multiple connection)

Total No. of the faulty CPU is stored.

Device	b15 to b8	b7 to b0
GS230	(00H fixed)	No. of faulty stations

(2) Ethernet multiple connection

Total No. of the faulty connected equipment is stored.

Channel	Device	b15 to b8	b7 to b0
Ch1	GS280	(00H fixed)	No. of faulty stations
Ch2	GS300	(00H fixed)	No. of faulty stations
Ch3	GS320	(00H fixed)	No. of faulty stations
Ch4	GS340	(00H fixed)	No. of faulty stations

POINT

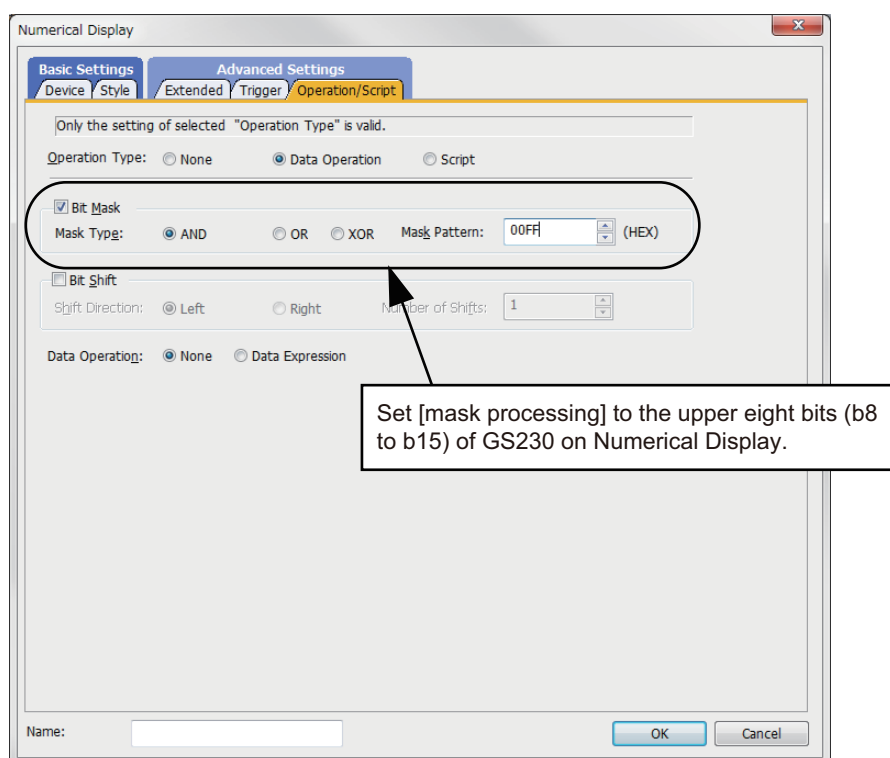
When monitoring GS230 on Numerical Display

When monitoring GS230 on Numerical Display, check [mask processing] with data operation tab as the following.

For the data operation, refer to the following manual.

➡ GT Designer3 (GOT2000) Screen Design Manual

- Numerical Display (Data Operation tab)



2. Faulty station information

The bit corresponding to the faulty station is set. (0: Normal, 1: Abnormal)

The bit is reset after the fault is recovered.

(1) Ethernet connection (Except for Ethernet multiple connection)

GS231 bit 0 . . .

GS231 bit 1 . . .

GS231 bit 2 . . .

GS231 bit 3 . . .

	Host	Net No.	Station	Unit Type	IP Address	Port No.	Communication
1	*	1	2	QJ71E71/LJ71E71	192.168.3.39	5001	UDP
2		1	3	QJ71E71/LJ71E71	192.168.3.40	5001	UDP
3		1	4	AJ71QE71	192.168.3.41	5001	UDP
4		1	5	AJ71E71	192.168.3.42	5006	UDP

Device	Ethernet setting No.															
	b15	b14	b13	b12	b11	b10	b9	b8	b7	b6	b5	b4	b3	b2	b1	b0
GS231	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
GS232	32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17
GS233	48	47	46	45	44	43	42	41	40	39	38	37	36	35	34	33
GS234	64	63	62	61	60	59	58	57	56	55	54	53	52	51	50	49
GS235	80	79	78	77	76	75	74	73	72	71	70	69	68	67	66	65
GS236	96	95	94	93	92	91	90	89	88	87	86	85	84	83	82	81
GS237	112	111	110	109	108	107	106	105	104	103	102	101	100	99	98	97
GS238	128	127	126	125	124	123	122	121	120	119	118	117	116	115	114	113

(2) Ethernet connection, CC-Link IE Controller Network connection, CC-Link IE Field Network connection, Temperature controller connection, Inverter connection, Servo amplifier connection.

The station number to which each device corresponds changes according to the connection/non connection with Ethernet.

With Ethernet connection: 1 to 128

With other than Ethernet connection: 0 to 127

Example) With Ethernet connection, when PC No. 100 CPU connecting to Ch3 is faulty, GS327.b3 is set.

- With Ethernet connection: 1 to 128

Device				Station number															
Ch1	Ch2	Ch3	Ch4	b15	b14	b13	b12	b11	b10	b9	b8	b7	b6	b5	b4	b3	b2	b1	b0
GS281	GS301	GS321	GS341	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
GS282	GS302	GS322	GS342	32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17
GS283	GS303	GS323	GS343	48	47	46	45	44	43	42	41	40	39	38	37	36	35	34	33
GS284	GS304	GS324	GS344	64	63	62	61	60	59	58	57	56	55	54	53	52	51	50	49
GS285	GS305	GS325	GS345	80	79	78	77	76	75	74	73	72	71	70	69	68	67	66	65
GS286	GS306	GS326	GS346	96	95	94	93	92	91	90	89	88	87	86	85	84	83	82	81
GS287	GS307	GS327	GS347	112	111	110	109	108	107	106	105	104	103	102	101	100	99	98	97
GS288	GS308	GS328	GS348	128	127	126	125	124	123	122	121	120	119	118	117	116	115	114	113

- With other than Ethernet connection: 0 to 127

Device				Station number															
Ch1	Ch2	Ch3	Ch4	b15	b14	b13	b12	b11	b10	b9	b8	b7	b6	b5	b4	b3	b2	b1	b0
GS281	GS301	GS321	GS341	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0 ^{*1}
GS282	GS302	GS322	GS342	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
GS283	GS303	GS323	GS343	47	46	45	44	43	42	41	40	39	38	37	36	35	34	33	32
GS284	GS304	GS324	GS344	63	62	61	60	59	58	57	56	55	54	53	52	51	50	49	48
GS285	GS305	GS325	GS345	79	78	77	76	75	74	73	72	71	70	69	68	67	66	65	64
GS286	GS306	GS326	GS346	95	94	93	92	91	90	89	88	87	86	85	84	83	82	81	80
GS287	GS307	GS327	GS347	111	110	109	108	107	106	105	104	103	102	101	100	99	98	97	96
GS288	GS308	GS328	GS348	127 *1*2	126 *1*2	125 *1*2	124 *1*2	123 *1*2	122 *1*2	121 *1*2	120	119	118	117	116	115	114	113	112

*1 When CC-Link IE controller network connection is not used.

*2 When CC-Link IE field network connection is not used.

For details on the GS Device, refer to the following help.

➡ GT Designer3 (GOT2000) Screen Design Manual

■ 3. Network No., station No. notification

The network No. and station No. of the GOT in Ethernet connection are stored at GOT startup.

If connected by other than Ethernet, 0 is stored.

Device				Description
CH1	CH2	CH3	CH4	
GS376	GS378	GS380	GS382	Network No. (1 to 239)
GS377	GS379	GS381	GS383	Station No. (1 to 64)

CONNECTIONS TO NON-MITSUBISHI PRODUCTS

2.	CONNECTION TO IAI ROBOT CONTROLLER	2 - 1
3.	CONNECTION TO AZBIL (former YAMATAKE) CONTROL EQUIPMENT	3 - 1
4.	CONNECTION TO OMRON PLC	4 - 1
5.	CONNECTION TO OMRON TEMPERATURE CONTROLLER	5 - 1
6.	CONNECTION TO KEYENCE PLC.	6 - 1
7.	CONNECTION TO KOYO EI PLC	7 - 1
8.	CONNECTION TO JTEKT PLC	8 - 1
9.	CONNECTION TO SHARP PLC	9 - 1
10.	CONNECTION TO SHINKO TECHNOS INDICATING CONTROLLER.	10 - 1
11.	CONNECTION TO CHINO CONTROLLER.	11 - 1
12.	CONNECTION TO TOSHIBA PLC	12 - 1
13.	CONNECTION TO TOSHIBA MACHINE PLC.	13 - 1
14.	CONNECTION TO PANASONIC SERVO AMPLIFIER	14 - 1
15.	CONNECTION TO PANASONIC INDUSTRIAL DEVICES SUNX PLC	15 - 1

2. CONNECTION TO IAI ROBOT CONTROLLER

2.1	Connectable Model List	2 - 2
2.2	System Configuration	2 - 3
2.3	Connection Diagram.	2 - 17
2.4	GOT Side Settings	2 - 26
2.5	Robot Controller Side Setting	2 - 28
2.6	Device Range that Can Be Set.	2 - 33
2.7	Precautions	2 - 49

2. CONNECTION TO IAI ROBOT CONTROLLER

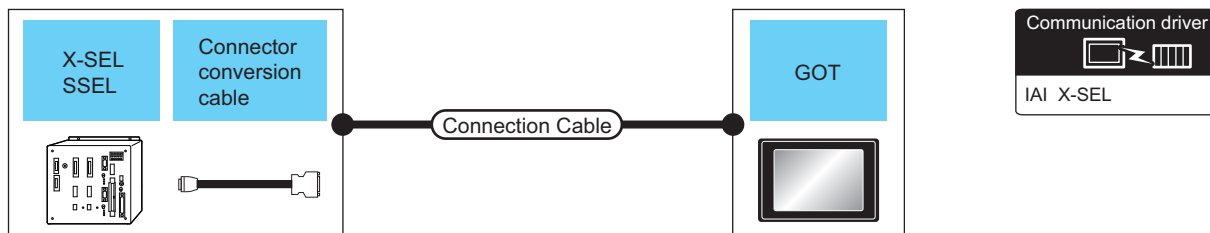
2.1 Connectable Model List

The following table shows the connectable models.







Series	Model name	Clock	Communication Type	Connectable GOT	Refer to
X-SEL	XSEL-J	×	RS-232	<div>GT 27</div> <div>GT 25</div> <div>GT 23</div> <div>GT 21</div> <div>GS</div>	➡ 2.2.1
	XSEL-K				
	XSEL-KE				
	XSEL-KT				
	XSEL-KET				
	XSEL-P				
	XSEL-Q				
	XSEL-JX				
	XSEL-KX				
	XSEL-KTX				
	XSEL-PX				
	XSEL-QX				
SSEL	SSEL				
ASEL	ASEL				
PSEL	PSEL				
PCON	PCON-C	×	RS-232 RS-422	<div>GT 27</div> <div>GT 25</div> <div>GT 23</div> <div>GT 21</div> <div>GS</div>	➡ 2.2.2
	PCON-CG				
	PCON-CF				
	PCON-CY				
	PCON-SE				
	PCON-PL				
	PCON-PO				
	PCON-CA				
	PCON-CFA				
ACON	ACON-C	×	RS-232 RS-422	<div>GT 27</div> <div>GT 25</div> <div>GT 23</div> <div>GT 21</div> <div>GS</div>	➡ 2.2.2
	ACON-CG				
	ACON-CY				
	ACON-SE				
	ACON-PL				
	ACON-PO				
SCON	SCON-C				
	SCON-CA				
ERC2	ERC2				

2.2 System Configuration

2.2.1 System Configuration for connecting to X-SEL, SSEL, ASEL, PSEL



PLC			Connection cable	Max. distance	GOT		Number of connectable equipment
Model name	RS-232C adapter	Communication Type	Cable model Connection diagram number		Option device	Model	
X-SEL (Teaching connector)	-	RS-232	CB-ST-E1MW050 ^{*1} or RS-232 connection diagram 1)	10m	- (Built into GOT)		1 GOT for 1 Controller
					GT15-RS2-9P		
					GT10-C02H- 6PT9P ^{*2}		
			CB-ST-E1MW050 ^{*1} + RS-232 connection diagram 4) or RS-232 connection diagram 5)	10m	- (Built into GOT)		
X-SEL (General RS232C port connector)	-	RS-232	RS-232 connection diagram 2)	10m	- (Built into GOT)		
					GT15-RS2-9P		
					GT10-C02H- 6PT9P ^{*2}		
			RS-232 connection diagram 6)	10m	- (Built into GOT)		

PLC			Connection cable	Max. distance	GOT		Number of connectable equipment
Model name	RS-232C adapter	Communication Type	Cable model Connection diagram number		Option device	Model	
SSEL ASEL PSEL	CB-SEL-SJ002*1	RS-232	CB-ST-E1MW050*1	10m	- (Built into GOT)		1 GOT for 1 Controller
					GT15-RS2-9P		
					GT10-C02H-6PT9P*2		
			CB-ST-E1MW050*1 +  RS-232 connection diagram 4) or  RS-232 connection diagram 5)	10m	- (Built into GOT)		

*1 Product manufactured by IAI Corporation. For details of the product, contact IAI Corporation.

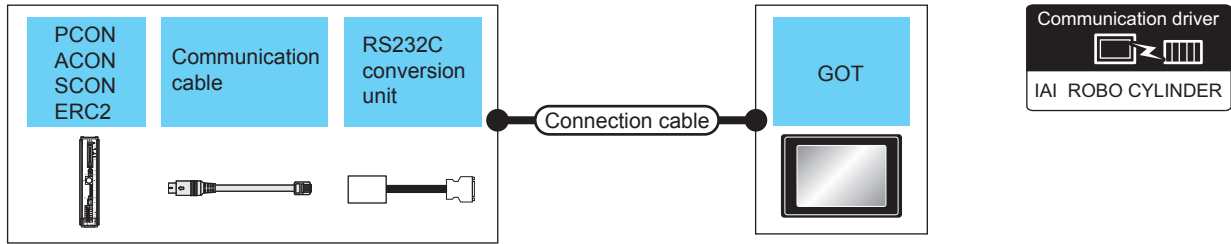
*2 When a GT10-C02H-6PT9P unit of the sub version A or B is used, do not ground the case of the D-sub (9-pin) connector.

2.2.2 System Configuration for connecting to PCON, ACON, SCON, ERC2

1. When connecting to one controller

(1) When using the RS-232 connection

(a) PCON, ACON, SCON, ERC2 (SIO specifications), ERC2 (NP/PN specifications)



Controller				Connection cable		GOT		Number of connectable equipment
Model name	Communication cable	RS232C conversion unit	Communication Type	Connection diagram number	Max. distance	Option device	Model	
PCON ACON SCON ERC2 (NP/PN specifications)*3	CB-RCA-SIO050*1 (5m)	RCB-CV-MW*1 (0.3m)	RS-232	-	-	(Built into GOT)	<div>GT 27</div> <div>GT 23</div> <div>GS 25</div>	1 GOT for 1 Controller
						GT15-RS2-9P	<div>GT 27</div> <div>GT 25</div>	
						GT10-C02H-6PT9P*4	<div>GT 03P 21</div> <div>GT 03P 21</div>	
				User RS-232 connection diagram 7)	10m	(Built into GOT)	<div>GT 04R 21</div> <div>GT 03P 21</div>	
ERC2 (SIO specifications)*2	CB-ERC2-SIO020*1 + CB-ERC2-PWBIO □□□ *1 or CB-ERC2-PWBIO □□□ -RB *1	RCB-CV-MW*1 (0.3m)	RS-232	-	-	(Built into GOT)	<div>GT 27</div> <div>GT 23</div> <div>GS 25</div>	1 GOT for 1 Controller
						GT15-RS2-9P	<div>GT 27</div> <div>GT 25</div>	
						GT10-C02H-6PT9P*4	<div>GT 03P 21</div> <div>GT 03P 21</div>	
				User RS-232 connection diagram 7)	10m	(Built into GOT)	<div>GT 04R 21</div> <div>GT 03P 21</div>	

*1 Product manufactured by IAI Corporation. For details of the product, contact IAI Corporation.

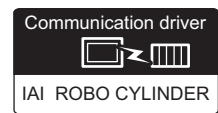
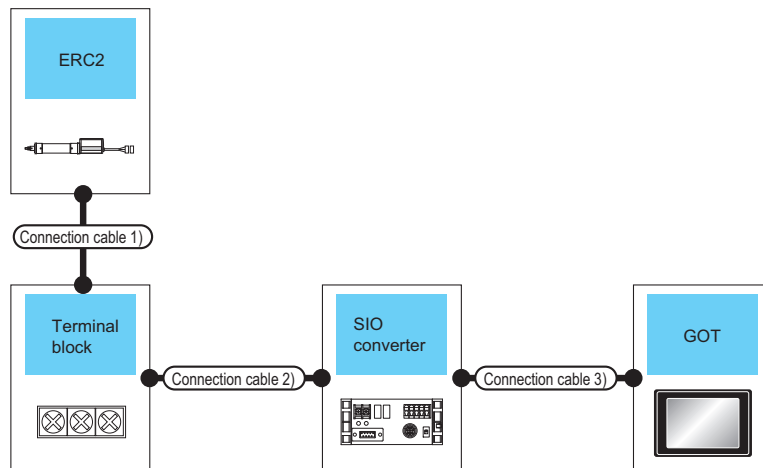
*2 Use ERC2-□-□-□-□-SE-□-□.













*3 Use the following models.

ERC2-□-□-□-□-NP-□-□, ERC2-□-□-□-□-PN-□-□

*4 When a GT10-C02H-6PT9P unit of the sub version A or B is used, do not ground the case of the D-sub (9-pin) connector.

(b) ERC2 (NP/PN specifications) only



Controller	Connection cable 1)* ¹	Terminal block	Connection cable 2)	Max. distance	SIO converter* ¹		Connection cable 3)		GOT		Number of connectable equipment
Model name	Cable model		Connection diagram number		Model name	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model	
ERC2 (NP/PN specifications) * ²	CB-ERC-PWBIO □□□ or CB-ERC-PWBIO □□□-RB	Terminal block (User preparing)	 RS-422/485 connection diagram 7) or  RS-422/485 connection diagram 8)	100m	RCB-TU-SIO-□	RS-232	RCB-CV-MW* ¹ (0.3m) + CB-RCA-SIO050* ¹ (5m) or  RS-232 connection diagram 3)	15m	- (Built into GOT)	  	1 GOT for 16 Controller
			RC□-TU-PIO* ¹						 RS-422/485 connection diagram 9)	GT15-RS-9P	
		GT10-C02H-6PT9P* ³								 	
		 RS-232 connection diagram 8)	- (Built into GOT)		 						

*1 Product manufactured by IAI Corporation. For details of the product, contact IAI Corporation.

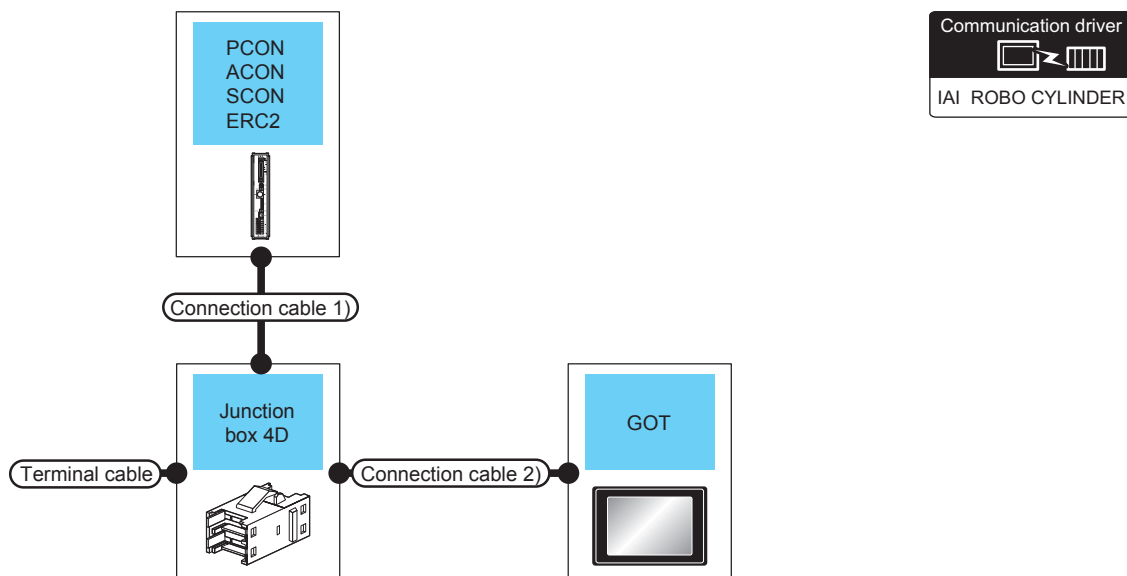
*2 Use the following models.

ERC2-□-□-□-□-NP-□-□, ERC2-□-□-□-□-PN-□-□

*3 When a GT10-C02H-6PT9P unit of the sub version A or B is used, do not ground the case of the D-sub (9-pin) connector.

(2) When using the RS-422/485 cable

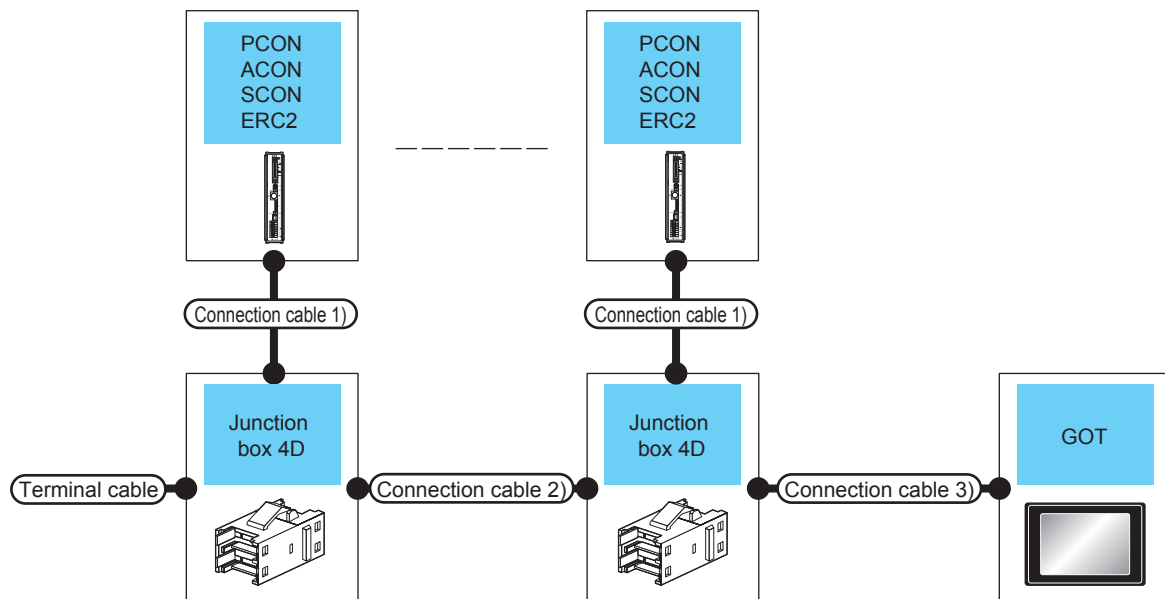
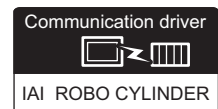
(a) PCON, ACON, SCON, ERC2 (SIO specifications), ERC2 (NP/PN specifications)
































Controller	Terminal cable	Connection cable 1)*1	Junction box 4D)*2	Connection cable 2)	GOT		Max. distance	Number of connectable equipment
Model name	Connection diagram number	Cable model	Model name	Connection diagram number	Option device	Model		
PCON ACON SCON ERC2 (NP/PN specifications) *5	RS-422/485 connection diagram 1)	CB-RCB-CTL002 (0.2m)	5-1473574-4	RS-422/485 connection diagram 3)	FA-LTBGT2R4CBL05(0.5m)*3 FA-LTBGT2R4CBL10(1m)*3 FA-LTBGT2R4CBL20(2m)*3	 	100m	16 Controllers for 1 GOT
					- (Built into GOT)	 		
				RS-422/485 connection diagram 4)	GT15-RS4-9S	 		
					GT10-C02H-9SC	 		
				RS-422/485 connection diagram 5)	GT15-RS4-TE	 		
				RS-422/485 connection diagram 14)	- (Built into GOT)	 		

■ 2. When connecting to multiple controllers

(1) PCON, ACON, SCON, ERC2 (SIO specifications), ERC2 (NP/PN specifications)



Controller	Terminal cable	Connection cable 1)*1	Junction box 4D*2	Connection cable 2)	Connection cable 3)	GOT		Max. distance	Number of connectable equipment
Model name	Connection diagram number	Cable model	Model name	Connection diagram number	Connection diagram number	Option device	Model		
PCON ACON SCON ERC2 (NP/PN specifications) *5	(User preparing) RS-422/ 485 connection diagram 1)	CB-RCB-CTL002 (0.2m)	5-1473574-4	(User preparing) RS-422/ 485 connection diagram 2)	(User preparing) RS-422/ 485 connection diagram 3)	FA-LTBGT2R4CBL05(0.5m)*3 FA-LTBGT2R4CBL10(1m)*3 FA-LTBGT2R4CBL20(2m)*3	GT 27 GT 25 GT 23	100m	16 Controllers for 1 GOT
						(Built into GOT)	GT 27 GT 25 GT 23 GS		
					(User preparing) RS-422/ 485 connection diagram 4)	GT15-RS4-9S	GT 27 GT 25		
						GT10-C02H-9SC	GT 21 GT 25 GT 23		
					(User preparing) RS-422/ 485 connection diagram 5)	GT15-RS4-TE	GT 27 GT 25		
					(User preparing) RS-422/ 485 connection diagram 14)	(Built into GOT)	GT 21 GT 25 GT 23 GS		

Controller	Terminal cable	Connection cable 1)* ¹	Junction box 4D)* ²	Connection cable 2)	Connection cable 3)	GOT		Max. distance	Number of connectable equipment
Model name	Connection diagram number	Cable model	Model name	Connection diagram number	Connection diagram number	Option device	Model		
ERC2 (SIO specifications) * ⁴	 RS-422/485 connection diagram 1)	CB-ERC2-CTL001 + CB-ERC2-PWBIO □□□□ or CB-ERC2-PWBIO □□□□-RB	5-1473574-4	 RS-422/485 connection diagram 2)	 RS-422/485 connection diagram 3)	FA-LTBGT2R4CBL05(0.5m)* ³ FA-LTBGT2R4CBL10(1m)* ³ FA-LTBGT2R4CBL20(2m)* ³	  	100m	16 Controllers for 1 GOT
						- (Built into GOT)	    		
					 RS-422/485 connection diagram 4)	GT15-RS4-9S	 		
						GT10-C02H-9SC	   		
					 RS-422/485 connection diagram 5)	GT15-RS4-TE	 		
					 RS-422/485 connection diagram 14)	- (Built into GOT)	      		

*¹ Product manufactured by IAI Corporation. For details of the product, contact IAI Corporation.

*² Product manufactured by Tyco Electronics. For details of the product, contact Tyco Electronics.

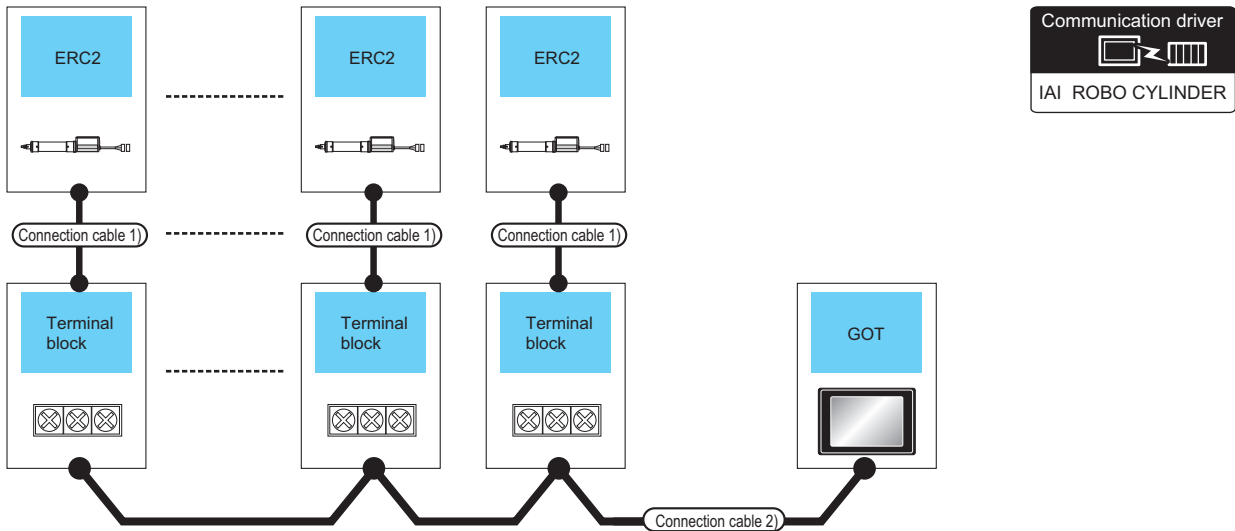
*³ Product manufactured by MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED. For details of the product, contact MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED.

*⁴ Use ERC2-□-□-□-□-SE-□-□.

*⁵ Use the following models.

ERC2-□-□-□-□-NP-□-□, ERC2-□-□-□-□-PN-□-□

(2) ERC2 (NP/PN specifications) only



Controller	Connection cable 1)* ¹	Terminal block	Connection cable 2)	GOT		Max. distance	Number of connectable equipment
Model name	Cable model		Connection diagram number	Option device	Model		
ERC2 (NP/PN specifications)* ⁴	CB-ERC-PWBIO □□□ or CB-ERC-PWBIO □□□-RB	Terminal block (User preparing)	RS-422/485 connection diagram 10)	FA-LTBGT2R4CBL05 (0.5m)* ² FA-LTBGT2R4CBL10 (1m)* ² FA-LTBGT2R4CBL20 (2m)* ²		100m	16 Controllers for 1 GOT
			RS-422/485 connection diagram 11)	- (Built into GOT)			
				GT15-RS4-9S			
				GT10-C02H-9SC			
			RS-422/485 connection diagram 12)	GT15-RS4-TE			
			RS-422/485 connection diagram 15)	- (Built into GOT)			

*¹ Product manufactured by IAI Corporation. For details of the product, contact IAI Corporation.

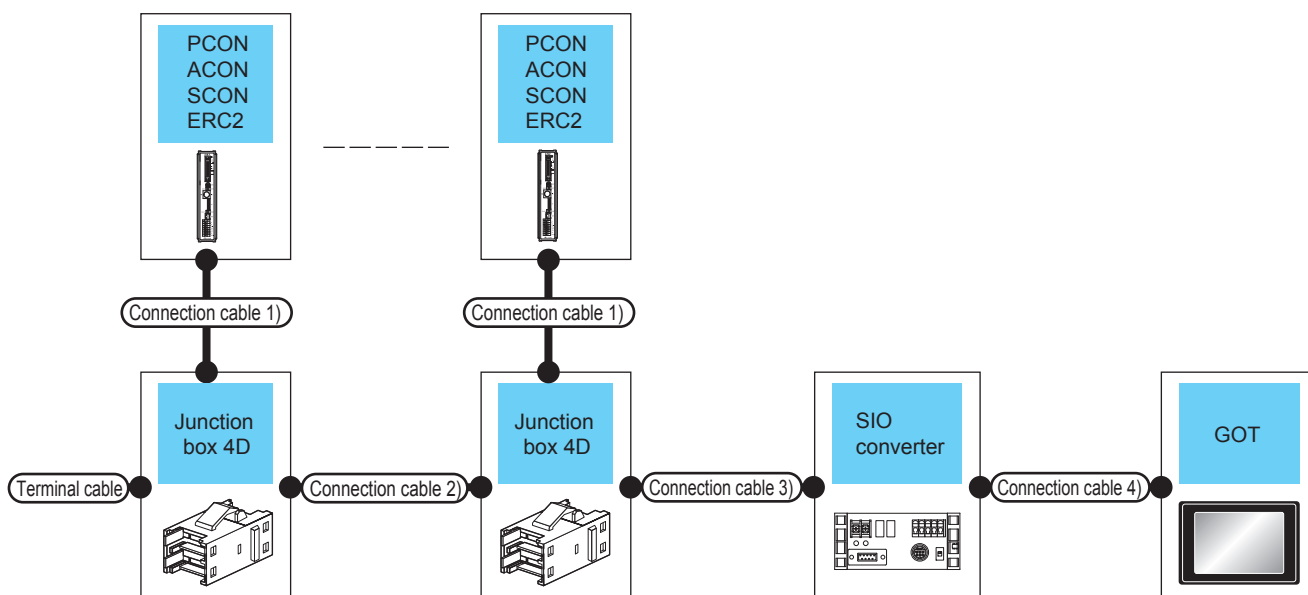
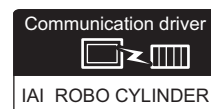
*² Product manufactured by MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED. For details of the product, contact MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED.

*³ Use the following models.


















ERC2-□-□-□-□-□-NP-□-□, ERC2-□-□-□-□-□-PN-□-□

3. When connecting to multiple controllers (via SIO converter)

(1) PCON, ACON, SCON, ERC2 (SIO specifications), ERC2 (NP/PN specifications)



Controller	Terminal cable	Connection cable 1)* ¹	Junction box 4D* ²	Connection cable 2)	Connection cable 3)	Max. distance	SIO converter* ¹		Connection cable 4)		GOT		Number of connectable equipment
Model name	Connection diagram number	Cable model	Model name	Connection diagram number	Connection diagram number		Model name	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model	
PCON ACON SCON	(User preparing) RS-422/ 485 connection diagram 1)	CB-RCB-CTL002 (0.2m)	5-147357 4-4	(User preparing) RS-422/ 485 connection diagram 2)	(User preparing) RS-422/ 485 connection diagram 2) or (User preparing) RS-422/ 485 connection diagram 6)	100m	RCB-TU-SIO-□	RS-232	RCB-CV-MW* ¹ (0.3m) + CB-RCA-SIO050* ¹ (5m) or (User preparing) RS-232 connection diagram 3)	15m	- (Built into GOT)	GT 27 GT 25 GT 23 GT 21 GS	16 Controllers for 1 GOT
												GT 27 GT 25	
												GT10-C02H-6PT9 P* ⁶	
									(User preparing) RS-232 connection diagram 8)			GT 21 GT 25 GT 03R 21 GT 03R 25 GT 04R 21 GT 04R 25	

Controller	Terminal cable	Connection cable 1)*1	Junction box 4D*2	Connection cable 2)	Connection cable 3)	Max. distance	SIO converter*1		Connection cable 4)		GOT		Number of connectable equipment
Model name	Connection diagram number	Cable model	Model name	Connection diagram number	Connection diagram number		Model name	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model	
PCON ACON SCON	 RS-422/ 485 connection diagram 1)	CB-RCB- CTL002*3 (0.2m)	-	-	-	100m	RCB- TU- SIO- □	RS-232	RCB-CV- MW*1 (0.3m) + CB-RCA- SIO050*1 (5m) or  RS-232 connection diagram 3)	15m	- (Built into GOT)		2 Controllers for 1 GOT
									GT15- RS2- 9P				
									GT10- C02H- 6PT9 P*6				
									 RS-232 connection diagram 8)		- (Built into GOT)		
ERC2 (SIO specifications)*4	 RS-422/ 485 connection diagram 1)	CB-ERC2- CTL001 + CB-ERC2- PWBIO □□□ or CB-ERC2- PWBIO □□□-RB	5- 147357 4-4	 RS-422/ 485 connection diagram 2)	 RS-422/ 485 connection diagram 2) or  RS-422/ 485 connection diagram 6)	100m	RCB- TU- SIO- □	RS-232	RCB-CV- MW*1 (0.3m) + CB-RCA- SIO050*1 (5m) or  RS-232 connection diagram 3)	15m	- (Built into GOT)		16 Controllers for 1 GOT
									GT15- RS2- 9P				
									GT10- C02H- 6PT9 P*6				
									 RS-232 connection diagram 8)		- (Built into GOT)		

Controller	Terminal cable	Connection cable 1)* ¹	Junction box 4D)* ²	Connection cable 2)	Connection cable 3)	Max. distance	SIO converter)* ¹		Connection cable 4)		GOT		Number of connectable equipment
Model name	Connection diagram number	Cable model	Model name	Connection diagram number	Connection diagram number		Model name	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model	
ERC2 (SIO specifications)* ⁴	-	CB-ERC2-CTL001 + CB-ERC2-PWBIO □□□□ or CB-ERC2-PWBIO □□□□-RB	-	-	-	100m	RCB-TU-SIO-□	RS-232	RCB-CV-MW)* ¹ (0.3m) + CB-RCA-SIO050)* ¹ (5m) or (User preparing) RS-232 connection diagram 3)	15m	- (Built into GOT)	GT 27 25 GT 23 21 GS	2 Controllers for 1 GOT
											GT15-RS2-9P	GT 27 25	
											GT10-C02H-6PT9 P* ⁶	GT 03B 21 04B 22 GT 03B 21 04B 22	
											- (Built into GOT)	GT 04B 21 04B 22 GT 03B 21 04B 22	
ERC2 (NP/PN specifications)* ⁵	(User preparing) RS-422/485 connection diagram 1)	CB-ERC-PWBIO □□□□ or CB-ERC-PWBIO □□□□-RB + Terminal block (User preparing) + (User preparing) RS-422/485 connection diagram 13)	5-147357 4-4	(User preparing) RS-422/485 connection diagram 2)	(User preparing) RS-422/485 connection diagram 2) or (User preparing) RS-422/485 connection diagram 6)	100m	RCB-TU-SIO-□	RS-232	RCB-CV-MW)* ¹ (0.3m) + CB-RCA-SIO050)* ¹ (5m) or (User preparing) RS-232 connection diagram 3)	15m	- (Built into GOT)	GT 27 25 GT 23 21 GS	16 Controllers for 1 GOT
											GT15-RS2-9P	GT 27 25	
											GT10-C02H-6PT9 P* ⁶	GT 03B 21 04B 22 GT 03B 21 04B 22	
											- (Built into GOT)	GT 04B 21 04B 22 GT 03B 21 04B 22	

*1 Product manufactured by IAI Corporation. For details of the product, contact IAI Corporation.

*2 Product manufactured by Tyco Electronics. For details of the product, contact Tyco Electronics.

*3 When not using junction box 4D, connection cable 2) or connection cable 3), connect the controller to the SIO converter directly by the cable CR-RCB-CTL002.

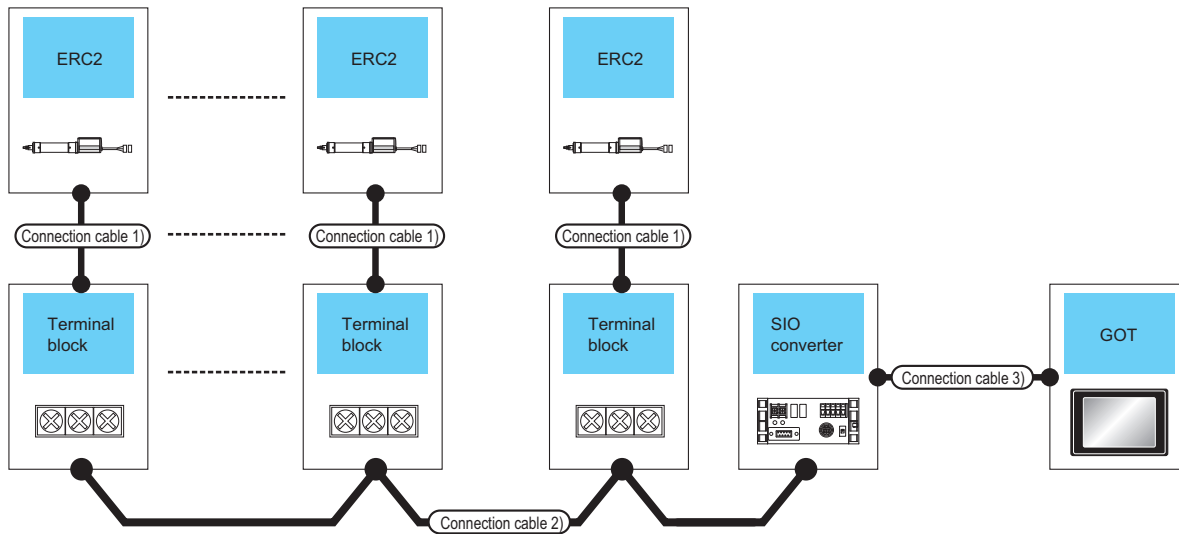
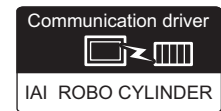
*4 Use ERC2-□-□-□-□-SE-□-□.

*5 Use the following models.

ERC2-□-□-□-□-NP-□-□, ERC2-□-□-□-□-PN-□-□

*6 When a GT10-C02H-6PT9P unit of the sub version A or B is used, do not ground the case of the D-sub (9-pin) connector.

(2) ERC2 (NP/PN specifications) only



Controller	Connection cable 1)* ¹	Terminal block	Connection cable 2)	Max. disantance	SIO converter* ¹		Connection cable 4)		GOT		Number of connectable equipment
Model name	Cable model		Connection diagram number		Model name	Connection diagram number	Cable model Connection diagram number	Max. disantance	Option device	Model* ³	
ERC2 (NP/PN specifications) * ³	CB-ERC-PWBIO □□□ or CB-ERC-PWBIO □□□-RB	Terminal block (User preparing)	<div>User preparing</div> RS-422/485 connection diagram 13) or <div>User preparing</div> RS-422/485 connection diagram 8)	100m	RCB-TU-SIO-□	RS-232	RCB-CV-MW* ¹ (0.3m) + CB-RCA-SIO050* ¹ (5m) or <div>User preparing</div> RS-232 connection diagram 3)	15m	- (Built into GOT)	<div>GT 27</div> <div>GT 25</div> <div>GT 23</div> <div>GT 21</div> <div>GS</div>	16 Controllers for 1 GOT
		RC □-TU-PIO* ¹	<div>User preparing</div> RS-422/485 connection diagram 9)						GT15-RS2-9P* ²	<div>GT 27</div> <div>GT 25</div>	
									GT10-C02H-6PT9P * ⁴	<div>GT 03B 21 04P R4</div> <div>GT 103B 21 104P R2</div>	
		- (Built into GOT)	<div>GT 04B 21</div> <div>GT 21 103B 21 104P R2</div>								

*1 Product manufactured by IAI Corporation. For details of the product, contact IAI Corporation.

*2 Connect it to the RS-232 interface (built into GOT). It cannot be mounted on GT1655 and GT155□.

*3 Use the following models.

ERC2-□-□-□-□-NP-□-□, ERC2-□-□-□-□-PN-□-□

*4 When a GT10-C02H-6PT9P unit of the sub version A or B is used, do not ground the case of the D-sub (9-pin) connector.

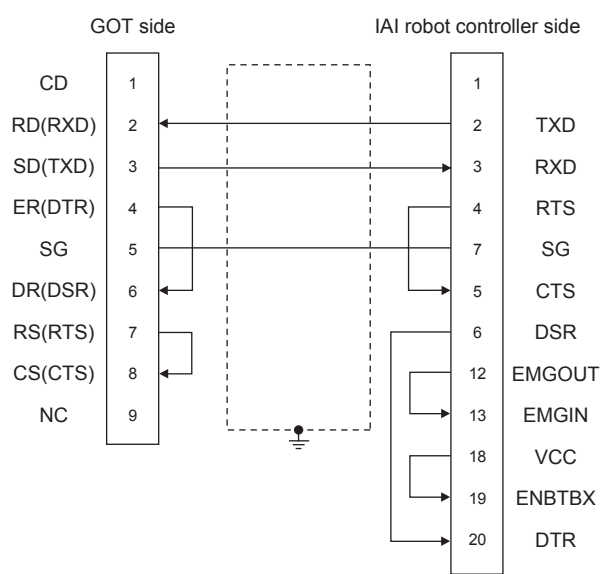
2.3 Connection Diagram

The following diagram shows the connection between the GOT and the PLC.

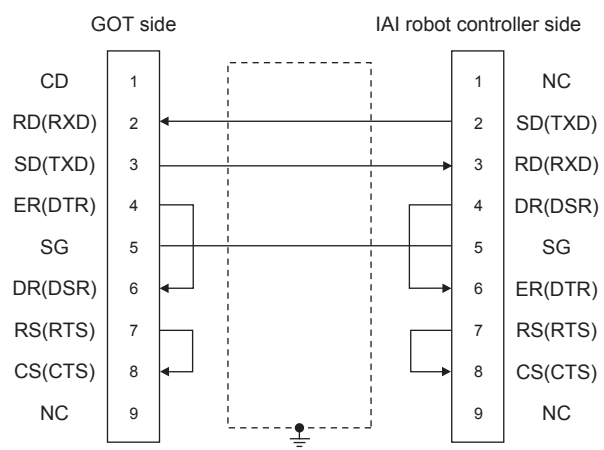
2.3.1 RS-232 cable

1. Connection diagram

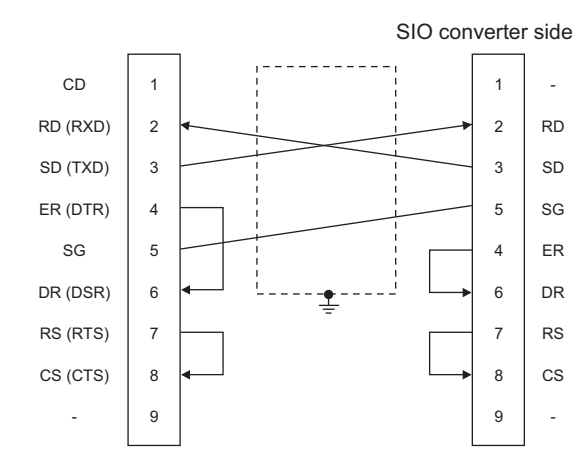
(1) RS-232 connection diagram 1)



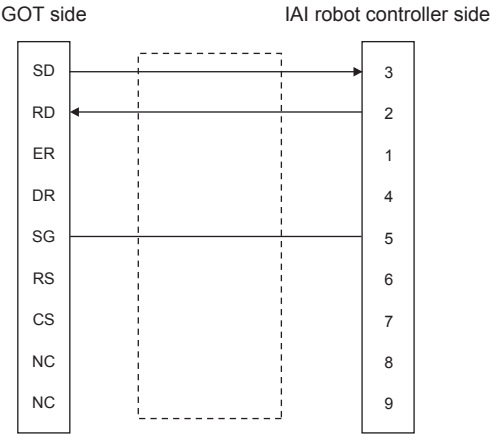
(2) RS-232 connection diagram 2)



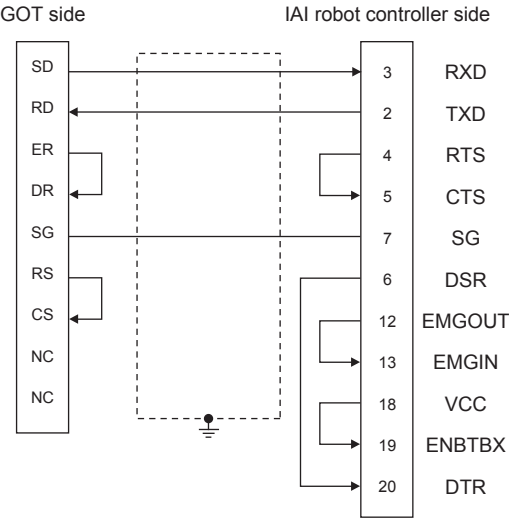
(3) RS-232 connection diagram 3)



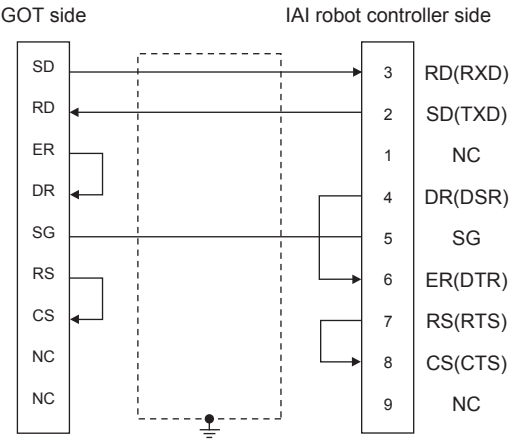
(4) RS-232 connection diagram 4)

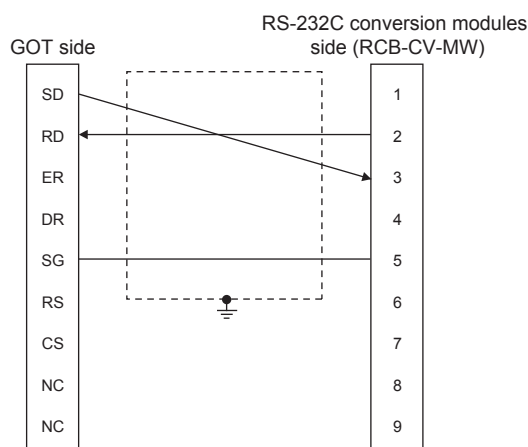
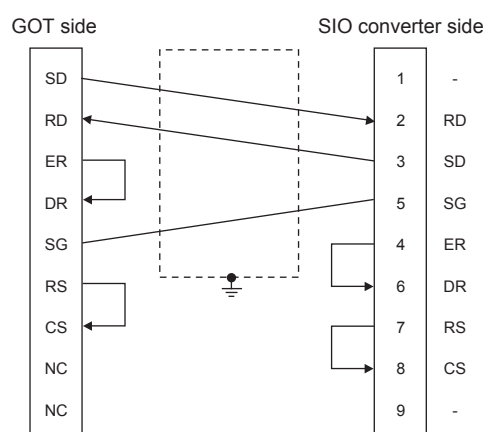


(5) RS-232 connection diagram 5)



(6) RS-232 connection diagram 6)



(7) RS-232 connection diagram 7)**(8) RS-232 connection diagram 8)****2. Precautions when preparing a cable****(1) Cable length**

The length of the RS-232 cable must be 10cm or less.

(2) GOT side connector

For the GOT side connector, refer to the following.

➡ 1.4.1 GOT connector specifications

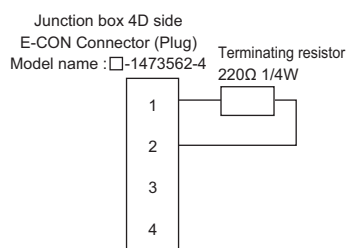
(3) IAI Robot Controller side connector

Use the connector compatible with the IAI Robot Controller.
For details, refer to the IAI Robot Controller user's manual.

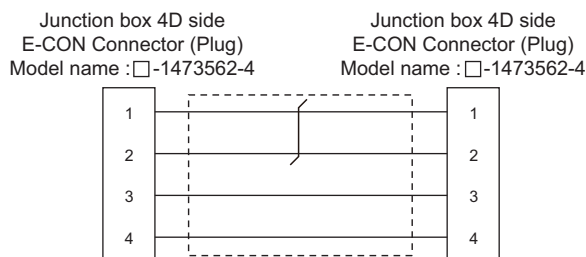
2.3.2 RS-422/485 cable

■ 1. Connection diagram

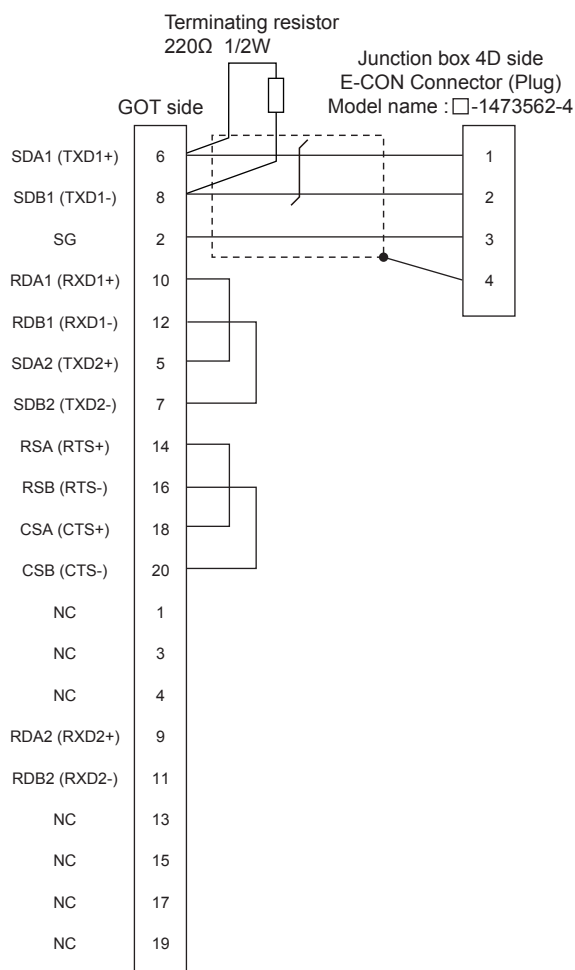
(1) RS-422/485 connection diagram 1)

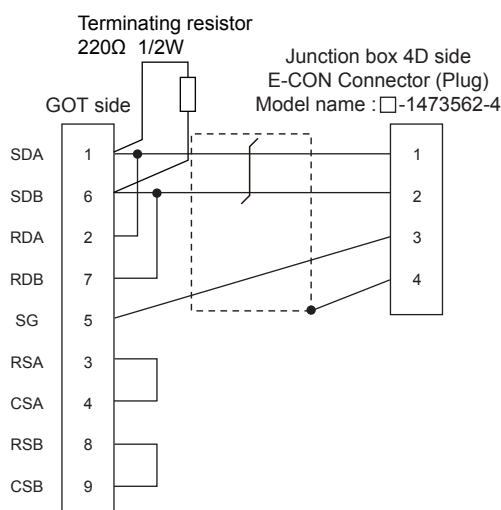
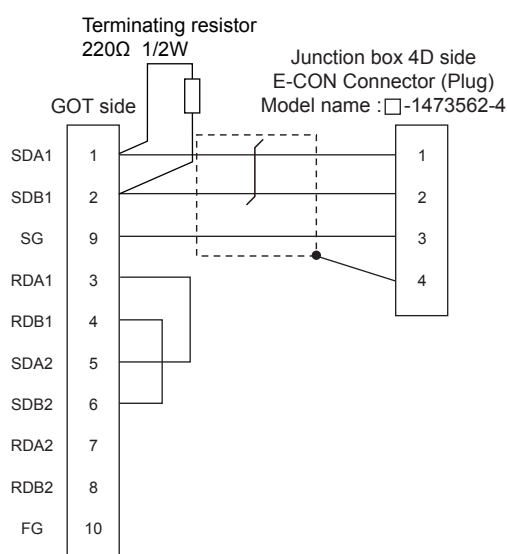
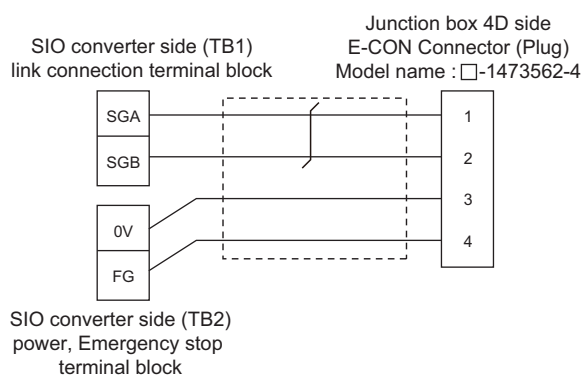


(2) RS-422/485 connection diagram 2)

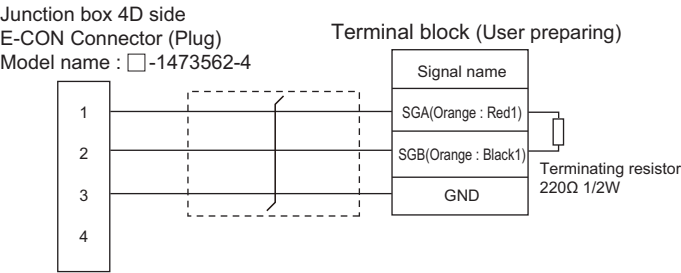


(3) RS-422/485 connection diagram 3)

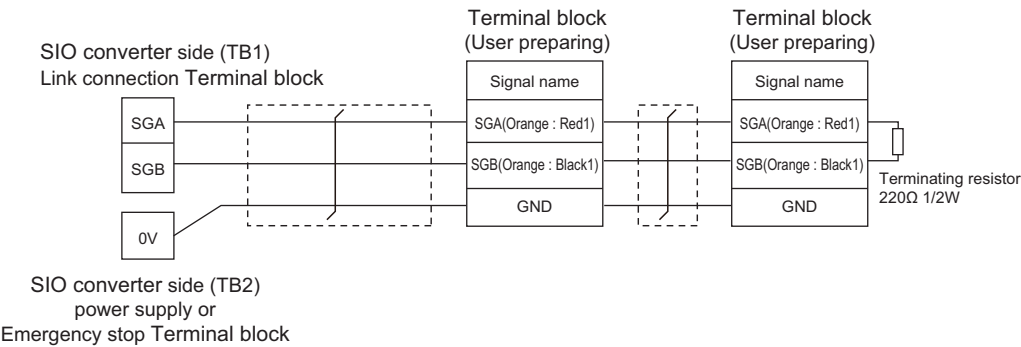


(4) RS-422/485 connection diagram 4)**(5) RS-422/485 connection diagram 5)****(6) RS-422/485 connection diagram 6)**

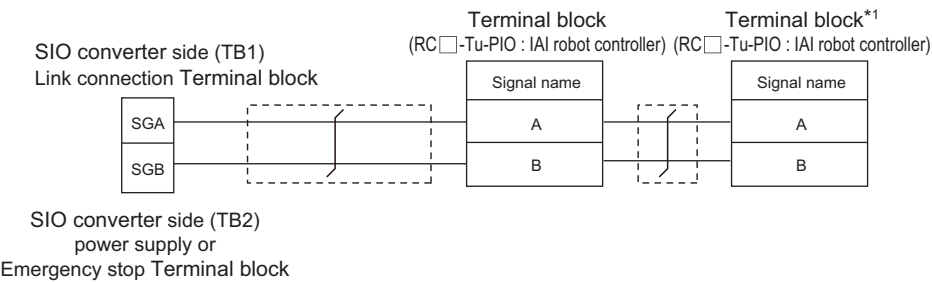
(7) RS-422/485 connection diagram 7)



(8) RS-422/485 connection diagram 8)

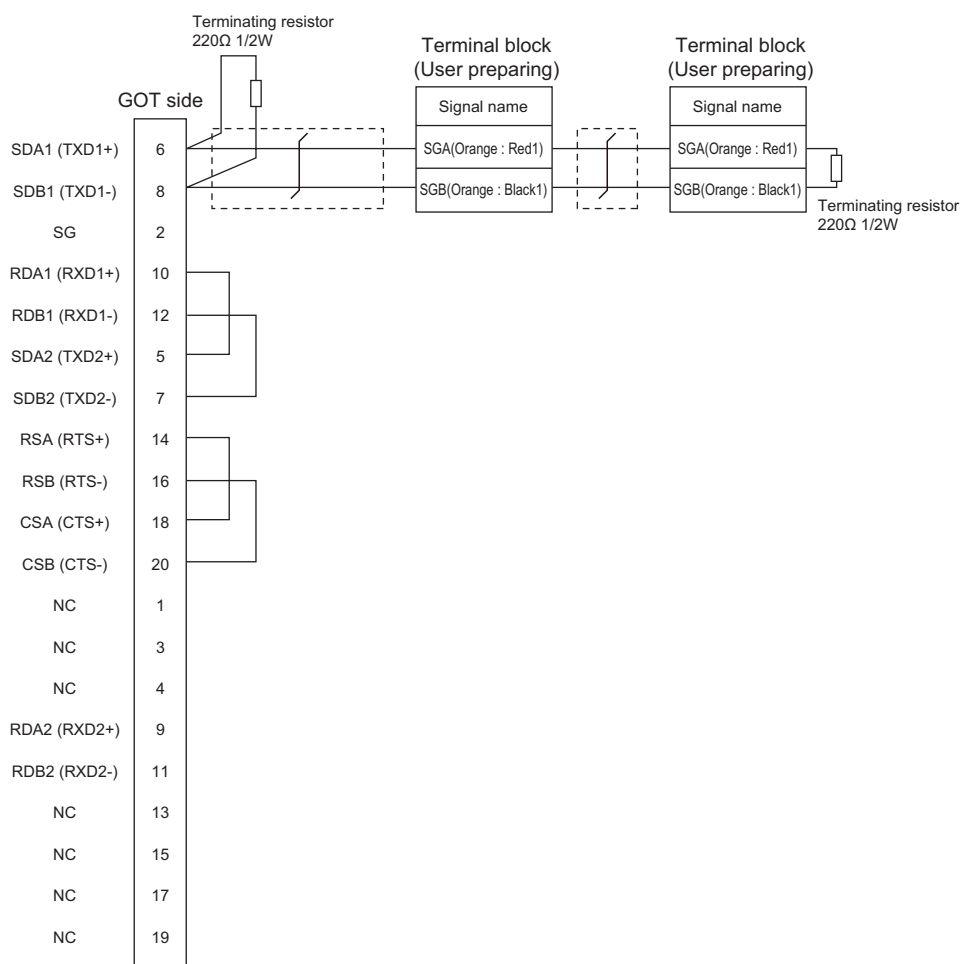


(9) RS-422/485 connection diagram 9)

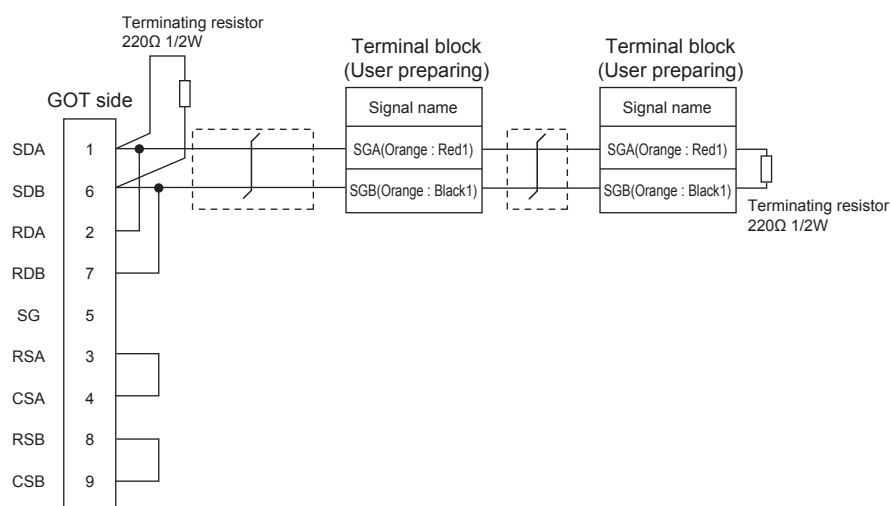


*1 Turn the terminator switch of a terminal block which will be a terminal to "RTON".

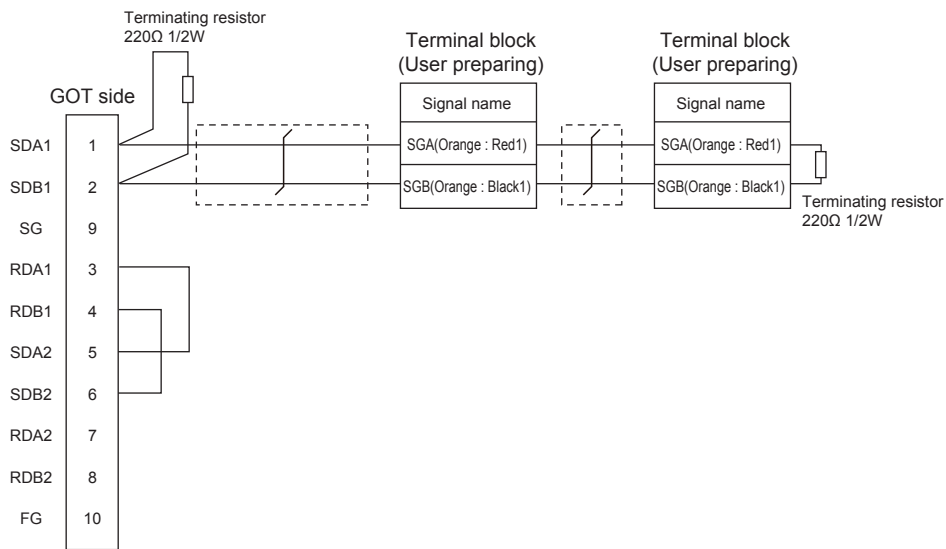
(10) RS-422/485 connection diagram 10)



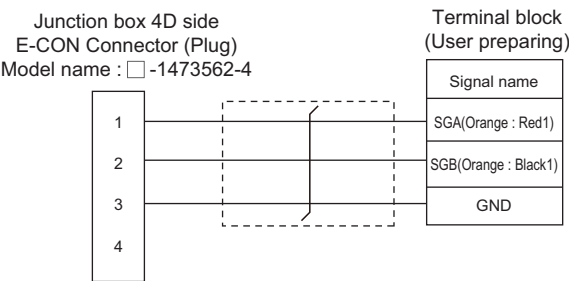
(11) RS-422/485 connection diagram 11)



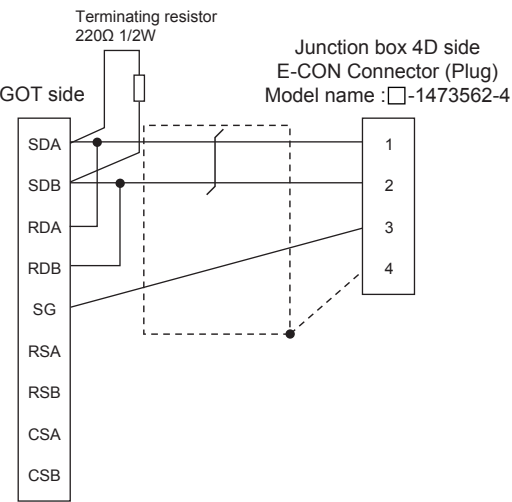
(12) RS-422/485 connection diagram 12)

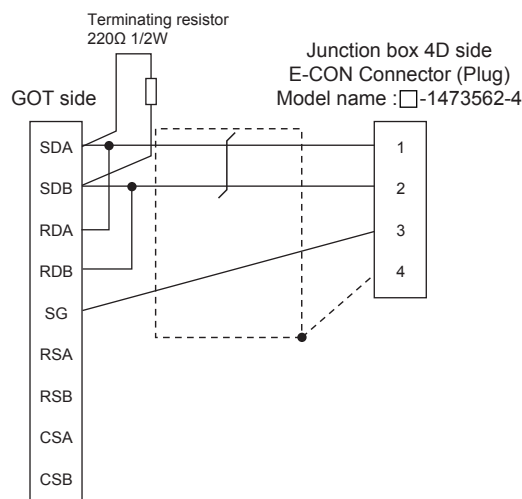


(13) RS-422/485 connection diagram 13)



(14) RS-422/485 connection diagram 14)



(15) RS-422/485 connection diagram 15)**2. Precautions when preparing a cable****(1) Cable length**

The maximum length of the RS-422/485 cable must be 100m or less.

(2) GOT side connector

For the GOT side connector, refer to the following.

➡ 1.4.1 GOT connector specifications

(3) E-CON connector (plug) (Type name: □-1473562-4)

Product manufactured by Tyco Electronics. For details of the product, contact Tyco Electronics.

3. Connecting terminating resistors**(1) GOT side**

When connecting a PLC to the GOT, a terminating resistor must be connected to the GOT.

(a) For GT27, GT25, GT23

Set the terminating resistor setting switch of the GOT main unit to "Disable".

(b) For GT21

Set the terminating resistor selector to "OPEN".

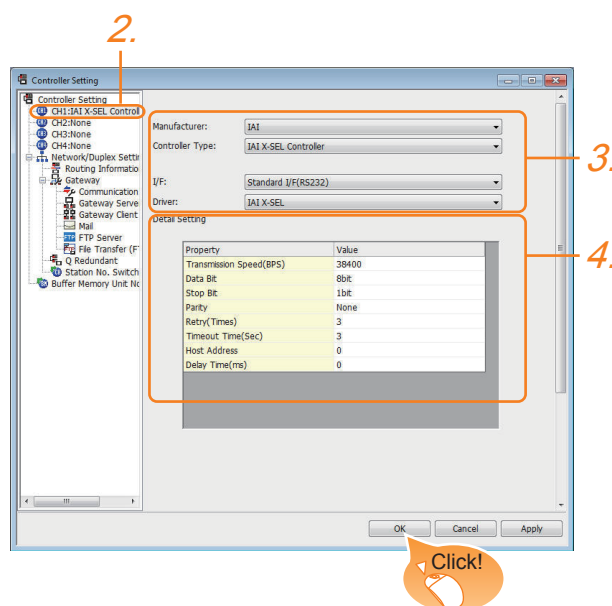
For the procedure to set the terminating resistor, refer to the following.

➡ 1.4.3 Terminating resistors of GOT

2.4 GOT Side Settings

2.4.1 Setting communication interface (Communication settings)

Set the channel of the equipment to be connected to the GOT.



Step 1. Select [Common] → [Controller Setting] from the menu.

Step 2. The Controller Setting window is displayed. Select the channel to be used from the list menu.

Step 3. Set the following items.

- Manufacturer: IAI
- Controller Type: Set either of followings.
<Connecting to X-SEL, SSEL, ASEL, PSEL>
IAI X-SEL Controller
<Connecting to PCON, ACON, SCON, ERC2>
IAI ROBO CYLINDER
- I/F: Interface to be used
- Driver: Set either of followings.
<Connecting to X-SEL, SSEL, ASEL, PSEL>
IAI X-SEL
<Connecting to PCON, ACON, SCON, ERC2>
IAI ROBO CYLINDER

Step 4. The detailed setting is displayed after Manufacturer, Controller Type, I/F, and Driver are set. Make the settings according to the usage environment.

⇒ 2.4.2 Communication detail settings

Click the [OK] button when settings are completed.

POINT

The settings of connecting equipment can be confirmed in [I/F Communication Setting].
For details, refer to the following.

⇒ 1.1.2 I/F communication setting

2.4.2 Communication detail settings

Make the settings according to the usage environment.

Property	Value
Transmission Speed(BPS)	38400
Data Bit	8 bit
Stop Bit	1 bit
Parity	None
Retry(Times)	3
Timeout Time(Sec)	3
Host Address	0
Delay Time(ms)	0

Item	Description	Range
Transmission Speed	Set this item when change the transmission speed used for communication with the connected equipment. (Default: 38400bps)	9600bps, 19200bps, 38400bps, 57600bps, 115200bps
Data Bit	Set this item when change the data length used for communication with the connected equipment. (Default: 8bits)	7bit, 8bit
Stop Bit	Specify the stop bit length for communications. (Default: 1bits)	1bit, 2bit
Parity	Specify whether or not to perform a parity check, and how it is performed during communication. (Default: None)	None Even Odd
Retry	Set the number of retries to be performed when a communication error occurs. (Default: 3time)	0 to 5times
Timeout Time	Set the time period for a communication to time out. (Default: 3sec)	1 to 30sec
Host Address	Make the settings according to the station number (station code) of the controller to be monitored. (Default: 0)	<Connecting to X-SEL, SSEL> 0 to 255 <Connecting to PCON, ACON, SCON> 0 to 15
Delay Time	Set this item to adjust the transmission timing of the communication request from the GOT. (Default: 0ms)	0 to 300 (ms)

POINT

(1) Communication interface setting by the Utility

The communication interface setting can be changed on the Utility's [Communication Settings] after writing [Communication Settings] of project data.
For details on the Utility, refer to the following manual.

➡ GOT2000 Series User's Manual (Utility)

(2) Precedence in communication settings

When settings are made by GT Designer3 or the Utility, the latest setting is effective.

2.5 Robot Controller Side Setting

POINT

IAI Robot Controller

For details of IAI Robot Controller, refer to the following manuals.

➡ IAI Robot Controller user's Manual

2.5.1 Connecting to X-SEL

■ 1. Parameter setting

Enter the following parameters using peripheral software. When setting parameters, set the mode switch of the controller to "MANU".

Parameter	Parameter Name	Set Value ^{*4}
I/O parameter 90	Usage of SIO channel 1 ^{*1} opened to user	<ul style="list-style-type: none">• When used in "MANU" Set either of the following. 0: SEL opened program 2: IAI protocol B• When used in "AUTO" 2: IAI protocol B
I/O parameter 91	Station code of SIO channel 1 ^{*1} opened to user	0 to 255 153*
I/O parameter 92 ^{*2}	Baud rate type of SIO channel 1 ^{*1} opened to user	0: 9600bps* 1: 19200bps 2: 38400bps 3: 57600bps 5: 115200bps
I/O parameter 93	Data length of SIO channel 1 ^{*1} opened to user	7bit, 8bit*
I/O parameter 94	Stop bit length of SIO channel 1 ^{*1} opened to user	1bit*, 2bit
I/O parameter 95	Parity type of SIO channel 1 ^{*1} opened to user	0: None* 1: Odd 2: Even
I/O parameter 97 ^{*3}	IAI-protocol minimum response delay for SIO channel 1 ^{*1} opened to user	0 to 999(ms)
Other parameter 46	Other setting bit pattern 1	bit0 to 3 = 1 (fixed)

*1 For X-SEL(P/Q/PX/QX), the parameter becomes the SIO channel 0 opened to user.

*2 Indicates only the transmission that can be specified on the GOT side.
Specify the transmission speed to match the baud rate of the GOT.

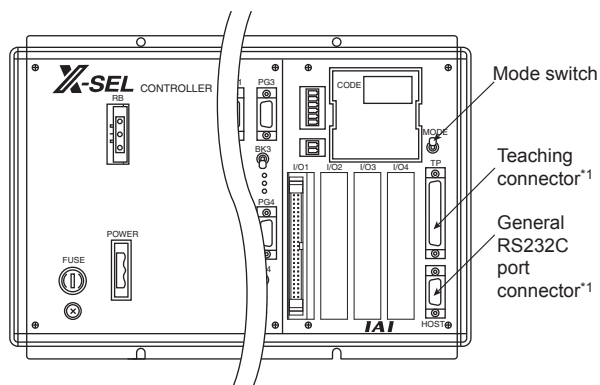
*3 Set it only when a wait time is required before the response and transmission to the GOT request. Normally, the communication is available using default values.

*4 When using the "MANU" mode, the set value is fixed to the value with *. Adjust the settings of the GOT side to the * settings. However, the communication setting of the PC software becomes the setting of X-SEL after the PC software for X-SEL is connected. In this case, adjust the communication setting of the GOT to the setting of the PC software.

2. Mode switch

(1) X-SEL K type

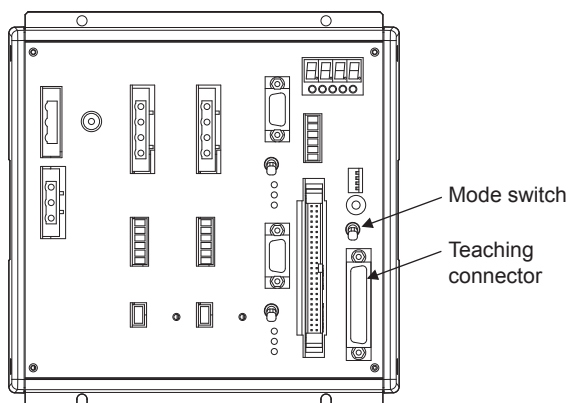
- (a) **When setting the mode switch to "MANU"**
Connect the GOT to the following teaching connector.
- (b) **When setting the mode switch to "AUTO"**
Connect the GOT to the following general RS232C port connector.



*1 The teaching connector and general RS232C port connector cannot be used at the same time.

(2) Other than X-SEL K type

Set the mode switch to "MANU" or "AUTO" and connect the GOT to the following teaching connector.



2.5.2 Connecting to SSEL, ASEL, PSEL

■ 1. Parameter setting

Enter the following parameters using peripheral software. When setting parameters, set the mode switch of the controller to "MANU".

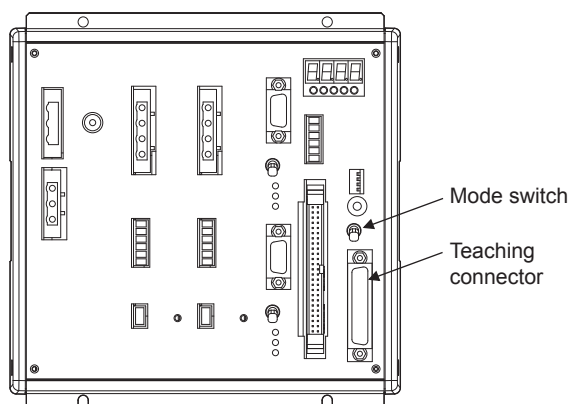
Parameter	Parameter Name	Set Value
I/O parameter 90	Usage of SIO channel 0 opened to user	2: IAI protocol B (fixed)
I/O parameter 91	Station code of SIO channel 0 opened to user	0 to 255
I/O parameter 92 ^{*1}	Baud rate type of SIO channel 0 opened to user	0: 9600bps 1: 19200bps 2: 38400bps 3: 57600bps 5: 115200bps
I/O parameter 93	Data length of SIO channel 0 opened to user	7bit, 8bit
I/O parameter 94	Stop bit length of SIO channel 0 opened to user	1bit, 2bit
I/O parameter 95	Parity type of SIO channel 0 opened to user	0: None 1: Odd 2: Even
I/O parameter 97 ^{*2}	IAI-protocol minimum response delay for SIO channel 0 opened to user	0 to 999(ms)
Other parameter 46	Other setting bit pattern 1	bit0 to 3 = 1 (fixed)

^{*1} Indicates only the transmission that can be specified on the GOT side.
Specify the transmission speed to match the baud rate of the GOT.

^{*2} Set it only when a wait time is required before the response and transmission to the GOT request. Normally, the communication is available using default values.

■ 2. Mode switch

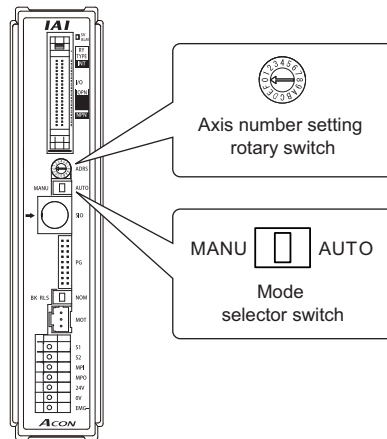
Set the mode switch to "AUTO" and connect the GOT to the following teaching connector.



2.5.3 Connecting to PCON, ACON, SCON

1. Axis number setting, Mode select

For controllers without the following switches, set from the setting tool (PC software).



Switch	Setting details
Axis number setting rotary switch	0 to 15
Mode selector switch	<Only the monitor> AUTO <monitor, data change> MANU

2. Transmission speed setting

Set the transmission speed from the setting tool (PC software).

Item	Range
SIO transmission speed*1	9600/19200/38400/57600/115200bps Default: 38400bps

*1 Indicates only the transmission speeds that can be set on the GOT side.
Set the same transmission speed of the GOT.

2.5.4 Connecting to ERC2

1. Axis number setting, Mode select

Set from the setting tool (PC software).

2. Transmission speed setting

Set the transmission speed from the setting tool (PC software).

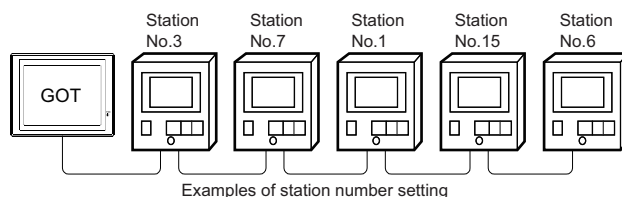
Item	Range
SIO transmission speed*1	9600/19200/38400/57600/115200bps Default: 38400bps

*1 Indicates only the transmission speeds that can be set on the GOT side.
Set the same transmission speed of the GOT.

2.5.5 Station No.settings

Set each station number so that no station number overlaps.

The station number can be set without regard to the cable connection order. There is no problem even if station numbers are not consecutive.



■1. Direct specification

When setting the device, specify the station number of the controller of which data is to be changed.

Model name	Specification range	Refer to
PCON, ACON, SCON	0 to 15	2.5.3
ERC2	0 to 15	2.5.4

■2. Indirect specification

When setting the device, indirectly specify the station number of the controller of which data is to be changed using the 16-bit GOT internal data register (GD10 to GD25).

When specifying the station No. from 100 to 115 on GT

Designer3, the value of GD10 to GD25 compatible to the station No. specification will be the station No. of the controller.

Specification station No.	Compatible device	Setting range
100	GD10	<p style="text-align: center;">0 to 15</p> <p>(If setting a value out of the range above, a timeout error occurs.)</p>
101	GD11	
102	GD12	
103	GD13	
104	GD14	
105	GD15	
106	GD16	
107	GD17	
108	GD18	
109	GD19	
110	GD20	
111	GD21	
112	GD22	
113	GD23	
114	GD24	
115	GD25	

2.6 Device Range that Can Be Set

The device ranges of controller that can be used for GOT are as follows.

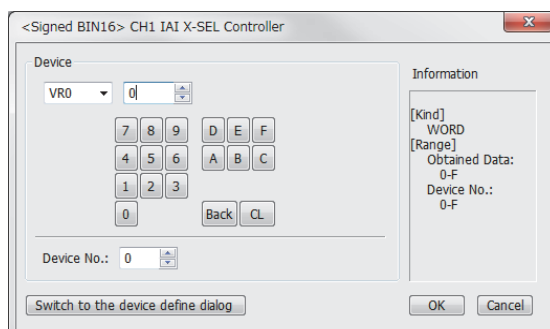
Note that the device ranges in the following tables are the maximum values that can be set in GT Designer3.

The device specifications of controllers may differ depending on the models, even though belonging to the same series. Please make the setting according to the specifications of the controller actually used.

When a non-existent device or a device number outside the range is set, other objects with correct device settings may not be monitored.

2.6.1 IAI robot controller (IAI X-SELController)

1. Setting item



Item	Description	
Device	Set the device name, device number, and bit number. The bit number can be set only when specifying the bit of word device.	
	Device No.	Set the number of the program for which the device is used.
	Information	Displays the device type and setting range which are selected in [Device].
Switch to the device define dialog	Device definition can be checked.	

POINT

Memory area for writing position data

Position data can be written to RAM or E²PROM of the controller.

(1) When written to RAM

Remember that written position data are cleared when power supply to the controller is turned off.

(2) When written to E²PROM

Written position data are not cleared even when power supply to the controller is turned off.

However, there are limits in the number of writing to E²PROM. If the data is frequently updated (more than once in an hour), write the parameters to the RAM. For details, refer to the manual of the controller used.

2. Device

Device name		Setting Range	Device No. representation
Bit device	Input Port (IP) ^{*1}	IP000 to IP299	Decimal
	Output Port (OP)	OP300 to OP599	
	Flag (FG)	FG000:600 to FG000:899 FG001:900 to FG001:999 : FG128:900 to FG128:999	
	Point Data Clear (PCLR) ^{*2*6}	PCLR0001 to PCLR4E20	Hexadecimal
Word device	Point Data Total Count (PDT) ^{*1}	PDT0	Decimal
	String (STR) ^{*3}	STR000:300 to STR000:998 STR001:001 to STR001:299 : STR128:001 to STR128:299	
	Axis Status (AXST) ^{*1}	AXST00 to AXST2F	Hexadecimal
	Scara Axis Status 0 (Base coordinate system) (SAXS0) ^{*1}	SAXS000 to SAXS0FF	
	Scara Axis Status 1 (Selected work coordinate system) (SAXS1) ^{*1}	SAXS100 to SAXS1FF	
	Scara Axis Status 2 (Reserved for system use) (SAXS2) ^{*1}	SAXS200 to SAXS2FF	
	Scara Axis Status 3 (Each axis system) (SAXS3) ^{*1}	SAXS300 to SAXS3FF	Hexadecimal
	Version 0 (Main CPU application/) (VR0) ^{*1}	VR00:0 to VR00:F : VR0F:0 to VR0F:F	
	Version 1 (Main CPU core) (VR1) ^{*1}	VR10:0 to VR10:F : VR1F:0 to VR1F:F	
	Version 2 (Driver CPU) (VR2) ^{*1}	VR20:0 to VR20:F : VR2F:0 to VR2F:F	
	Version 3 (Mount SIO) (VR3) ^{*1}	VR30:0 to VR30:F : VR3F:0 to VR3F:F	
	Program Status (PGST) ^{*1}	PGST000 to PGST511	Decimal
	System Status (SYST) ^{*1}	SYST0 to SYST6	
	Program Control (PRG) ^{*2*4}	PRG000 to PRG128	
	Alarm Reset (AR) ^{*2}	AR0	Decimal

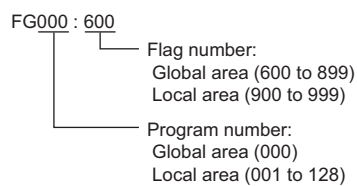
Device name		Setting Range	Device No. representation
Word device	Software Reset (SR) ^{*2*5}	SR0	Decimal
	Drive-Source Recovery (DSR) ^{*2}	DSR0	
	Origin return (RO) ^{*7}	RO0 to RO3	
	Point number specification movement (PNM) ^{*7}	PNM0 to PNM5	
	Operation stop/Cancel (OSC) ^{*7}	OSC0 to OSC2	
Double word device	Operation-Pause Reset (OPR) ^{*2}	OPR0	Hexadecimal
	Servo (SV) ^{*7}	SV0 to SV2	
	Write to Flash ROM (FRW) ^{*7}	FRW0 to FRW1	
	Coordinate Affiliate Data 0 (CD0) ^{*1}	CD000:0 to CD000:F : CD0FF:0 to CD0FF:F	Hexadecimal
	Coordinate Affiliate Data 1 (CD1) ^{*1}	CD100:0 to CD100:F : CD1FF:0 to CD1FF:F	
	Integer (INT)	INT000:0200 to INT000:1299 INT001:0001 to INT001:1099 : INT128:0001 to INT128:1099	Decimal
	Real (RL)	RL000:0300 to INT000:1399 RL001:0100 to INT001:1199 : INT128:0100 to INT128:1199	
	Jog/inch movement (JIM) ^{*7}	JIM0 to JIM6	
	Error Detail 0 (System error) (ER0) ^{*1}	ER000:000:00 to ER0FF:000:FF : ER000:FFF:00 to ER0FF:FFF:FF	Hexadecimal
	Error Detail 1 (Axis-specific error) (ER1) ^{*1}	ER100:000:00 to ER1FF:000:FF : ER100:FFF:00 to ER1FF:FFF:FF	
	Error Detail 2 (Program-specific error:)(ER2) ^{*1}	ER200:000:00 to ER2FF:000:FF : ER200:FFF:00 to ER2FF:FFF:FF	
	Error Detail 3 (Error in error list record)(ER3) ^{*1}	ER300:000:00 to ER3FF:000:FF : ER300:FFF:00 to ER3FF:FFF:FF	Hexadecimal
	Error Detail 4 (Reserved for system use) (ER4) ^{*1}	ER400:000:00 to ER4FF:000:FF : ER400:FFF:00 to ER4FF:FFF:FF	
	Error Detail 5 (Reserved for system use) (ER5) ^{*1}	ER500:000:00 to ER5FF:000:FF : ER500:FFF:00 to ER5FF:FFF:FF	
	Error Detail 6 (Reserved for system use) (ER6) ^{*1}	ER600:000:00 to ER6FF:000:FF : ER600:FFF:00 to ER6FF:FFF:FF	
	Error Detail 7 (Reserved for system use) (ER7) ^{*1}	ER700:000:00 to ER7FF:000:FF : ER800:FFF:00 to ER8FF:FFF:FF	
	Point Data Total Count (PD) ^{*7}	PD00 to PD9E	
	Simple Interference Check Zone Data (SD) ^{*1}	SD01:0 to SD01:F : SDFF:0 to SDFF:F	

- *1 Write disabled
- *2 Read disabled
- *3 The following restrictions are applied depending on the program number.
 - When the program number is 000, the variable number can be only even numbers.
 - When the program number is 001 to 128, the variable number can be only odd numbers.
- *4 For the program control device, the command to be sent differs depending on the write data. Write data other than the followings are processed as an internal error of GOT.
 - Write data 0: Program Exit Command(0x254)
 - Write data 1: Program Execution Command(0x253)
 - Write data 2: Program Pause Command(0x255)
 - Write data 3: Program 1 Step Execution Command(0x256)
 - Write data 4: Program Restart Command(0x257)
- *5 When performing software reset, a no response error is displayed after a non-communicating period of ten and several seconds, and then the communication is resumed.
- *6 For the word address, the value is specified only when the last digit is 1.
- *7 For the device whose obtained data No.0 is a command trigger, a request is sent to the controller when the Write or Read is input to the command trigger. It is not sent when the Clear is input.

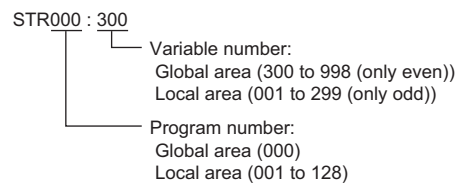
POINT

Device representation

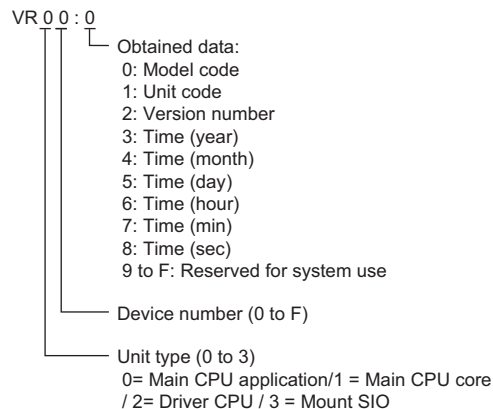
(1) Flag device



(2) String device



(3) Version device



(4) Axis Status device

AXST00



Obtained data:

AXST00 to AXST05: Single-axis status

00: Axis status

Bit 7 (Reserved for system use)

Bit 6 (Reserved for system use)

Bit 5 (Push error detection): 0 = Not detected / 1 = Detected

Bit 4 (Operation command successful completion):

0 = Not yet complete / 1 = Completed successfully

* Can be used only for completion check after an operation command.

Bit 3 (Servo): 0 = OFF / 1 = ON

Bit 1-2 (Origin return): 0 = Not yet performed

/ 1 = Returning to origin / 2 = Completed

Bit 0 (Servo axis in use): 0 = Not in use

/ 1 = In use (moving, etc.)

* "Servo axis in use" indicates that a given task has the right to use the applicable axis.

Therefore, this bit will turn ON in the following conditions:

- When an operation command involving axis movement is in progress (including when an axis is moving)
- Servo is starting up from an OFF state
- Servo is shutting down from an ON state (excluding emergency stop)
- Operation axis is paused

01: Axis sensor input status

Bit 3 (Reserved for system use)

Bit 2 (Origin sensor): 0 = OFF / 1 = ON

Bit 1 (Overrun sensor): 0 = OFF / 1 = ON

Bit 0 (Creep sensor): 0 = OFF / 1 = ON

02: Axis error code

03: Encoder status

Bit 7 (Battery alarm (BA))

Bit 6 (Battery error (BE))

Bit 5 (Multi-rotation error (ME))

Bit 4 (Reserved for system use)

Bit 3 (Counter overflow (OF))

Bit 2 (Count error (CE))

Bit 1 (Full absolute status (FS))

Bit 0 (Overspeed (OS))

04: Current position (L) unit (0.001mm)

Indicates the lower 16 bits of the current position in Hex.

05: Current position (H) unit (0.001mm)

Indicates the upper 16 bits of the current position in Hex.

AXST06 to AXST11: Double axes status

AXST42 to AXST47: Eight axes status

(5) Scara Axis Status device

SAXS 0 00

Obtained data:

00: Work coordinate system selection number

01: Tool coordinate system selection number

02: Common axis status

Bit 7 (Reserved for system use)

Bit 6 (Reserved for system use)

Bit 5 (Reserved for system use)

Bit 4 (Reserved for system use)

Bit 2-3 (Scara axis current position coordinate system type):

0 = Base coordinate system

/ 1 = Selected work coordinate system

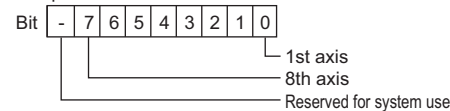
/ 2 = Reserved for system use / 3 = Each axis system

Bit 0-1: (Scara axis current arm system):

0 = Right arm system / 1 = Left arm system

/ 2 = Indeterminable / 3 = Reserved for system use

03: Axis pattern



04 to 09: Single-axis status

04: Axis status

Bit 7 (Reserved for system use)

Bit 6 (Reserved for system use)

Bit 5 (Push error detection): 0 = Not detected / 1 = Detected

Bit 4 (Operation command successful completion):

0 = Not yet complete / 1 = Completed successfully

* Can be used only for completion check after an operation command.(For positioning that includes any of the X, Y and R axes, be sure to check completion for all of the X, Y and R axes.)

Bit 3 (Servo): 0 = OFF / 1 = ON

Bit 1-2 (Origin return): 0 = Not yet performed

/ 1 = Returning to origin / 2 = Completed

Bit 0 (Servo axis in use): 0 = Not in use

/ 1 = In use (moving, etc.)

* "Servo axis in use" indicates that a given task has the right to use the applicable axis. Therefore, this bit will turn ON in the following conditions:

- When an operation command involving axis movement is in progress (including when an axis is moving)
- Servo is starting up from an OFF state
- Servo is shutting down from an ON state (excluding emergency stop)
- Operation axis is paused

05: Axis sensor input status

Bit 3 (Reserved for system use)

Bit 2 (Origin sensor): 0 = OFF / 1 = ON

Bit 1 (Overrun sensor): 0 = OFF / 1 = ON

Bit 0 (Creep sensor): 0 = OFF / 1 = ON

06: Axis error code

07: Encoder status

Bit 7 (Battery alarm (BA))

Bit 6 (Battery error (BE))

Bit 5 (Multi-rotation error (ME))

Bit 4 (Reserved for system use)

Bit 3 (Counter overflow (OF))

Bit 2 (Count error (CE))

Bit 1 (Full absolute status (FS))

Bit 0 (Overspeed (OS))

08: Current position (L) unit (0.001mm or 0.001deg)

Indicates the lower 16 bits of the current position in Hex.

09: Current position (H) unit (0.001mm or 0.001deg)

Indicates the upper 16 bits of the current position in Hex.

0A to 0E: Double axes status

...

2E to 33: Eight axes status

34 to FF: Reserved for system use

Unit type (0 to F)

Bit 3 (Reserved for system use) Fixed to 0

Bit 2 (Reserved for system use) Fixed to 0

Bit 0-1 (Scara axis current position type):

0 = Base coordinate system

/ 1 = Selected work coordinate system

/ 2 = Reserved for system use / 3 = Each axis system

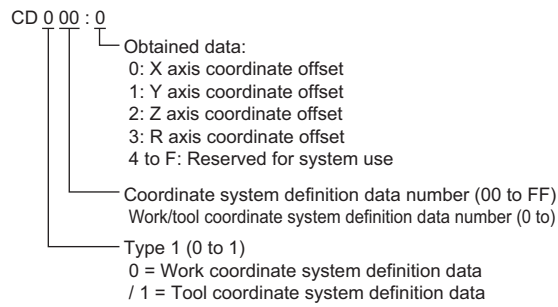
(6) Program Status device

PGST 000
 Obtained data:
 000 to 003: Program number 1 status
 000: Status
 Bit 3 (Reserved for system use)
 Bit 2 (Reserved for system use)
 Bit 1 (Reserved for system use)
 Bit 0 (Start): 0 = Not started / 1 = Started
 001: Execution program step number
 002: Program-dependent error code
 003: Error occurrence step number
 004 to 007: Program number 2 status
 . . .
 508 to 511: Program number 128 status

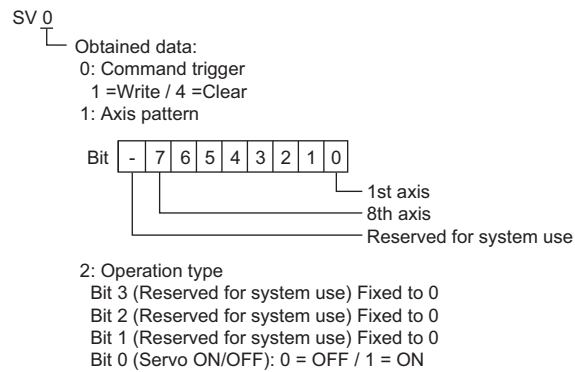
(7) System Status device

SYST 0
 Obtained data:
 0: System mode
 0 = Indeterminable / 1 = AUTO mode / 2 = MANUAL mode
 / 3 = Slave update mode / 4 = Core update mode
 1 Critical level system error number
 2: Latest system error number
 3: System status byte 1
 Bit 7 (Reserved for system use)
 Bit 6 (Battery voltage error status): 0 = No error / 1 = Error
 Bit 5 (Battery voltage low warning status): 0 = No low / 1 = Low
 Bit 4 (Power error status): 0 = Normal / 1 = Error
 Bit 3 (Emergency stop switch status):
 0 = No emergency stop / 1 = Emergency stop
 Bit 2 (Safety gate status): 0 = CLOSE / 1 = OPEN
 * X-SEL (P/Q Series) (Multi axes/Scara)/SSEL/ASEL/PSEL: Enable switch
 (Deadman switch / Enable switch) status is indicated.
 Bit 1 (TP enable switch status): 0 = ON / 1 = OFF
 * X-SEL (P/Q Series) (Multi axes/Scara)/SSEL/ASEL/PSEL:
 This bit is disabled (fixed to 0).
 Bit 0 (Operation mode switch status): 0 = AUTO / 1 = MANUAL
 4: System status byte 2
 Bit 7 (Reserved for system use)
 Bit 6 (Reserved for system use)
 Bit 5 (Program run status): 0 = Not run / 1 = Running
 Bit 4 (Restart wait status): 0 = Not waiting / 1 = Waiting
 Bit 3 (I/O interlock status): 0 = No interlock / 1 = Interlock
 Bit 2 (Servo interlock status): 0 = No interlock / 1 = Interlock
 Bit 1 (Slave parameter writing status):
 0 = Not writing / 1 = Writing
 Bit 0 (Application data flash ROM write status):
 0 = Not writing/erasing / 1 = Writing/erasing
 * When the core program is in operation (Application update mode),
 only Bit 0 is enabled. Data for System mode, Critical level
 system error number, Latest system error number,
 System status byte 1, System status byte 3 and System
 status byte 4 is disabled.
 5: System status byte 3
 Bit 7 (Reserved for system use)
 Bit 6 (Reserved for system use)
 Bit 5 (Reserved for system use)
 Bit 4 (Operation mode):
 0 = Program mode / 1 = Position mode
 Bit 3 (Reserved for system use)
 Bit 2 (System ready status): 0 = Not ready / 1 = Ready
 Bit 1 (System operation status):
 0 = Not operating in AUTO mode
 / 1 = Operating in AUTO mode
 Bit 0 (Drive-source cutoff status): 0 = Not cut off / 1 = Cut off
 6: System status byte 4
 Reserved for system use

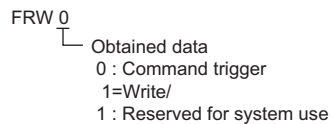
(8) Coordinate Affiliate Data device



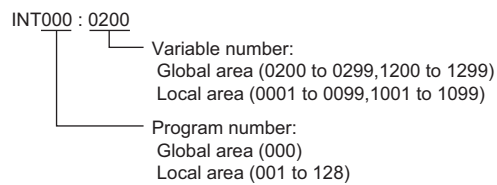
(9) Servo device



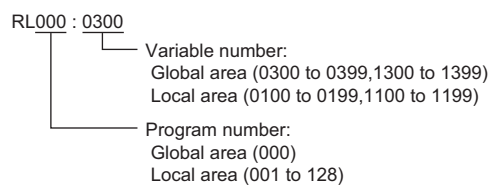
(10)Write to Flash ROM device



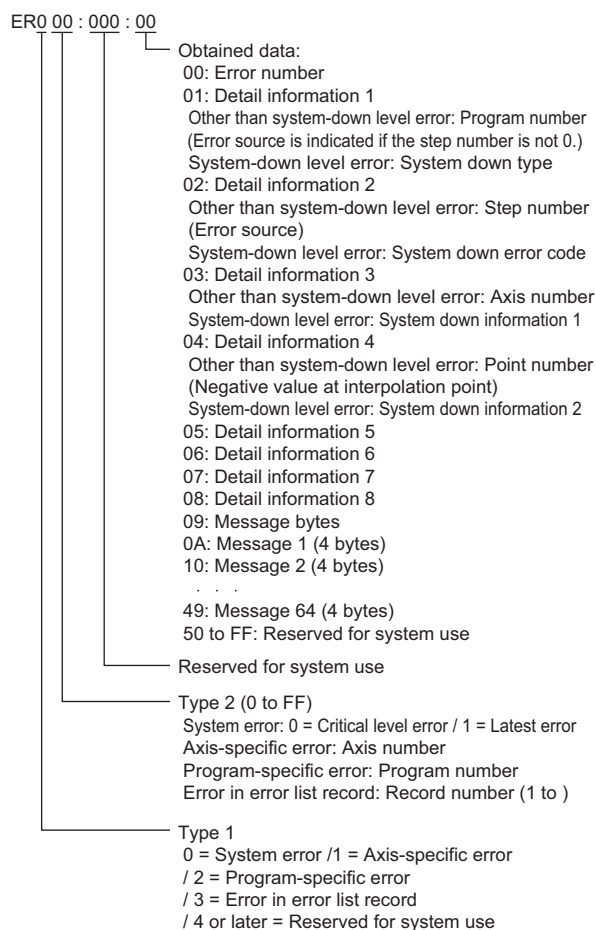
(11)Integer device



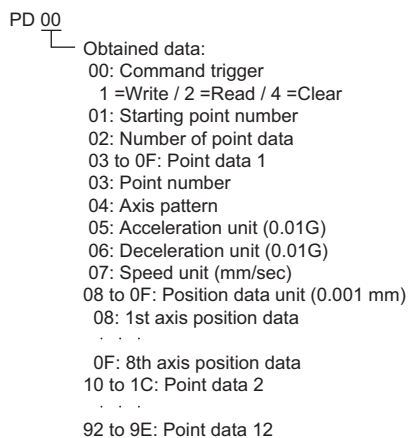
(12)Real device



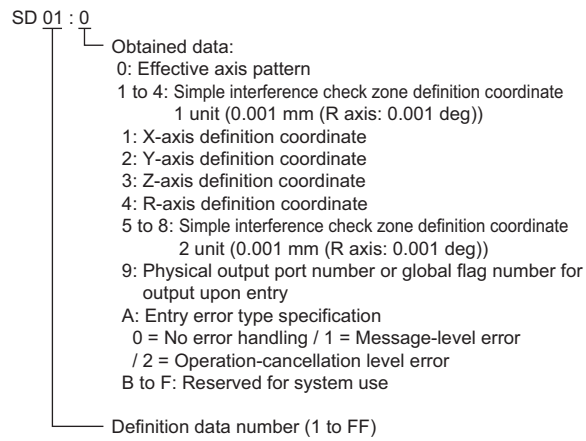
(13)Error Detaildevice(Detail 0 to Detail 7)



(14)Point Data Total Count device



(15)Simple Interference Check Zone Data device



2.6.2 IAI robot controller (IAI PCON, ACON, SCON, ERC2 controller)

1. Setting item

Item	Description	
Device	Set the device name, device number, and bit number. The bit number can be set only when specifying the bit of word device.	
Information	Displays the device type and setting range which are selected in [Device].	
Network	Station No.	Monitors the robo cylinder of the specified station No. 0 to 15: To monitor the robo cylinder of the specified station No. 100 to 115: To set the station No. of the robo cylinder to be monitored by the value of GOT data register (GD). ^{*1}
Switch to the device define dialog	Device definition can be checked.	

^{*1} The following shows the relation between station numbers of the robo cylinder and the GOT data register.

Station No.	GOT data register (GD)	Setting range
100	GD10	0 to 15 (If setting a value out of the range above, a timeout error occurs.)
101	GD11	
:	:	
114	GD24	
115	GD25	

2. Device

(1) Device name

Device name		Setting Range	Device No. representation
Bit device	Status (S)	S0000 to SFFFF	Hexadecimal
	The bit specification of the word device	Setting range of each word device	
Word / Double word device	Register (R)	R0000 to RFFFF	Hexadecimal

(2) Status (S) (Bit device)

The following shows device numbers which can be set for the status and the corresponding device contents.

Status	Area name	Description	Abbreviation
0000 to 00FF	- (Reserved for system)		
0100	Device status register 1 (DSS1)	EMG status	EMGS
0101		Safety speed enabled status	SFTY
0102		Controller ready status	PWR
0103		Servo ON status	SV
0104		Missed work in push-motion operation	PSFL
0105		Major failure status	ALMH
0106		Minor failure status	ALML
0107		Absolute error status	ABER
0108		Brake forced-release status	BKRL
0109		Cannot be used	
010A		Pause status	STP
010B		HomingHome return status	HEND
010C		Positioning completion Position complete status	PEND
010D to 010F		Cannot be used	
0110	Device status register 2 (DSS2)	Cannot be used	
0111		Cannot be used	
0112		Load output judgment status	LOAD
0113		Torque level status	TRQS
0114		Teaching mode status	MODS
0115		Position-data load command status	TEAC
0116		Jog+ status	JOG+
0117		Jog- status	JOG-
0118		Completed positionPosition complete 7	PE7
0119		Completed positionPosition complete 6	PE6
011A		Completed positionPosition complete 5	PE5
011B		Completed positionPosition complete 4	PE4
011C		Completed positionPosition complete 3	PE3
011D		Completed positionPosition complete 2	PE2
011E		Completed positionPosition complete 1	PE1
011F		Completed positionPosition complete 0	PE0
0120	Expansion device status register (DSSE)	Emergency stop status	EMGP
0121		Motor voltage low status	MPUV
0122		Operation mode status	RMDS
0123		Cannot be used	
0124		HomingHome return status	GHMS
0125		Push-motion operation in progress	PUSH
0126		Excitation detection status	PSNS
0127		PIO/Modbus switching status	PMSS
0128		Cannot be used	
0129		Cannot be used	
012A		Moving signal	MOVE
012B to 012F	Expansion device status register (DSSE)	Cannot be used	

Status	Area name	Description	Abbreviation
0130 to 0136	Position number status register (POSS)	Cannot be used	
0137		Completed position numberPosition complete number status bit 256	PM256
0138		Completed position numberPosition complete number status bit 128	PM128
0139		Completed position numberPosition complete number status bit 64	PM64
013A		Completed position numberPosition complete number status bit 32	PM32
013B		Completed position numberPosition complete number status bit 16	PM16
013C		Completed position numberPosition complete number status bit 8	PM8
013D		Completed position numberPosition complete number status bit 4	PM4
013E		Completed position numberPosition complete number status bit 2	PM2
013F		Completed position numberPosition complete number status bit 1	PM1
0140	Zone status register (ZONS)	Cannot be used	
0141		Limit sensor output monitor 2	LS2
0142		Limit sensor output monitor 1	LS1
0143		Limit sensor output monitor 0	LS0
0144 to 0146		Cannot be used	
0147		Position zone output monitor	ZP
0148 to 014D		Cannot be used	
014E		Zone output monitor 2	Z2
014F		Zone output monitor 1	Z1
0150 to 015F	Input port monitor register (DIPM)	PIO connector pin numbers 20A (IN15) to 5A (IN0)	
0160 to 016F	Output port monitor register (DOPM)	PIO connector pin numbers 16B (OUT15) to 1B (OUT0)	
0170	Special input port monitor register (SIPM)	Cannot be used	
0171		Command pulse NP signal status	NP
0172		Cannot be used	
0173		Command pulse PP signal status	PP
0174 to 0175		Cannot be used	
0176		Cannot be used	
0177		Mode switch status	MDSW
0178		Cannot be used	
0179 to 017B		Cannot be used	
017C		Home-check sensor monitor	HMCK
017D		Overtravel sensor	OT
017E		Creep sensor	CREP
017F		Limit sensor	LS
0180 to 03FF	- (Reserved for system)		

Status	Area name	Description	Abbreviation
0400	Device control register 1 (DRG1)	EMG operation specification	EMG
0401		Safety speed command	SFTY
0402		Cannot be used	
0403		Servo ON command	SON
0404 to 0406		Cannot be used	
0407		Alarm reset command	ALRS
0408		Brake forced-release command	BKRL
0409		Cannot be used	
040A		Pause command	STP
040B		HomingHome return command	HOME
040C		Positioning start command	CSTR
040D to 040F		Cannot be used	
0410	Device control register 2 (DRG2)	Cannot be used	
0411		Jog/inch switching	JISL
0412 to 0413		Cannot be used	
0414		Teaching mode command	MOD
0415		Position data load command	TEAC
0416		Jog+ command	JOG+
0417		Jog- command	JOG-
0418		Start position 7	ST7
0419		Start position 6	ST6
041A		Start position 5	ST5
041B		Start position 4	ST4
041C		Start position 3	ST3
041D		Start position 2	ST2
041E		Start position 1	ST1
041F		Start position 0	ST0
0420 to 0426	Expansion device control register (DRGE)	Cannot be used	
0427		PIO/Modbus switching specification	PMSL
0428 to 042B		Cannot be used	
042C		Deceleration stop	STOP
042D to 042F		Cannot be used	
0430 to 0436	Position number specification register (POSR)	Cannot be used	
0437		Position command bit 256	PC256
0438		Position command bit 128	PC128
0439		Position command bit 64	PC64
043A		Position command bit 32	PC32
043B		Position command bit 16	PC16
043C		Position command bit 8	PC8
043D		Position command bit 4	PC4
043E		Position command bit 2	PC2
043F		Position command bit 1	PC1
0440 to FFFF	- (Reserved for system)		

3. Register (R) (Word device/Double word device)

The following shows device numbers which can be set for the register and the corresponding device contents.

Register	Data length	Area name	Description	Abbreviation
0000 to 0CFF	- (Reserved for system)			
0D00	Word	I/O control information category	Device control register 1	DRG1
0D01	Word		Device control register 2	DRG2
0D03	Word		Position number specification register	POSR
0D04 to 0FFF	- (Reserved for system)			
1000 to 3FFF		Position table information (low-speed memory area)	Offset (Hex.)	
	Double word		+0000H	Target position
	Double word		+0002H	In-position bandPositioning band
	Double word		+0004H	Speed command
	Double word		+0006H	Individual zone boundary +
	Double word		+0008H	Individual zone boundary -
	Word		+000AH	Acceleration command
	Word		+000BH	Deceleration command
	Word		+000CH	Push-current limiting value
	Word		+000DH	Load current threshold
	Word		+000EH	Control flag specification
	(Calculation of detailed device number) Device number (Hex) = 1000H + (16 × Position number (0 to 767)) ^{*1} + (Offset value corresponding to the device content) H Example) Position number: 5 Device content: Speed command (Offset value = 0004H) Device number (Hex) = 1000H + (16 × 5 = 80) ^{*1*2} + 0004H = 1000H + 50H ^{*2} + 0004H = 1054H ^{*1} Calculated in decimal. ^{*2} Converting 16 × 5 = 80 to hexadecimal results 50H.			
4000 to 8FFF	- (Reserved for system)			
9000	Double word	Controller monitor information category	Current position monitor	PNOW
9002	Word		Present alarm code query	ALMC
9003	Word		Input port query	DIPM
9004	Word		Output port monitor query	DOPM
9005	Word		Device status 1 query	DSS1
9006	Word		Device status 2 query	DSS2
9007	Word		Expanded device status query	DSSE
9008	Double word		System status query	STAT
900A	Double word		Current speed monitor	VNOW
900C	Double word		Current ampere monitor	CNOW
900E	Double word		Deviation monitor	DEVI
9010	Double word		System timer query	STIM
9012	Word		Special input port query	SIPM
9013	Word		Zone status query	ZONS
9014	Word		Completed position numberPosition complete number status query	POSS
9015 to 97FF	- (Reserved for system)			
9800	Word	Position command category	Position movement command register	POSR
9801 to 98FF	- (Reserved for system)			

Register	Data length	Area name	Description	Abbreviation
9900	Double word	Numerical value command category	Target position coordinate specification register	PCMD
9902	Double word		In-position bandPositioning band specification register	INP
9904	Double word		Speed specification register	VCMD
9906	Word		Acceleration/deceleration speed specification register	ACMD
9907	Word		Push-current limiting value	PPOW
9908	Word		Control flag specification register	CTLF
9909 to FFFF	- (Reserved for system)			

2.7 Precautions

■1. Program control device

- When Program Execution Command (0), Program Exit Command (2), or Program Restart Command (4) is written to the program control device (PRG 0), it will be a request for all programs running in the controllers.
- When unsupported write data is input to the program control device, the following error is displayed in the system alarm.
315: Device writing error.
Correct device.

■2. Variable devices

The variable number 99 of Integer device and variable number 199 of Real device are special devices used for operations by the X-SEL controller system. Do not use these variables for general purpose.

■3. Command trigger compatible device

- For the device whose obtained data No.0 is a command trigger, communication with the controller is performed when the Write(1)/Read(2) is set to the command trigger. When the command trigger and setting value are written in a batch, the communication is performed based on the value set with batch write.
- When Clear(4) is set to the command trigger, the communication with the controller is not performed and the set value is initialized.
- When an unsupported set value is input to the command trigger, the following error is displayed in the system alarm.
315: Device writing error.
Correct device.

■4. Device reserved for system use

Devices of "Reserved for system use" are devices with indefinite values. Do not write to these devices.

■5. Write to the flash ROM

- The point data can be written to the flash ROM of the X-SEL controller. When the point data is written to the flash ROM, it is not cleared even when power supply to the controller is turned off. However, there are limits in the number of writing. For details, refer to the user's manual of X-SEL controller used.
- Never turn off the main power supply during the flash ROM write. Doing so may cause the loss of data and malfunction of controllers. For details, refer to the user's manual of X-SEL controller used.

■6. Communication disconnection

- Writing to the flash ROM disconnects the communication with controllers until the writing is completed.
- Resetting software restarts the controllers. During this time, the communication with controllers is disconnected.

■7. Station number setting of the IAI robot controller system

The robot controller with the station number set with the host address must be included.

➡ 2.4.2 Communication detail settings

■8. Connection of the IAI X-SEL K type

Note the following precaution when using the controller with the mode switch set to MANU.

- After powering up the X-SEL, connecting the GOT before the PC software causes the program startup disabled (A1D alarm) on the X-SEL side.


















































3. CONNECTION TO AZBIL (former YAMATAKE) CONTROL EQUIPMENT

3.1	Connectable Model List	3 - 2
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3.3	Connection Diagram.....	3 - 33
3.4	GOT Side Settings	3 - 55
3.5	Control Equipment Side Setting	3 - 58
3.6	Device Range that Can Be Set.....	3 - 70
3.7	Precautions	3 - 73

3. CONNECTION TO AZBIL CONTROL EQUIPMENT

3.1 Connectable Model List

The following table shows the connectable models.

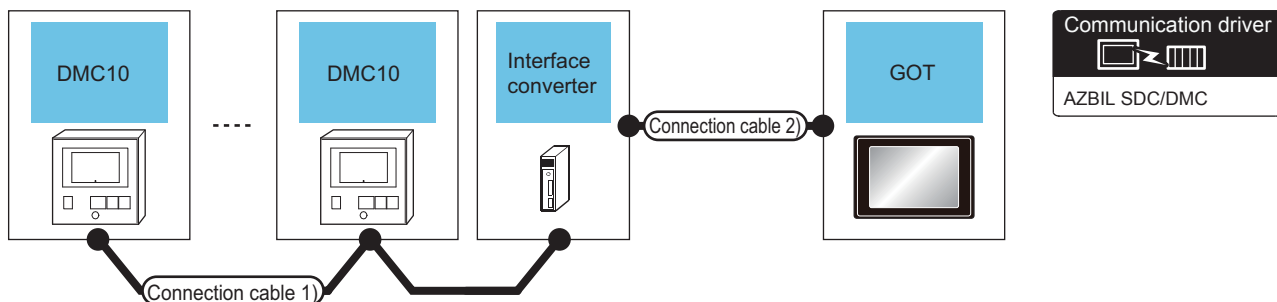
Series	Model name	Clock	Communication Type	Connectable model	Refer to
DMC	DMC10	×	RS-232 RS-485	   	➡ 3.2.1
			RS-232		➡ 3.2.1
	DMC50	×	RS-485	   	➡ 3.2.2
SDC	SDC15	×	RS-232 RS-485	   	➡ 3.2.3
	SDC25				
	SDC26				
	SDC35				
	SDC36	×	RS-232		➡ 3.2.1
	SDC20		RS-232 RS-485	   	➡ 3.2.4
	SDC21		RS-232		➡ 3.2.1
	SDC30	×	RS-232 RS-485	   	➡ 3.2.5
	SDC31		RS-232		➡ 3.2.1
	SDC40A	×	RS-232 RS-485	   	➡ 3.2.6
	SDC40B		RS-232		➡ 3.2.1
	SDC40G				
	SDC45	×	RS-232 RS-485	   	➡ 3.2.7
	SDC46		RS-232		➡ 3.2.1
CMS	CMS	×	RS-232 RS-485	   	➡ 3.2.8
			RS-232		➡ 3.2.1
CMF	CMF015	×	RS-232 RS-485	   	➡ 3.2.9
	CMF050		RS-232		➡ 3.2.1
CML	CML	×	RS-232 RS-485	   	➡ 3.2.10
			RS-232		➡ 3.2.1

Series	Model name	Clock	Communication Type	Connectable model	Refer to
MQV	MQV	×	RS-232 RS-485	<div>GT 27</div> <div>GT 25</div> <div>GT 23</div> <div>GT 21</div>	➡ 3.2.8
MPC	MPC				➡ 3.2.8
MVF	MVF				➡ 3.2.8
			RS-232	<div>GS</div>	➡ 3.2.1
PBZ	PBC201-VN2	×	RS-232 RS-485	<div>GT 27</div> <div>GT 25</div> <div>GT 23</div> <div>GT 21</div>	➡ 3.2.10
			RS-232	<div>GS</div>	➡ 3.2.1
AUR	AUR350C	×	RS-232 RS-485	<div>GT 27</div> <div>GT 25</div> <div>GT 23</div> <div>GT 21</div>	➡ 3.2.11
	AUR450C		RS-232	<div>GS</div>	➡ 3.2.1
RX	RX	×	RS-232 RS-485	<div>GT 27</div> <div>GT 25</div> <div>GT 23</div> <div>GT 21</div>	➡ 3.2.8
			RS-232	<div>GS</div>	➡ 3.2.1
CMC	CMC10B	×	RS-232 RS-485	<div>GT 27</div> <div>GT 25</div> <div>GT 23</div> <div>GT 21</div>	➡ 3.2.12
			RS-232	<div>GS</div>	➡ 3.2.1
AHC2001	AHC2001	×	RS-232 RS-485	<div>GT 27</div> <div>GT 25</div> <div>GT 23</div> <div>GT 21</div>	➡ 3.2.13
			RS-232	<div>GS</div>	➡ 3.2.1
NX	NX-D15	×	RS-232 RS-485 (MODBUS)	<div>GT 27</div> <div>GT 25</div> <div>GT 23</div>	➡ 3.2.14
	NX-D25				
	NX-D35				
	NX-DX1				
	NX-DX2				
	NX-DY				
	NX-S01				
	NX-S11				
	NX-S12				
	NX-S21				
	NX-D15	×	Ethernet (MODBUS)	<div>GT 27</div> <div>GT 25</div> <div>GT 23</div>	➡ 3.2.14
	NX-D25				
	NX-D35				
	NX-DX1				
	NX-DX2				
	NX-DY				
	NX-S01				
	NX-S11				
	NX-S12				
	NX-S21				

3.2 System Configuration

3.2.1 Connecting to DMC10

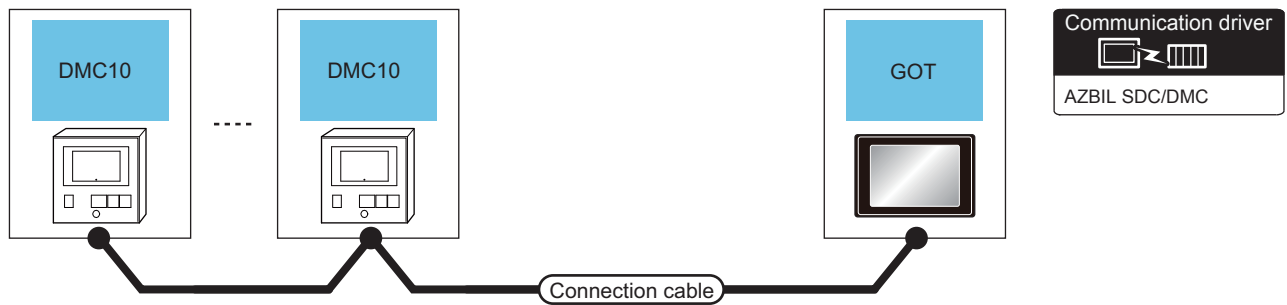
■ 1. When using the Interface converter



Temperature controller	Connection cable 1)		Interface converter*1		Connection cable 2)		GOT		Number of connectable equipment
Model name	Cable model Connection diagram number	Max. distance	Model name	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model	
DMC10	RS485 connection diagram 1)	500m	CMC10L	RS-232	RS232 connection diagram 1)	15m	- (Built into GOT)	 	Up to 15 temperature controllers for 1 GOT
							GT15-RS2-9P		
					RS232 connection diagram 3)	15m	- (Built into GOT)	 	

*1 Product manufactured by Azbil Corporation. For details on the product, contact Azbil Corporation.

2. When connecting directly



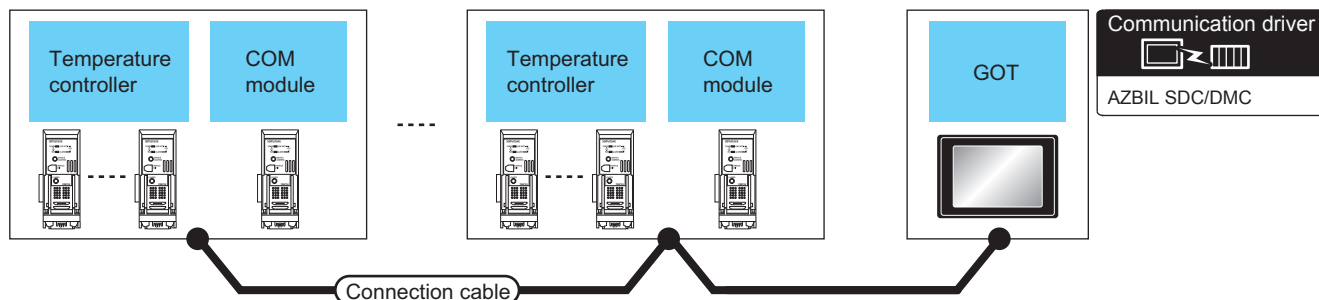
Temperature controller		Connection cable		GOT		Number of connectable equipment
Model name	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model	
DMC10	RS-485	RS485 connection diagram 12)	500m	- (Built into GOT)		Up to 15 temperature controllers for 1 GOT
		RS485 connection diagram 3)	500m ^{*1}	FA-LTBGT2R4CBL05 (0.5m) ^{*2} FA-LTBGT2R4CBL10 (1m) ^{*2} FA-LTBGT2R4CBL20 (2m) ^{*2}		
		RS485 connection diagram 5)	500m	GT15-RS4-TE		
		RS485 connection diagram 21)	500m	- (Built into GOT)		

*1 Including the cable length of the option devices.

*2 Product manufactured by MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED. For details of the product, contact MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED.

3.2.2 Connecting to DMC50

1. When using the COM module



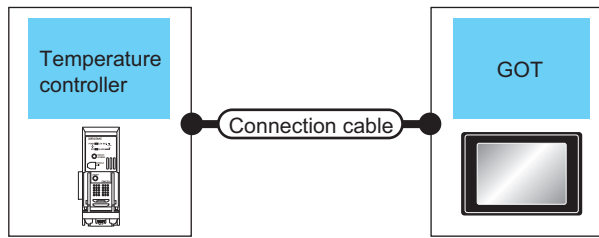
Temperature controller	Connection cable		COM module ^{*1}		GOT		Number of connectable equipment
Model name	Connection diagram number	Max. distance	Model name	Communication Type	Option device	Model	
DMC50CX	RS485 connection diagram 8)	500m ^{*2}	DMC50M20X	RS-485	FA-LTBGT2R4CBL05 (0.5m) ^{*3} FA-LTBGT2R4CBL10 (1m) ^{*3} FA-LTBGT2R4CBL20 (2m) ^{*2}		Up to 8 COM module for 1 GOT. Up to 120 temperature controllers for 1 COM module.
	RS485 connection diagram 9)	500m	DMC50M20X	RS-485	- (Built into GOT)		
					GT15-RS4-9S		
	RS485 connection diagram 22)	500m	DMC50M□20X	RS-485	- (Built into GOT)		

*1 Including the cable length of the option devices.

*2 Product manufactured by Azbil Corporation. For details on the product, contact Azbil Corporation.

*3 Product manufactured by MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED. For details of the product, contact MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED.

■2. When connecting directly to one temperature controller



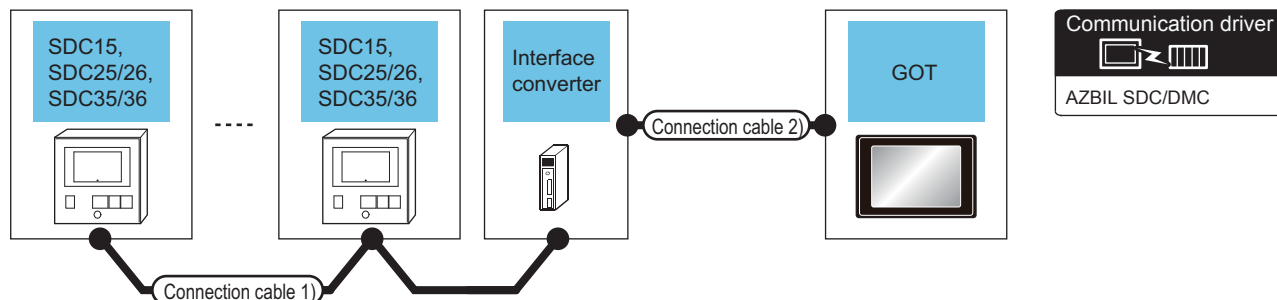
Temperature controller	Connection cable			GOT		Number of connectable equipment
Model name	Connection diagram number	Max. distance	Communication Type	Option device	Model	
DMC50CX	RS485 connection diagram 10)	500m*1	RS-485	FA-LTBGT2R4CBL05 (0.5m)*2 FA-LTBGT2R4CBL10 (1m)*2 FA-LTBGT2R4CBL20 (2m)*2	 	Up to 1 temperature controller for 1 GOT
	RS485 connection diagram 13)	500m	RS-485	- (Built into GOT)	 	
	RS485 connection diagram 11)	500m	RS-485	GT15-RS4-TE		
	RS485 connection diagram 23)	500m	RS-485	- (Built into GOT)	 	

*1 Including the cable length of the option devices.

*2 Product manufactured by MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED. For details of the product, contact MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED.

3.2.3 Connecting to SDC15, SDC25/26 or SDC35/36

■ 1. When using the Interface converter

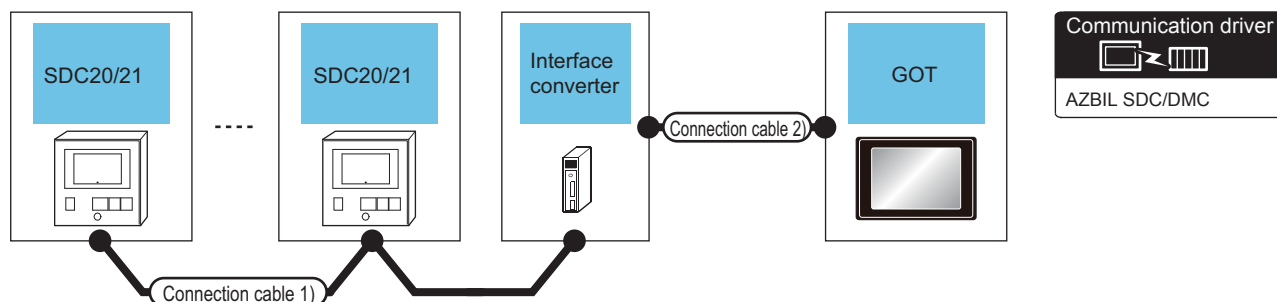


Temperature controller	Connection cable 1)		Interface converter*1		Connection cable 2)		GOT		Number of connectable equipment
Model name	Cable model Connection diagram number	Max. distance	Model name	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model	
SDC15 SDC25/26 SDC35/36	RS485 connection diagram 1)	500m	CMC10L	RS-232	RS232 connection diagram 1)	15m	- (Built into GOT)	<div>GT 27</div> <div>GT 23</div> <div>GS</div> <div>GT 25</div> <div>GT 21</div>	Up to 31 temperature controllers for 1 GOT
							GT15-RS2-9P	<div>GT 27</div> <div>GT 25</div>	
				RS-232	RS232 connection diagram 3)	15m	- (Built into GOT)	<div>GT 21</div> <div>GT 25</div> <div>GT 04P</div> <div>GT 03P</div> <div>GT 104P</div> <div>GT 104P</div>	

*1 Product manufactured by Azbil Corporation. For details on the product, contact Azbil Corporation.

3.2.4 Connecting to SDC20/21

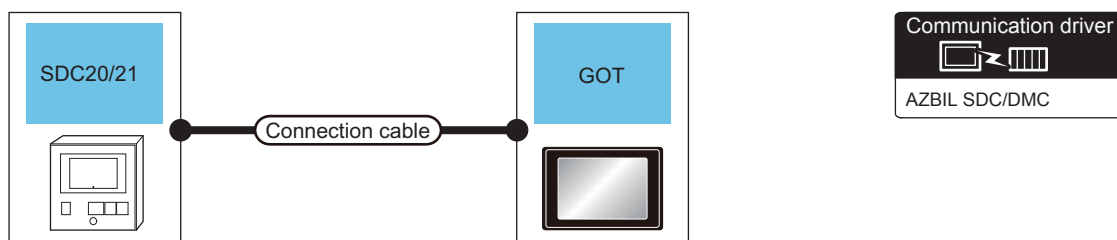
■ 1. When using the Interface converter



Temperature controller	Connection cable 1)		Interface converter*1		Connection cable 2)		GOT		Number of connectable equipment
Model name	Cable model Connection diagram number	Max. distance	Model name	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model	
SDC20/21	RS485 connection diagram 2)	500m	CMC10L	RS-232	RS232 connection diagram 1)	15m	- (Built into GOT)	 	Up to 31 temperature controllers for 1 GOT
					RS232 connection diagram 3)	15m	GT15-RS2-9P		
							- (Built into GOT)	 	

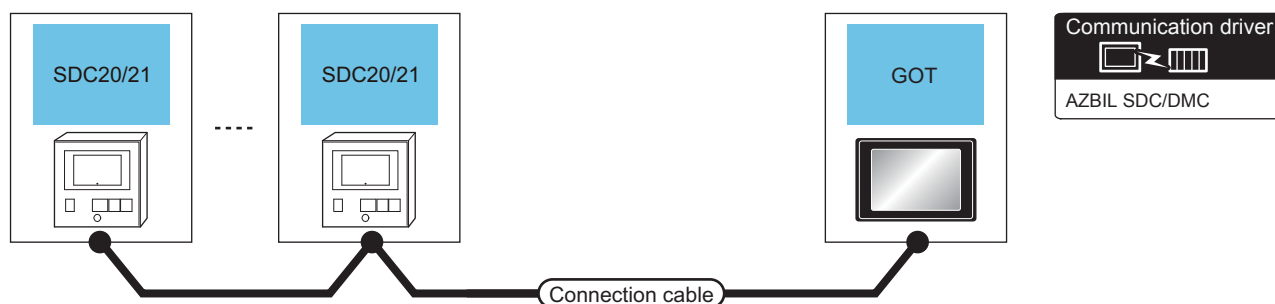
*1 Product manufactured by Azbil Corporation. For details on the product, contact Azbil Corporation.

■ 2. When connecting directly to one temperature controller



Temperature controller	Connection cable			GOT		Number of connectable equipment
Model name	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model	
SDC20/21	RS-232	RS232 connection diagram 2)	15m	- (Built into GOT)	 	Up to 1 temperature controller for 1 GOT
		RS232 connection diagram 4)	15m	GT15-RS2-9P		
				- (Built into GOT)	 	

3. When connecting directly to multiple temperature controllers



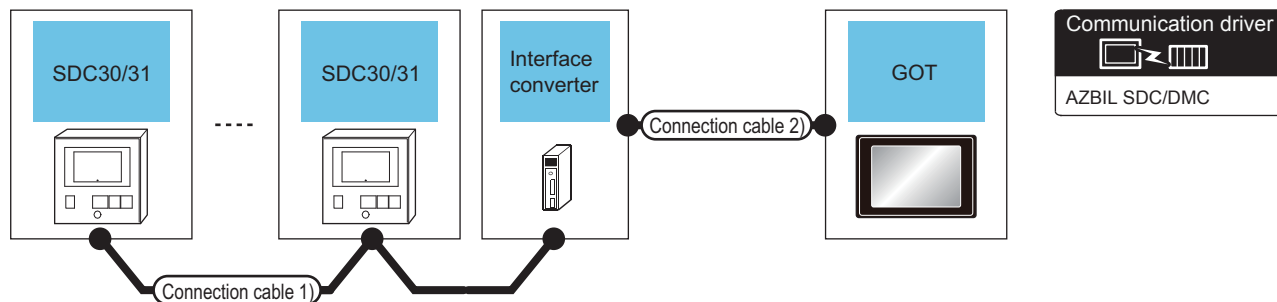
Temperature controller		Connection cable		GOT		Number of connectable equipment	
Model name	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model		
SDC20/21	RS-485	RS485 connection diagram 4)(4-wire)	500m ^{*1}	FA-LTBGT2R4CBL05 (0.5m) ^{*2} FA-LTBGT2R4CBL10 (1m) ^{*2} FA-LTBGT2R4CBL20 (2m) ^{*2}	 	Up to 31 temperature controllers for 1 GOT	
		RS485 connection diagram 14)(2-wire)					
		RS485 connection diagram 6)(4-wire)	500m	- (Built into GOT)	 		
				GT15-RS4-9S			
		RS485 connection diagram 15)(2-wire)	500m	- (Built into GOT)	 		
		RS485 connection diagram 7)(4-wire)	500m	GT15-RS4-TE			
		RS485 connection diagram 16)(2-wire)					
		RS485 connection diagram 24)(4-wire)	500m	- (Built into GOT)	 		
		RS485 connection diagram 25)(2-wire)					

*1 Including the cable length of the option devices.

*2 Product manufactured by MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED. For details of the product, contact MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED.

3.2.5 Connecting to SDC30/31

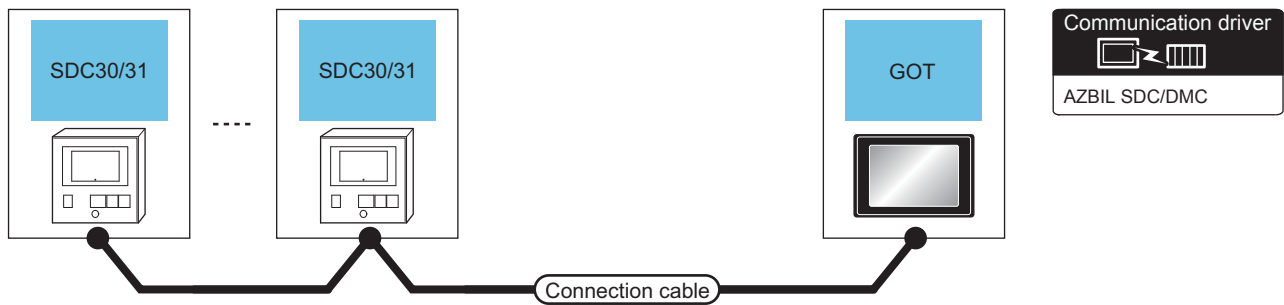
■ 1. When using the Interface converter



Temperature controller	Connection cable 1)		Interface converter ^{*1}		Connection cable 2)		GOT		Number of connectable equipment
Model name	Cable model Connection diagram number	Max. distance	Model name	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model	
SDC30/31	RS485 connection diagram 2)	500m	CMC10L	RS-232	RS232 connection diagram 1)	15m	- (Built into GOT)		Up to 31 temperature controllers for 1 GOT
							GT15-RS2-9P		
					RS232 connection diagram 3)	15m	- (Built into GOT)		

^{*1} Product manufactured by Azbil Corporation. For details on the product, contact Azbil Corporation.

2. When connecting directly



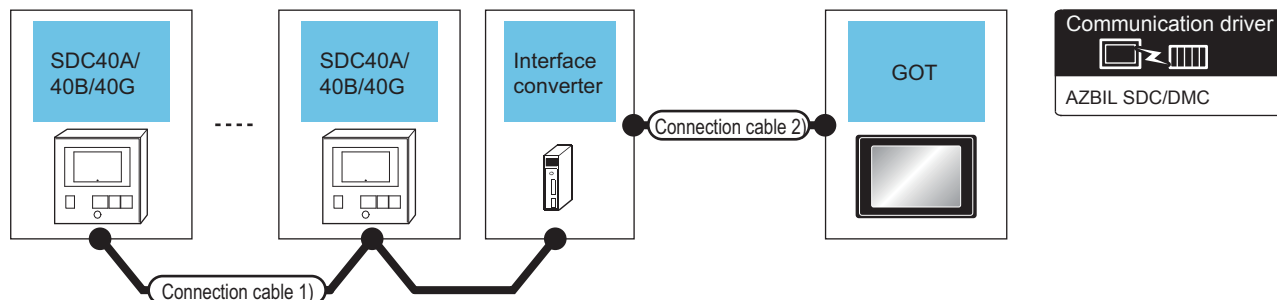
Temperature controller		Connection cable		GOT		Number of connectable equipment	
Model name	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model		
SDC30/31	RS-485	RS485 connection diagram 4)(4-wire)	500m ^{*1}	FA-LTBGT2R4CBL05 (0.5m) ^{*2} FA-LTBGT2R4CBL10 (1m) ^{*2} FA-LTBGT2R4CBL20 (2m) ^{*2}		Up to 31 temperature controllers for 1 GOT	
		RS485 connection diagram 14)(2-wire)					
		RS485 connection diagram 6)(4-wire)	500m	- (Built into GOT)			
				GT15-RS4-9S			
		RS485 connection diagram 7)(4-wire)	500m	GT15-RS4-TE			
		RS485 connection diagram 16)(2-wire)					
		RS485 connection diagram 24)(4-wire)	500m	- (Built into GOT)			

*1 Including the cable length of the option devices.

*2 Product manufactured by MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED. For details of the product, contact MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED.

3.2.6 Connecting to SDC40A/40B/40G

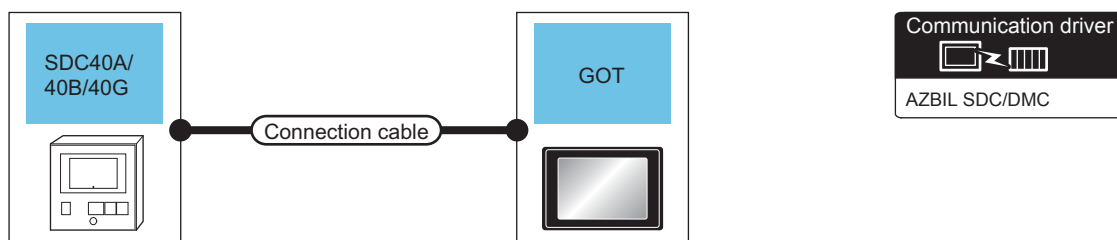
■ 1. When using the Interface converter



Temperature controller	Connection cable 1)		Interface converter*1		Connection cable 2)		GOT		Number of connectable equipment
Model name	Cable model Connection diagram number	Max. distance	Model name	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model	
SDC40A/40B/40G	RS485 connection diagram 2)	500m	CMC10L	RS-232	RS232 connection diagram 1)	15m	- (Built into GOT)		Up to 31 temperature controllers for 1 GOT
							GT15-RS2-9P		
					RS232 connection diagram 3)	15m	- (Built into GOT)		

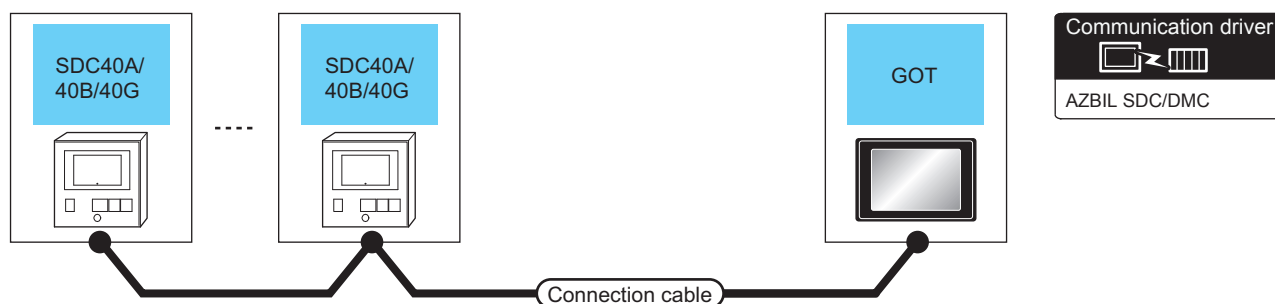
*1 Product manufactured by Azbil Corporation. For details on the product, contact Azbil Corporation.

■ 2. When connecting directly to one temperature controller



Temperature controller	Connection cable			GOT		Number of connectable equipment
Model name	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model	
SDC40A/40B/40G	RS-232	RS232 connection diagram 2)	15m	- (Built into GOT)		Up to 1 temperature controller for 1 GOT
				GT15-RS2-9P		
		RS232 connection diagram 4)	15m	- (Built into GOT)		

3. When connecting directly to multiple temperature controllers



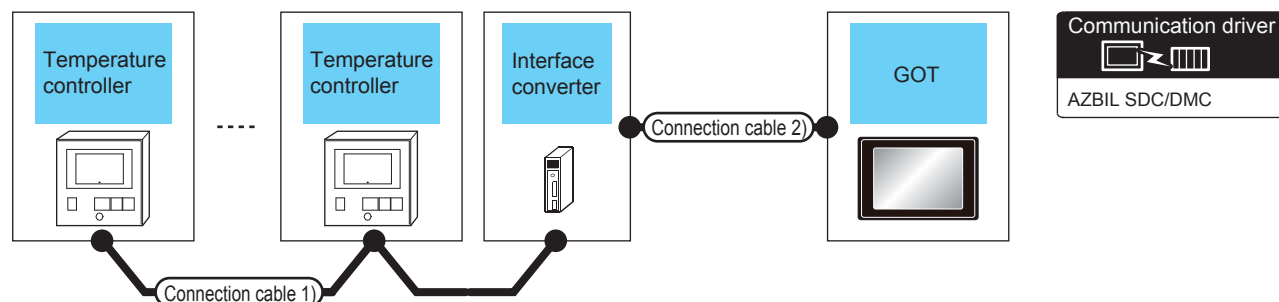
Temperature controller		Connection cable		GOT		Number of connectable equipment	
Model name	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model		
SDC40A/ 40B/40G	RS-485	RS485 connection diagram 4)(4-wire)	500m ^{*1}	FA-LTBGT2R4CBL05 (0.5m) ^{*2} FA-LTBGT2R4CBL10 (1m) ^{*2} FA-LTBGT2R4CBL20 (2m) ^{*2}		Up to 31 temperature controllers for 1 GOT	
		RS485 connection diagram 14)(2-wire)					
		RS485 connection diagram 6)(4-wire)	500m	- (Built into GOT)			
				GT15-RS4-9S			
		RS485 connection diagram 15)(2-wire)	500m	- (Built into GOT)			
		RS485 connection diagram 7)(4-wire)	500m	GT15-RS4-TE			
		RS485 connection diagram 16)(2-wire)					
		RS485 connection diagram 24)(4-wire)	500m	- (Built into GOT)			
		RS485 connection diagram 25)(2-wire)					

*1 Including the cable length of the option devices.

*2 Product manufactured by MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED. For details of the product, contact MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED.

3.2.7 Connecting to SDC45/46

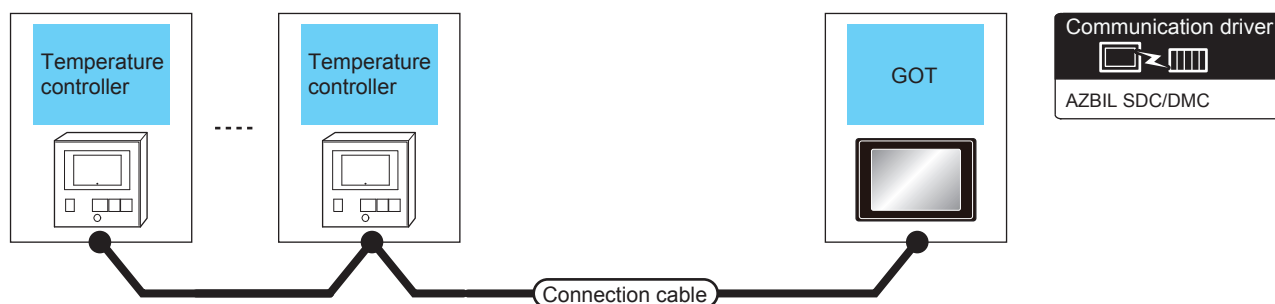
■ 1. When using the Interface converter




















Temperature controller	Connection cable 1)		Interface converter*1		Connection cable 2)		GOT		Number of connectable equipment
Model name	Cable model Connection diagram number	Max. distance	Model name	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model	
SDC45/46	(User preparing) RS485 connection diagram 17)	500m	CMC10L	RS-232	(User preparing) RS232 connection diagram 1)	15m	- (Built into GOT)	<div>GT 27</div> <div>GT 23</div> <div>GS</div> <div>GT 25</div> <div>GT 21</div>	Up to 31 temperature controllers for 1 GOT
							GT15-RS2-9P	<div>GT 27</div> <div>GT 25</div>	
					(User preparing) RS232 connection diagram 3)	15m	- (Built into GOT)	<div>GT 21</div> <div>GT 25</div> <div>GT 03P</div> <div>GT 04P</div>	

*1 Product manufactured by Azbil Corporation. For details on the product, contact Azbil Corporation.

2. When connecting directly to multiple temperature controllers



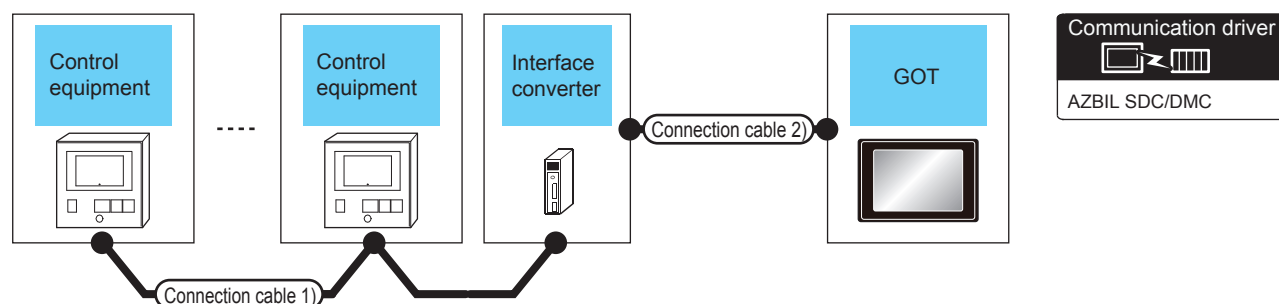
Temperature controller		Connection cable		GOT		Number of connectable equipment
Model name	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model	
SDC45/46	RS-485	 RS485 connection diagram 18)	500m ^{*1}	FA-LTBGT2R4CBL05 (0.5m) ^{*2} FA-LTBGT2R4CBL10 (1m) ^{*2} FA-LTBGT2R4CBL20 (2m) ^{*2}	  	Up to 31 temperature controller for 1 GOT
		 RS485 connection diagram 19)	500m	GT15-RS4-TE	 	
		 RS485 connection diagram 20)	500m	- (Built into GOT)	   	
		 RS485 connection diagram 26)	500m	- (Built into GOT)	   	

*1 Including the cable length of the option devices.

*2 Product manufactured by MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED. For details of the product, contact MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED.

3.2.8 Connecting to CMS, MQV, MPC, MVF, RX

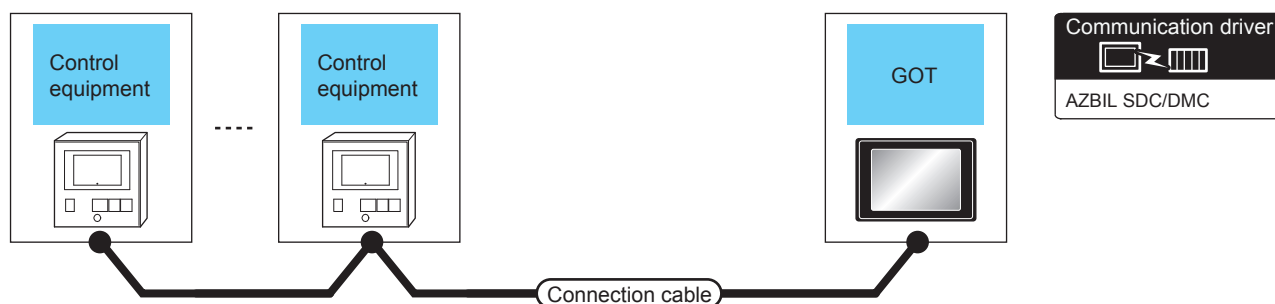
■ 1. When using the Interface converter



Control equipment	Connection cable 1)		Interface converter*1		Connection cable 2)		GOT		Number of connectable equipment
	Cable model Connection diagram number	Max. distance	Model name	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model	
CMS MQV MPC MVF RX	(User preparing) RS485 connection diagram 17)	500m	CMC10L	RS-232	(User preparing) RS232 connection diagram 1)	15m	- (Built into GOT)	<div>GT 27</div> <div>GT 23</div> <div>GS</div> <div>GT 25</div> <div>GT 050</div> <div>GT 21</div>	Up to 31 control equipment for 1 GOT
					(User preparing) RS232 connection diagram 3)	15m	GT15-RS2-9P	<div>GT 27</div> <div>GT 25</div>	
					(User preparing) RS232 connection diagram 3)	15m	- (Built into GOT)	<div>GT 21</div> <div>GT 04R</div> <div>GT 03P</div> <div>GT 04P</div> <div>GT 02</div>	

*1 Product manufactured by Azbil Corporation. For details on the product, contact Azbil Corporation.

2. When connecting directly to multiple control equipments



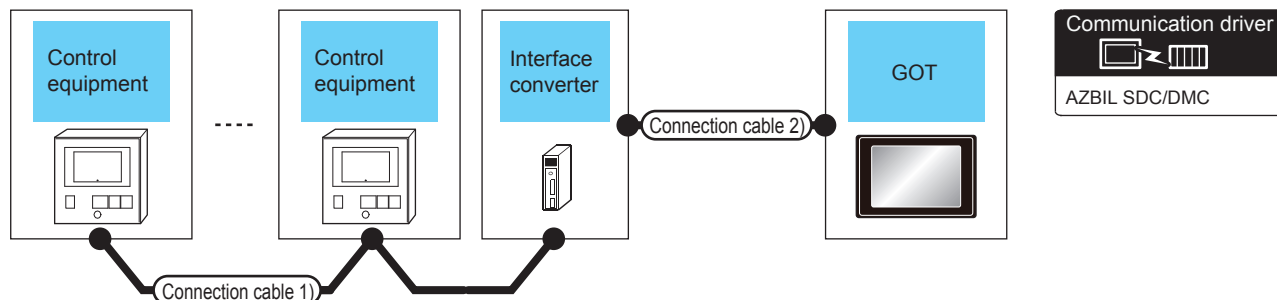
Control equipment		Connection cable		GOT		Number of connectable equipment
Model name	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model	
CMS MQV MPC MVF RX	RS-485	RS485 connection diagram 18)	500m*1	FA-LTBGT2R4CBL05 (0.5m)*2 FA-LTBGT2R4CBL10 (1m)*2 FA-LTBGT2R4CBL20 (2m)*2	 	Up to 1 control equipment for 1 GOT
		RS485 connection diagram 19)	500m	GT15-RS4-TE		
		RS485 connection diagram 20)	500m	- (Built into GOT)	 	
		RS485 connection diagram 26)	500m	- (Built into GOT)	 	

*1 Including the cable length of the option devices.

*2 Product manufactured by MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED. For details of the product, contact MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED.

3.2.9 Connecting to CMF015, CMF050

■ 1. When using the Interface converter

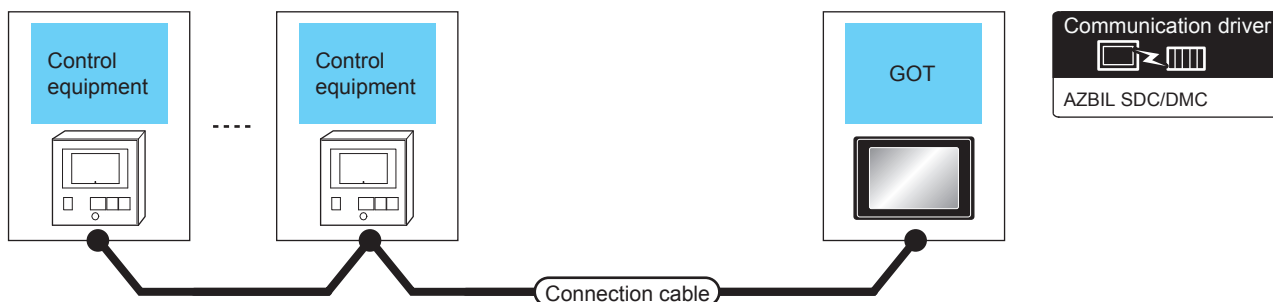


Control equipment	Connection cable 1)		Interface converter*1		Connection cable 2)		GOT		Number of connectable equipment
Model name	Cable model Connection diagram number	Max. distance	Model name	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model	
CMF015	RS485 connection diagram 17)	500m	CMC10L	RS-232	RS232 connection diagram 1)	15m	- (Built into GOT)		Up to 31 control equipment for 1 GOT
							GT15-RS2-9P		
					RS232 connection diagram 3)	15m	- (Built into GOT)		
CMF050	RS485 connection diagram 2)	500m	CMC10L	RS-232	RS232 connection diagram 1)	15m	- (Built into GOT)		Up to 31 control equipment for 1 GOT
							GT15-RS2-9P		
					RS232 connection diagram 3)	15m	- (Built into GOT)		

*1 Product manufactured by Azbil Corporation. For details on the product, contact Azbil Corporation.

2. When connecting directly

(1) Connecting to CMF015

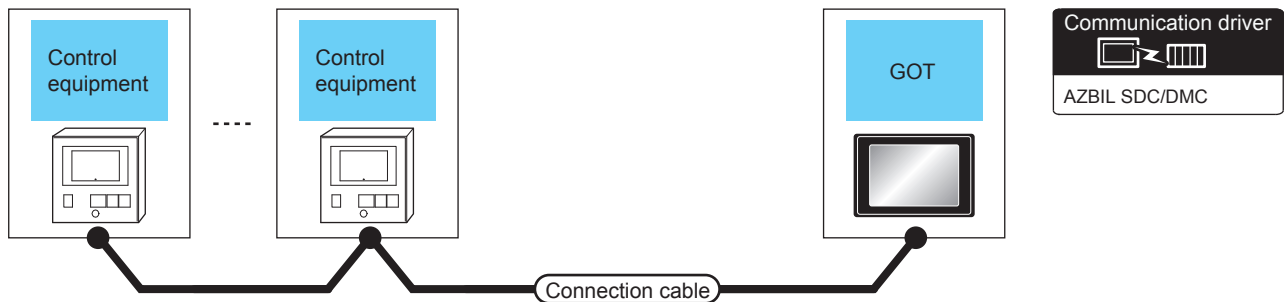


Control equipment		Connection cable		GOT		Number of connectable equipment
Model name	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model	
CMF015	RS-485	RS485 connection diagram 18)	500m ^{*1}	FA-LTBGT2R4CBL05 (0.5m) ^{*2} FA-LTBGT2R4CBL10 (1m) ^{*2} FA-LTBGT2R4CBL20 (2m) ^{*2}		Up to 1 control equipment for 1 GOT
		RS485 connection diagram 19)	500m	GT15-RS4-TE		
		RS485 connection diagram 20)	500m	- (Built into GOT)		
		RS485 connection diagram 26)	500m	- (Built into GOT)		

*1 Including the cable length of the option devices.

*2 Product manufactured by MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED. For details of the product, contact MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED.

(2) Connecting to CMF050



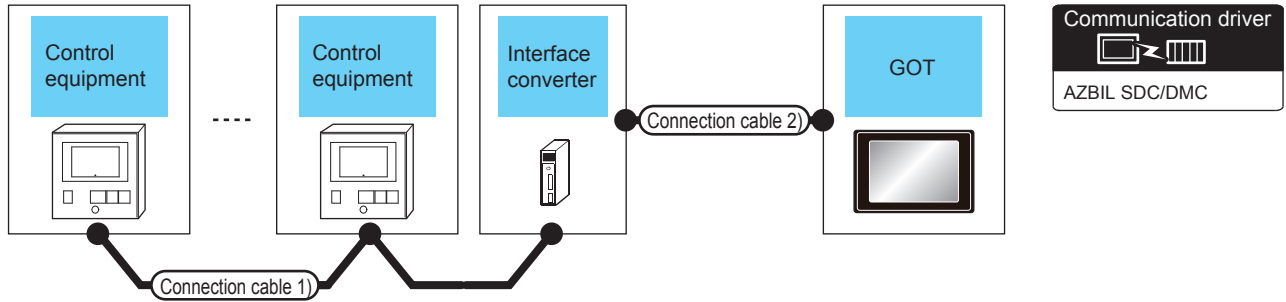
Control equipment		Connection cable		GOT		Number of connectable equipment	
Model name	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model		
CMF050	RS-485	RS485 connection diagram 4)(4-wire)	500m ^{*1}	FA-LTBGT2R4CBL05 (0.5m) ^{*2} FA-LTBGT2R4CBL10 (1m) ^{*2} FA-LTBGT2R4CBL20 (2m) ^{*2}	 	Up to 1 control equipment for 1 GOT	
		RS485 connection diagram 14)(2-wire)					
		RS485 connection diagram 6)(4-wire)	500m	- (Built into GOT)	 		
				GT15-RS4-9S			
		RS485 connection diagram 15)(2-wire)	500m	- (Built into GOT)	 		
		RS485 connection diagram 7)(4-wire)	500m	GT15-RS4-TE			
		RS485 connection diagram 16)(2-wire)					
		RS485 connection diagram 24)(4-wire)	500m	- (Built into GOT)	 		
		RS485 connection diagram 25)(2-wire)					

*1 Including the cable length of the option devices.

*2 Product manufactured by MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED. For details of the product, contact MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED.

3.2.10 Connecting to CML, PBC201-VN2

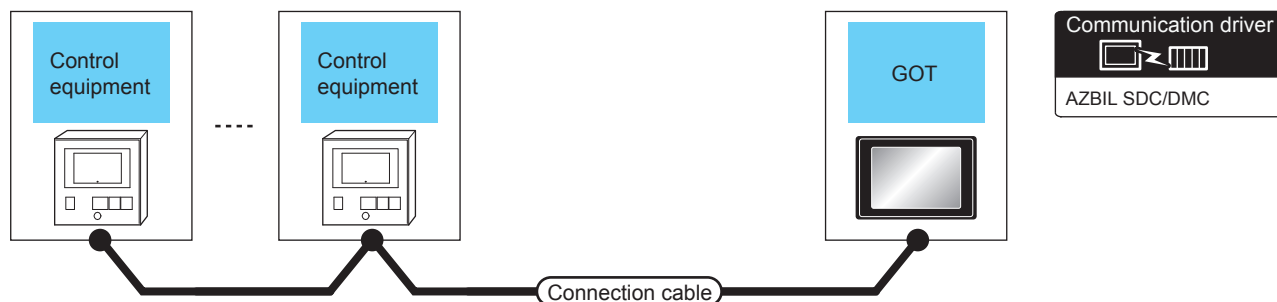
■1. When using the Interface converter



|--|

*1 Product manufactured by Azbil Corporation. For details on the product, contact Azbil Corporation.

2. When connecting directly



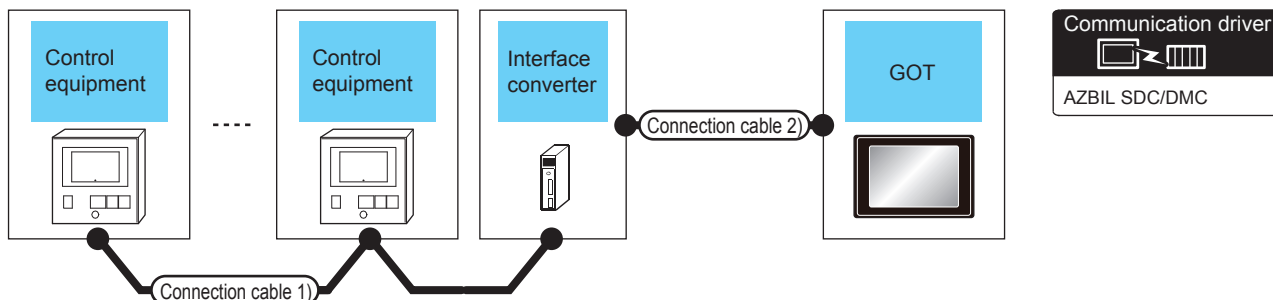
Control equipment		Connection cable		GOT		Number of connectable equipment	
Model name	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model		
CML PBC201-VN2	RS-485	RS485 connection diagram 4)(4-wire)	500m ^{*1}	FA-LTBGT2R4CBL05 (0.5m) ^{*2} FA-LTBGT2R4CBL10 (1m) ^{*2} FA-LTBGT2R4CBL20 (2m) ^{*2}		Up to 1 control equipment for 1 GOT	
		RS485 connection diagram 14)(2-wire)					
		RS485 connection diagram 6)(4-wire)	500m	- (Built into GOT)			
				GT15-RS4-9S			
		RS485 connection diagram 15)(2-wire)	500m	- (Built into GOT)			
		RS485 connection diagram 7)(4-wire)	500m	GT15-RS4-TE			
		RS485 connection diagram 16)(2-wire)					
		RS485 connection diagram 24)(4-wire)	500m	- (Built into GOT)			
		RS485 connection diagram 25)(2-wire)					

*1 Including the cable length of the option devices.

*2 Product manufactured by MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED. For details of the product, contact MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED.

3.2.11 Connecting to AUR350C, AUR450C

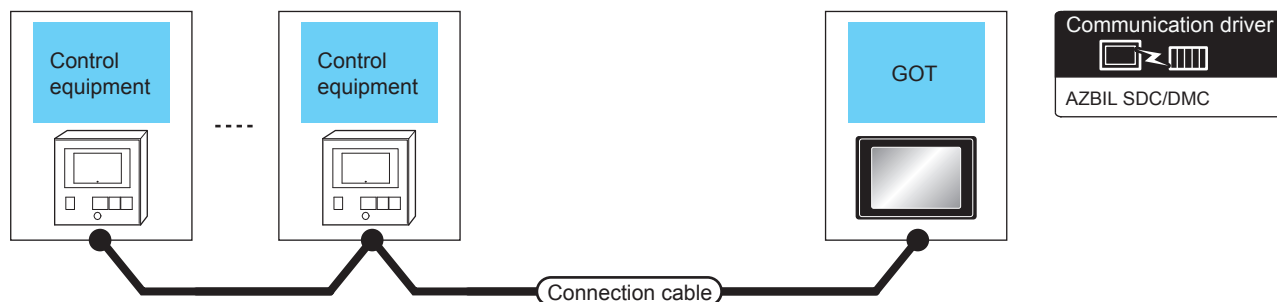
■ 1. When using the Interface converter



Control equipment	Connection cable 1)		Interface converter ^{*1}		Connection cable 2)		GOT		Number of connectable equipment
	Model name	Cable model Connection diagram number	Max. distance	Model name	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model
AUR350C AUR450C	RS485 connection diagram 1)	500m	CMC10L	RS-232	RS232 connection diagram 1)	15m	- (Built into GOT)	 	Up to 31 control equipment for 1 GOT
							GT15-RS2-9P		
					RS232 connection diagram 3)	15m	- (Built into GOT)		

^{*1} Product manufactured by Azbil Corporation. For details on the product, contact Azbil Corporation.

■ 2. When connecting directly



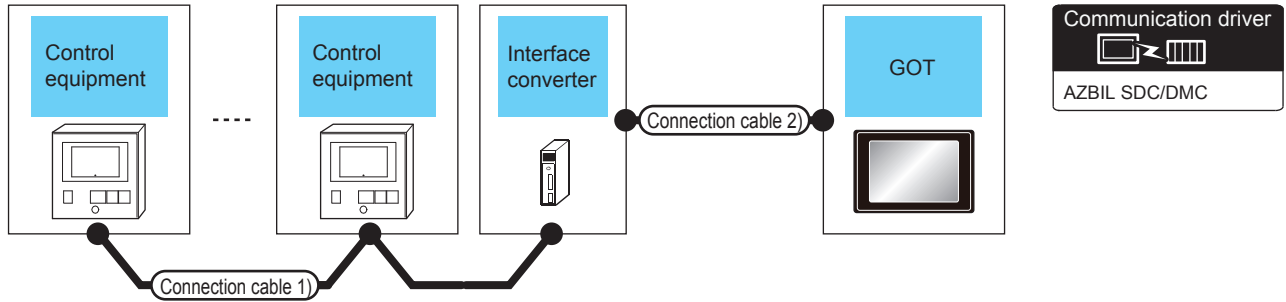
Control equipment		Connection cable		GOT		Number of connectable equipment
Model name	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model	
AUR350C AUR450C	RS-485	RS485 connection diagram 3)	500m ^{*1}	FA-LTBGT2R4CBL05 (0.5m) ^{*2} FA-LTBGT2R4CBL10 (1m) ^{*2} FA-LTBGT2R4CBL20 (2m) ^{*2}	 	Up to 1 control equipment for 1 GOT
		RS485 connection diagram 5)	500m	GT15-RS4-TE		
		RS485 connection diagram 12)	500m	- (Built into GOT)	 	
		RS485 connection diagram 21)	500m	- (Built into GOT)	 	

*1 Including the cable length of the option devices.

*2 Product manufactured by MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED. For details of the product, contact MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED.

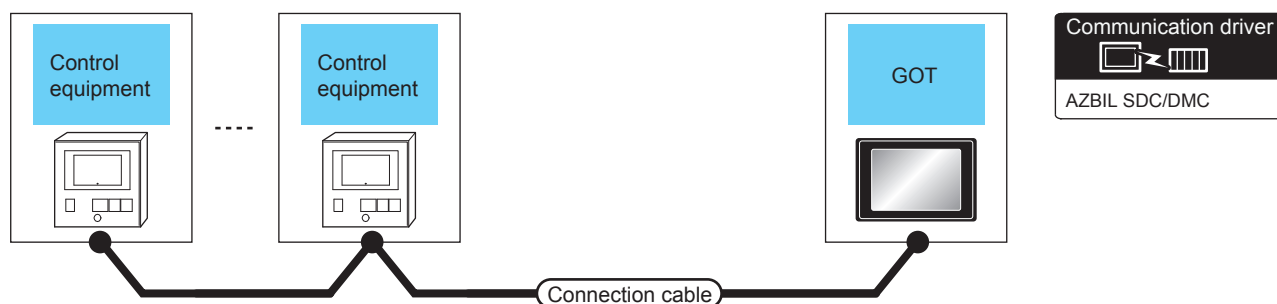
3.2.12 Connecting to CMC10B

■1. When using the Interface converter



*1 Product manufactured by Azbil Corporation. For details on the product, contact Azbil Corporation.

■ 2. When connecting directly to multiple control equipments



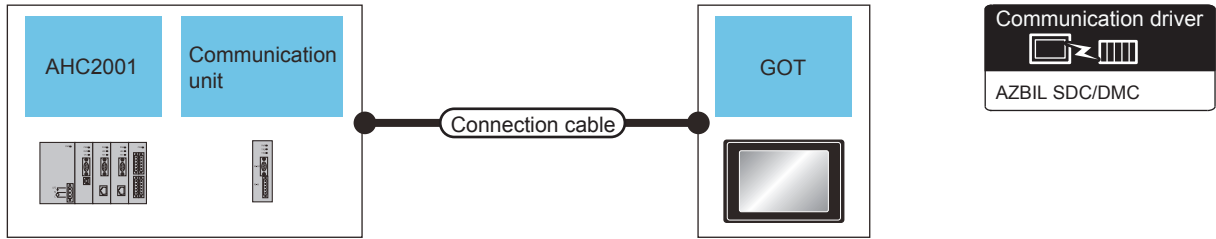
Control equipment		Connection cable		GOT		Number of connectable equipment
Model name	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model	
CMC10B	RS-485	RS485 connection diagram 4)	500m ^{*1}	FA-LTBGT2R4CBL05 (0.5m) ^{*2} FA-LTBGT2R4CBL10 (1m) ^{*2} FA-LTBGT2R4CBL20 (2m) ^{*2}	 	Up to 1 control equipment for 1 GOT
		RS485 connection diagram 6)	500m	- (Built into GOT)	 	
		RS485 connection diagram 7)	500m	GT15-RS4-9S		
		RS485 connection diagram 24)	500m	- (Built into GOT)		














*1 Including the cable length of the option devices.






























*2 Product manufactured by MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED. For details of the product, contact MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED.

3.2.13 Connecting to AHC2001

■ 1. When connecting to one temperature controller



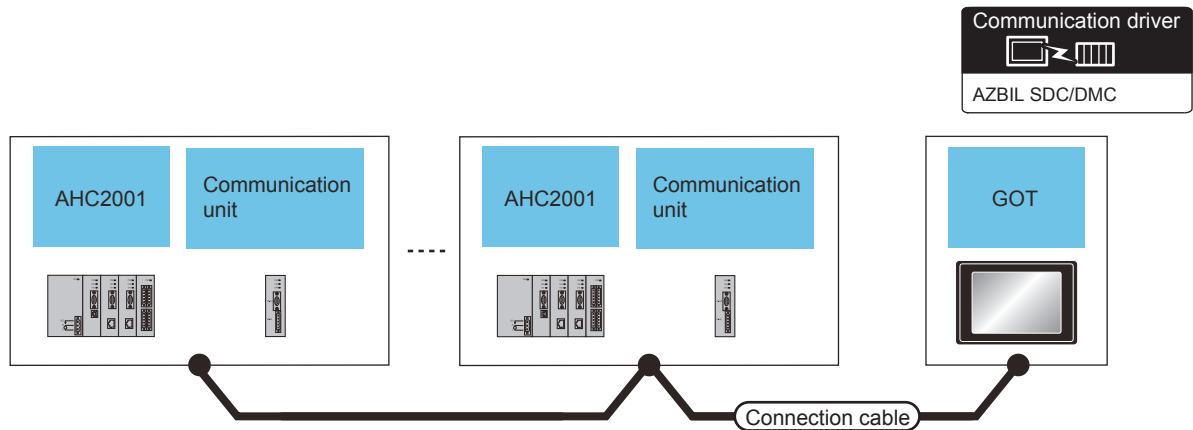
Control equipment			Connection cable		GOT		Number of connectable equipment	
Model name	Communication unit	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model		
AHC2001	-	RS-232	 RS232 connection diagram 2)	15m	- (Built into GOT)	    	Up to 1 temperature controllers for 1 GOT	
	SCU				GT15-RS2-9P	 		
			 RS232 connection diagram 4)	15m	- (Built into GOT)	   		

Control equipment			Connection cable		GOT		Number of connectable equipment	
Model name	Communication unit	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model		
AHC2001	SCU	RS-485	 RS485 connection diagram 4)	500m ^{*1}	FA-LTBGT2R4CBL05 (0.5m) ^{*2} FA-LTBGT2R4CBL10 (1m) ^{*2} FA-LTBGT2R4CBL20 (2m) ^{*2}	  	Up to 1 temperature controllers for 1 GOT	
			 RS485 connection diagram 14)					
			 RS485 connection diagram 6)	500m	- (Built into GOT)	   		
					GT15-RS4-9S	 		
			 RS485 connection diagram 15)	500m	- (Built into GOT)	   		
			 RS485 connection diagram 7)	500m	GT15-RS4-TE	 		
			 RS485 connection diagram 16)					
			 RS485 connection diagram 24)(4-wire)	500m	- (Built into GOT)	     		
			 RS485 connection diagram 25)(2-wire)					

*1 Including the cable length of the option devices.

*2 Product manufactured by MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED. For details of the product, contact MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED.

2. When connecting to multiple temperature controllers

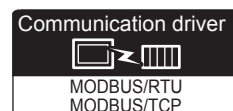


Control equipment			Connection cable		GOT		Number of connectable equipment	
Model name	Communication unit	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model		
AHC2001	SCU	RS-485	RS485 connection diagram 4)	500m ^{*1}	FA-LTBGT2R4CBL05 (0.5m) ^{*2} FA-LTBGT2R4CBL10 (1m) ^{*2} FA-LTBGT2R4CBL20 (2m) ^{*2}		Up to 31 temperature controllers for 1 GOT	
			RS485 connection diagram 14)					
			RS485 connection diagram 6)	500m	- (Built into GOT)			
					GT15-RS4-9S			
			RS485 connection diagram 15)	500m	- (Built into GOT)			
			RS485 connection diagram 7)	500m	GT15-RS4-TE			
			RS485 connection diagram 16)					
			RS485 connection diagram 24)(4-wire)	500m	- (Built into GOT)			
			RS485 connection diagram 25)(2-wire)					

*1 Including the cable length of the option devices.

*2 Product manufactured by MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED. For details of the product, contact MITSUBISHI ELECTRIC ENGINEERING COMPANY LIMITED.

3.2.14 Connecting to NX series



Use a MODBUS(R)/RTU or MODBUS(R)/TCP communication driver to connect the GOT to NX series.
For the MODBUS(R)/RTU or MODBUS(R)/TCP connection, refer to the following manual.

- ➡ GOT2000 Series Connection Manual (Microcomputer/MODBUS/Peripheral Connection)
 - 4. MODBUS(R)/RTU CONNECTION
 - 5. MODBUS(R)/TCP CONNECTION

For the valid devices, refer to the following Technical News.

- ➡ List of Valid Devices Applicable for GOT2000 Series with MODBUS Connection (GOT-A-0070)

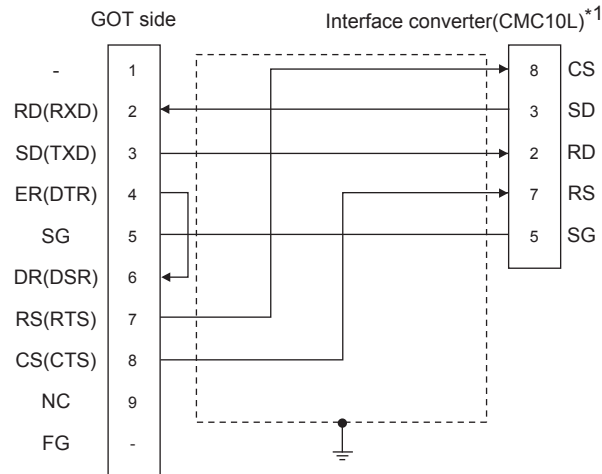
3.3 Connection Diagram

The following diagram shows the connection between the GOT and the control equipment.

3.3.1 RS-232 cable

1. Connection diagram

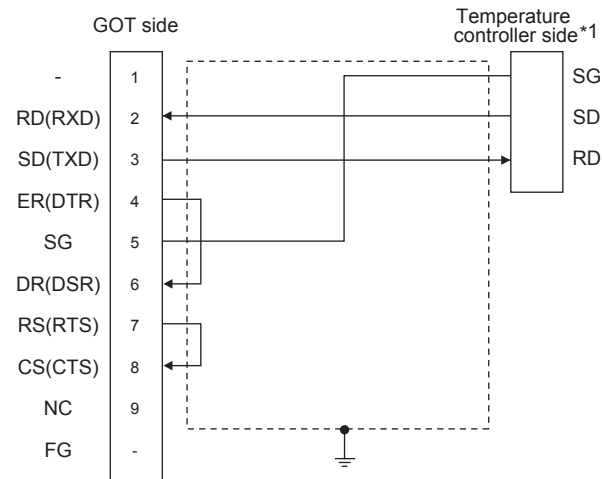
(1) RS232 connection diagram 1)



*1 For details on the setting method of the TERMINAL mode, refer to the following.

➡ 3.5.5 Connecting to CMC10L

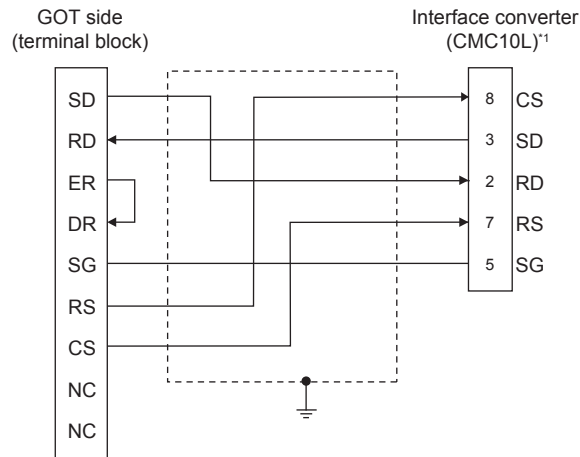
(2) RS232 connection diagram 2)



*1 Pin No. of temperature controller differs depending on model and optional function model. Refer to the following table. The numbers in () of the following table correspond to optional function models.

Signal name	Model of temperature controller					
	SDC20		SDC21	SDC40A, SDC40B, SDC40G	AHC2001	
	(03, 05)	(10)	(04, 07, 09)		CPU	SCU
	Pin No.	Pin No.	Pin No.	Pin No.	Pin No.	Pin No.
SG	5	18	29	61	5	5
SD	17	16	27	60	3	3
RD	18	17	28	59	2	2

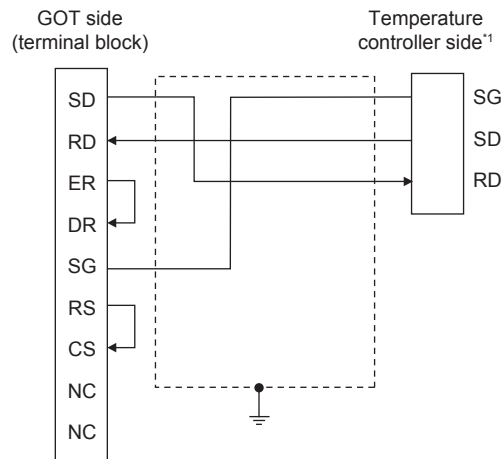
(3) RS232 connection diagram 3)



*1 For details on the setting method of the TERMINAL mode, refer to the following.

➡ 3.5.5 Connecting to CMC10L

(4) RS232 connection diagram 4)



*1 Pin No. of temperature controller differs depending on model and optional function model.

Refer to the following table. The numbers in () of the following table correspond to optional function models.

Signal name	Model of temperature controller					
	SDC20		SDC21	SDC40A, SDC40B, SDC40G	AHC2001	
	(03, 05)	(10)	(04, 07, 09)		CPU	SCU
	Pin No.	Pin No.	Pin No.	Pin No.	Pin No.	Pin No.
SG	5	18	29	61	5	5
SD	17	16	27	60	3	3
RD	18	17	28	59	2	2

■ 2. Precautions when preparing a cable

(1) Cable length

The length of the RS-232 cable must be 15m or less.

(2) GOT side connector

For the GOT side connector, refer to the following.

➡ 1.4.1 GOT connector specifications

(3) AZBIL control equipment side connector

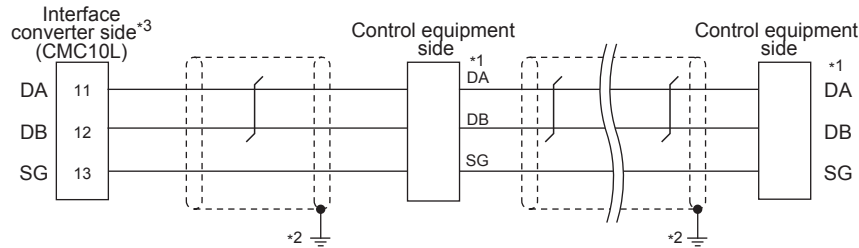
Use the connector compatible with the AZBIL control equipment side module.

For details, refer to the user's manual of the AZBIL control equipment

3.3.2 RS-485 cable

1. Connection diagram

(1) RS485 connection diagram 1)



*1 Pin No. of control equipment differs depending on the model. Refer to the following table.

Signal name	Model of control equipment			
	DMC10	SDC15	SDC25/26 SDC35/36	AUR350C AUR450C
	Pin No.	Pin No.	Pin No.	Pin No.
DA	4	16	22	DA
DB	5	17	23	DB
SG	6	18	24	SG

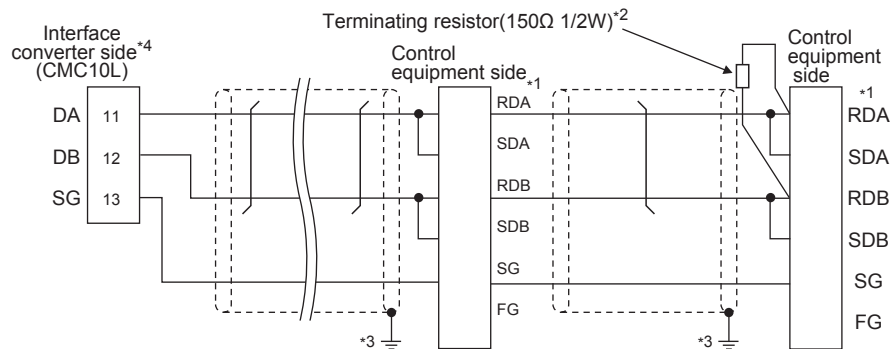
*2 Connect FG grounding to the single-sided end of a cable shield line.

*3 Set the terminal resistor to "Disable".

For details of terminating resistor settings, refer to the following.

➡ 3.5.5 Connecting to CMC10L

(2) RS485 connection diagram 2)



*1 Pin No. of control equipment differs depending on model and optional function model. Refer to the following table. The numbers in () of the following table correspond to optional function models.

Signal name	Model of control equipment									
	SDC20		SDC21	SDC30	SDC31		SDC40A/ 40B/40G	CMF050C ML	PBC201- VN2	CMC10B
	(02, 04)	(09)	(03, 06, 08)	(040, 041)	(045)	(446, 546)				
	Pin No.	Pin No.	Pin No.	Pin No.	Pin No.	Pin No.	Pin No.	Pin No.	Pin No.	Pin No.
RDA	17	18	27	18	18	27	59	9	12	11
RDB	18	19	28	19	19	28	60	10	13	12
SDA	15	16	25	16	16	25	57	7	14	13
SDB	16	17	26	17	17	26	58	8	15	14
SG	5	5	29	5	5	29	61	12	16	15
FG	3, 4	3, 4	3, 4	3, 4	3, 4	3, 4	3	19	3	-

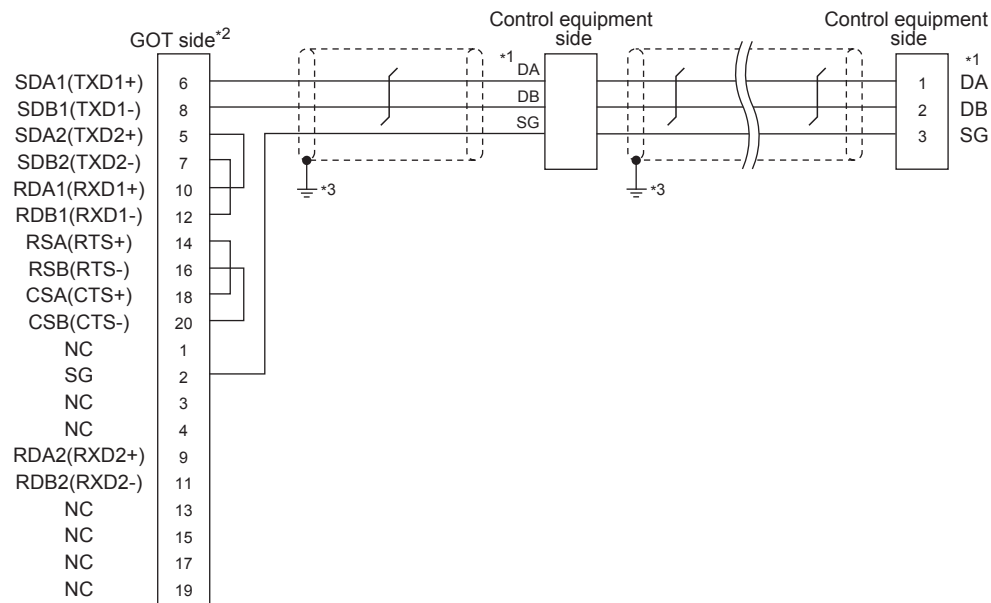
*2 Terminating resistor should be provided for a Interface converter and a control equipment which will be terminals.

*3 Connect FG grounding to the single-sided end of a cable shield line.

*4 Since the Interface converter has a built-in terminating resistor, set the terminating resistor of GOT to "Enable".
For details of terminating resistor settings, refer to the following.

➡ 3.5.5 Connecting to CMC10L

(3) RS485 connection diagram 3)



*1 Pin No. of control equipment differs depending on the model. Refer to the following table.

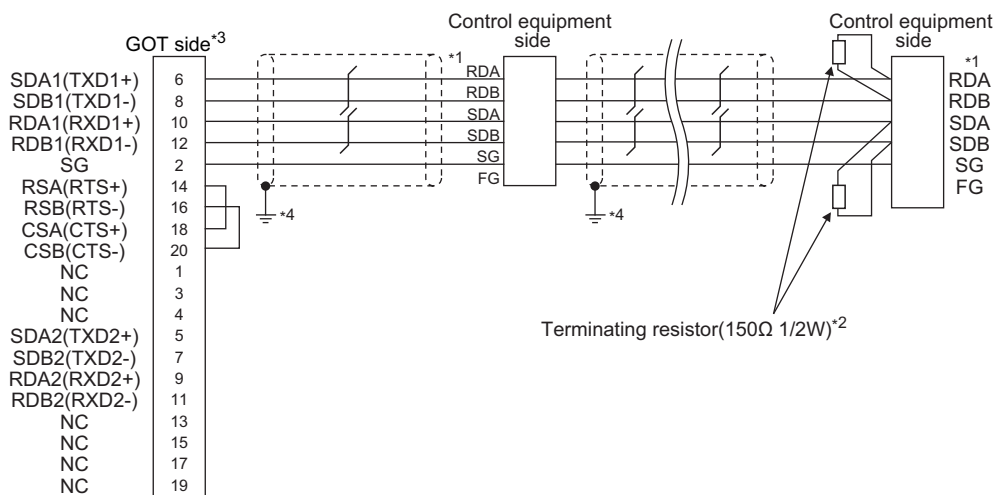
Signal name	Model of control equipment			
	DMC10	SDC15	SDC25/26 SDC35/36	AUR350C AUR450C
	Pin No.	Pin No.	Pin No.	Pin No.
DA	4	16	22	DA
DB	5	17	23	DB
SG	6	18	24	SG

*2 Set the terminating resistor of GOT as follows.
Set the terminating resistor setting switch of the GOT main unit to "Disable".

➡ **3. Connecting terminating resistors**

*3 Connect FG grounding to the single-sided end of a cable shield line.

(4) RS485 connection diagram 4)



*1 Pin No. of control equipment differs depending on model or optional function model.
Refer to the following table. The numbers in () of the following table correspond to optional function models.

Signal name	Model of control equipment						
	SDC20		SDC21	SDC30	SDC31		SDC40A/40B/40G
	(02, 04)	(09)	(03, 06, 08)	(040, 041)	(045)	(446, 546)	
	Pin No.	Pin No.	Pin No.	Pin No.	Pin No.	Pin No.	
RDA	17	18	27	18	18	27	59
RDB	18	19	28	19	19	28	60
SDA	15	16	25	16	16	25	57
SDB	16	17	26	17	17	26	58
SG	5	5	29	5	5	29	61
FG	3, 4	3, 4	3, 4	3, 4	3, 4	3, 4	3

Signal name	Model of control equipment			
	CMF050 CML	PBC201-VN2	CMC10B	AHC2001
	Pin No.	Pin No.	Pin No.	Pin No.
RDA	9	12	11	3
RDB	10	13	12	2
SDA	7	14	13	5
SDB	8	15	14	4
SG	12	16	15	1
FG	19	3	-	-

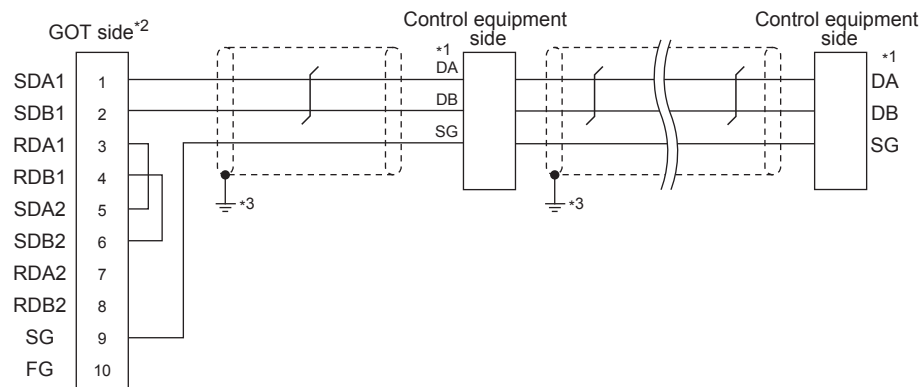
*2 Terminating resistor should be provided for a control equipment which will be a terminal.

*3 Set the terminating resistor of GOT as follows.
Set the terminating resistor setting switch of the GOT main unit to "100 OHM".

➡ **3. Connecting terminating resistors**

*4 Connect FG grounding to the single-sided end of a cable shield line.

(5) RS485 connection diagram 5)



*1 Pin No. of Model of control equipment differs depending on the model. Refer to the following table.

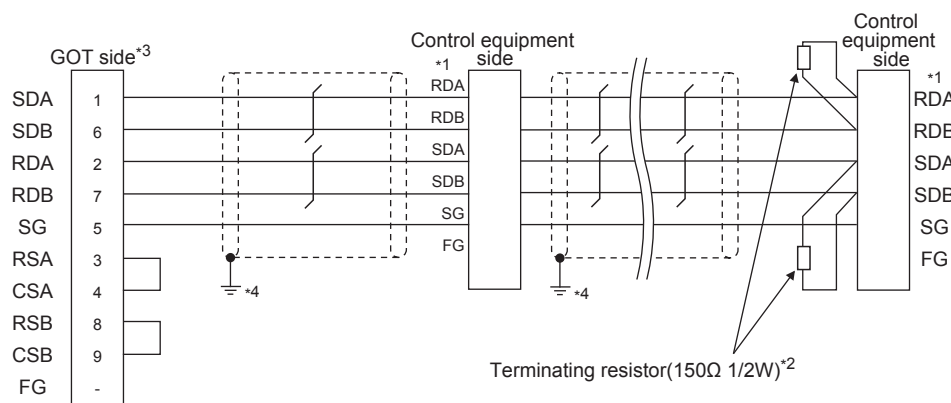
Signal name	Model of control equipment			
	DMC10	SDC15	SDC25/26 SDC35/36	AUR350C AUR450C
	Pin No.	Pin No.	Pin No.	Pin No.
DA	4	16	22	DA
DB	5	17	23	DB
SG	6	18	24	SG

*2 Set the terminating resistor of GOT as follows.
Set the terminating resistor setting switch of the GOT main unit to "Disable".

➡ **3.** Connecting terminating resistors

*3 Connect FG grounding to the single-sided end of a cable shield line.

(6) RS485 connection diagram 6)



*1 Pin No. of control equipment differs depending on model or optional function model.
Refer to the following table. The numbers in () of the following table correspond to optional function models.

Signal name	Model of control equipment						
	SDC20		SDC21	SDC30	SDC31		SDC40A/40B/40G
	(02, 04)	(09)	(03, 06, 08)	(040, 041)	(045)	(446, 546)	
	Pin No.	Pin No.	Pin No.	Pin No.	Pin No.	Pin No.	
RDA	17	18	27	18	18	27	59
RDB	18	19	28	19	19	28	60
SDA	15	16	25	16	16	25	57
SDB	16	17	26	17	17	26	58
SG	5	5	29	5	5	29	61
FG	3, 4	3, 4	3, 4	3, 4	3, 4	3, 4	3

Signal name	Model of control equipment			
	CMF050 CML	PBC201-VN2	CMC10B	AHC2001
	Pin No.	Pin No.	Pin No.	Pin No.
RDA	9	12	11	3
RDB	10	13	12	2
SDA	7	14	13	5
SDB	8	15	14	4
SG	12	16	15	1
FG	19	3	-	-

*2 Terminating resistor should be provided for a control equipment which will be a terminal.

*3 Set the terminating resistor of GOT as follows.

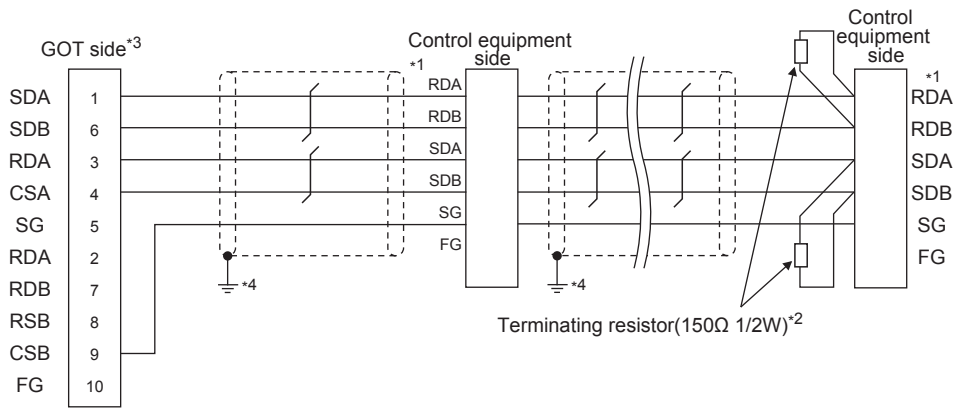
Set the terminating resistor setting switch of the GOT main unit to "100 OHM".

Set the terminating resistor selector to "330 Ω".

➡ **3.** Connecting terminating resistors

*4 Connect FG grounding to the single-sided end of a cable shield line.

(7) RS485 connection diagram 7)



*1 Pin No. of control equipment differs depending on model or optional function model.

Refer to the following table. The numbers in () of the following table correspond to optional function models.

Signal name	Model of control equipment						
	SDC20		SDC21	SDC30	SDC31		SDC40A/40B/40G
	(02, 04)	(09)	(03, 06, 08)	(040, 041)	(045)	(446, 546)	
	Pin No.	Pin No.	Pin No.	Pin No.	Pin No.	Pin No.	
RDA	17	18	27	18	18	27	59
RDB	18	19	28	19	19	28	60
SDA	15	16	25	16	16	25	57
SDB	16	17	26	17	17	26	58
SG	5	5	29	5	5	29	61
FG	3, 4	3, 4	3, 4	3, 4	3, 4	3, 4	3

Signal name	Model of control equipment			
	CMF050 CML	PBC201-VN2	CMC10B	AHC2001
	Pin No.	Pin No.	Pin No.	Pin No.
RDA	9	12	11	3
RDB	10	13	12	2
SDA	7	14	13	5
SDB	8	15	14	4
SG	12	16	15	1
FG	19	3	-	-

*2 Terminating resistor should be provided for a control equipment which will be a terminal.

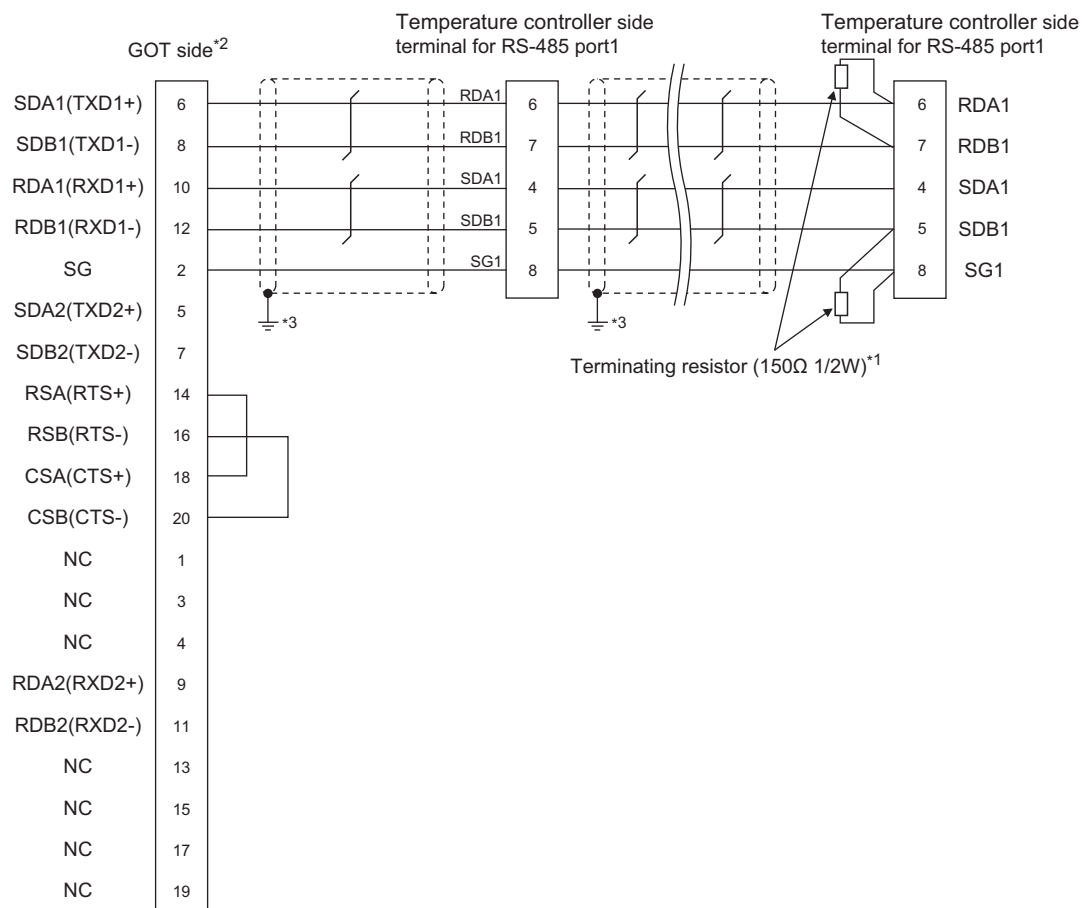
*3 Set the terminating resistor of GOT as follows.

Set the terminating resistor setting switch of the GOT main unit to "100 OHM".

➡ **3. Connecting terminating resistors**

*4 Connect FG grounding to the single-sided end of a cable shield line.

(8) RS485 connection diagram 8)



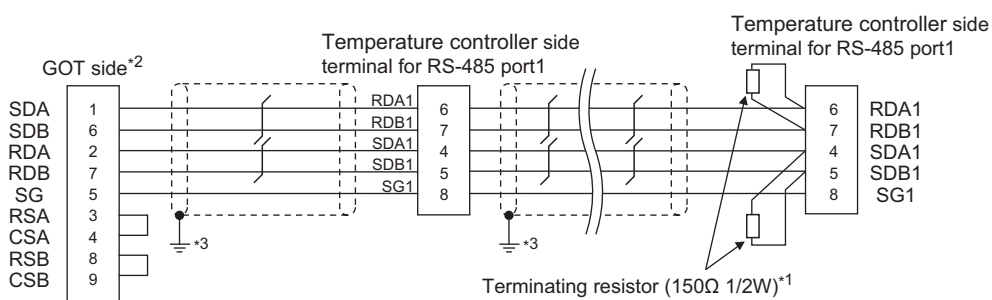
*1 Terminating resistor should be provided for a temperature controller which will be a terminal.

*2 Set the terminating resistor of GOT as follows.
Set the terminating resistor setting switch of the GOT main unit to "100 OHM".

■ 3. Connecting terminating resistors

*3 Connect FG grounding to the single-sided end of a cable shield line.

(9) RS485 connection diagram 9)



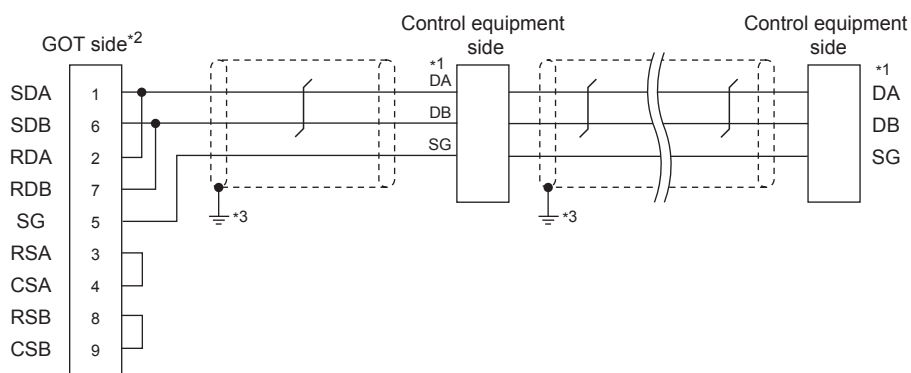
*1 Terminating resistor should be provided for a temperature controller which will be a terminal.

*2 Set the terminating resistor of GOT as follows.
Set the terminating resistor setting switch of the GOT main unit to "100 OHM".

■ 3. Connecting terminating resistors

*3 Connect FG grounding to the single-sided end of a cable shield line.

(12) RS485 connection diagram 12)



*1 Pin No. of control equipment differs depending on the model. Refer to the following table.

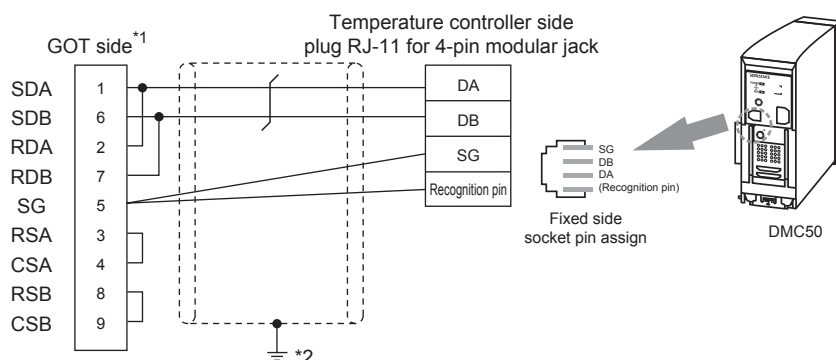
Signal name	Model of control equipment			
	DMC10	SDC15	SDC25/26 SDC35/36	AUR350C AUR450C
	Pin No.	Pin No.	Pin No.	Pin No.
DA	4	16	22	DA
DB	5	17	23	DB
SG	6	18	24	SG

*2 Set the terminating resistor setting switch of the GOT main unit to "100 OHM".

➡ **3.** Connecting terminating resistors

*3 Connect FG grounding to the single-sided end of a cable shield line.

(13) RS485 connection diagram 13)

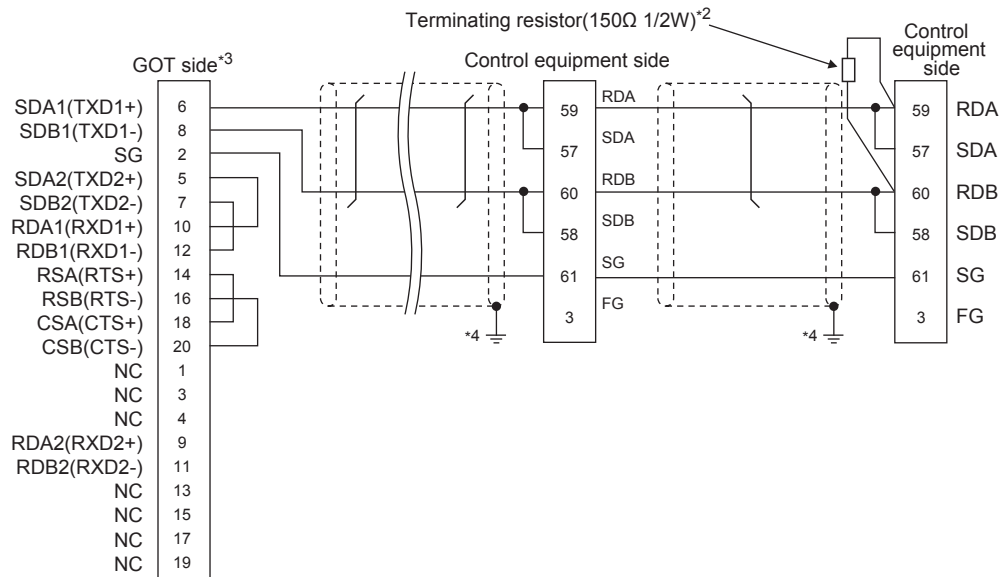


*1 Set the terminating resistor setting switch of the GOT main unit to "100 OHM".

➡ **3.** Connecting terminating resistors

*2 Connect FG grounding to the single-sided end of a cable shield line.

(14) RS485 connection diagram 14)



*1 Pin No. of control equipment differs depending on the model. Refer to the following table.

Signal name	Model of control equipment						
	SDC20		SDC21	SDC30	SDC31		SDC40A/40B/ 40G
	(02, 04)	(09)	(03, 06, 08)	(040, 041)	(045)	(446, 546)	
	Pin No.	Pin No.	Pin No.	Pin No.	Pin No.	Pin No.	Pin No.
RDA	17	18	27	18	18	27	59
RDB	18	19	28	19	19	28	60
SDA	15	16	25	16	16	25	57
SDB	16	17	26	17	17	26	58
SG	5	5	29	5	5	29	61
FG	3, 4	3, 4	3, 4	3, 4	3, 4	3, 4	3

Signal name	Model of control equipment			
	CMF050 CML	PBC201-VN2	CMC10B	AHC2001
	Pin No.	Pin No.	Pin No.	Pin No.
RDA	9	12	11	3
RDB	10	13	12	2
SDA	7	14	13	5
SDB	8	15	14	4
SG	12	16	15	1
FG	19	3	-	-

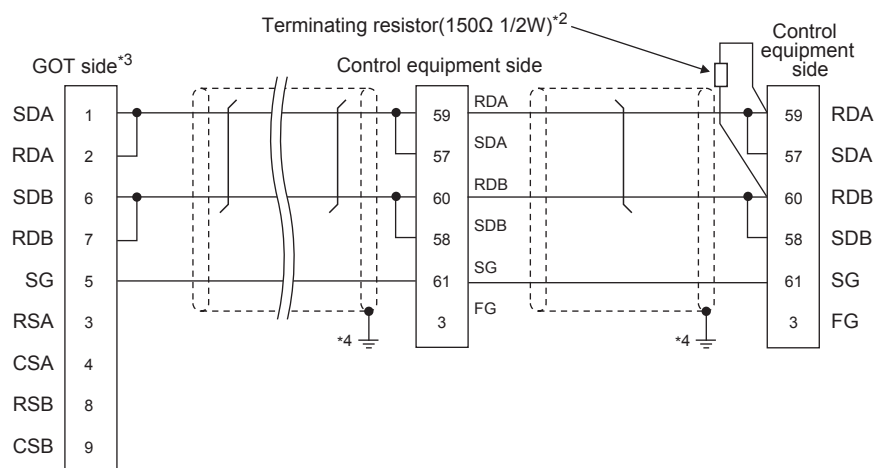
*2 Terminating resistor should be provided for a control equipment which will be a terminal.

*3 Set the terminating resistor of GOT as follows.
Set the terminating resistor setting switch of the GOT main unit to "100 OHM".

➡ ■ 3. Connecting terminating resistors

*4 Connect FG grounding to the single-sided end of a cable shield line.

(15) RS485 connection diagram 15)



*1 Pin No. of control equipment differs depending on the model. Refer to the following table.

Signal name	Model of control equipment			
	SDC20		SDC21	SDC40A/40B/40G
	(02, 04)	(09)	(03, 06, 08)	
	Pin No.	Pin No.	Pin No.	
RDA	17	18	27	59
RDB	18	19	28	60
SDA	15	16	25	57
SDB	16	17	26	58
SG	5	5	29	61
FG	3, 4	3, 4	3, 4	3

Signal name	Model of control equipment			
	CMF050 CML	PBC201-VN2	CMC10B	AHC2001
	Pin No.	Pin No.	Pin No.	Pin No.
RDA	9	12	11	3
RDB	10	13	12	2
SDA	7	14	13	5
SDB	8	15	14	4
SG	12	16	15	1
FG	19	3	-	-

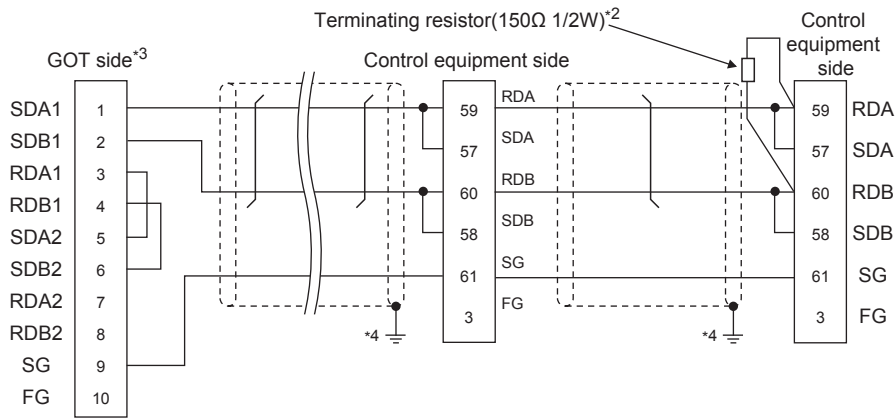
*2 Terminating resistor should be provided for a control equipment which will be a terminal.

*3 Set the terminating resistor setting switch of the GOT main unit to "100 OHM".

➡ **3. Connecting terminating resistors**

*4 Connect FG grounding to the single-sided end of a cable shield line.

(16) RS485 connection diagram 16)



*1 Pin No. of control equipment differs depending on the model. Refer to the following table.

Signal name	Model of control equipment						
	SDC20		SDC21	SDC30	SDC31		SDC40A/40B/ 40G
	(02, 04)	(09)	(03, 06, 08)	(040, 041)	(045)	(446, 546)	
	Pin No.	Pin No.	Pin No.	Pin No.	Pin No.	Pin No.	Pin No.
RDA	17	18	27	18	18	27	59
RDB	18	19	28	19	19	28	60
SDA	15	16	25	16	16	25	57
SDB	16	17	26	17	17	26	58
SG	5	5	29	5	5	29	61
FG	3, 4	3, 4	3, 4	3, 4	3, 4	3, 4	3

Signal name	Model of control equipment			
	CMF050 CML	PBC201-VN2	CMC10B	AHC2001
	Pin No.	Pin No.	Pin No.	Pin No.
RDA	9	12	11	3
RDB	10	13	12	2
SDA	7	14	13	5
SDB	8	15	14	4
SG	12	16	15	1
FG	19	3	-	-

*2 Terminating resistor should be provided for a control equipment which will be a terminal.

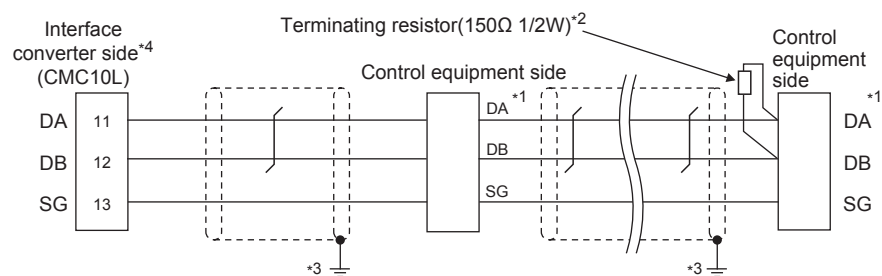
*3 Set the terminating resistor of GOT as follows.

Set the terminating resistor setting switch of the GOT main unit to "100 OHM".

➡ **3.** Connecting terminating resistors

*4 Connect FG grounding to the single-sided end of a cable shield line.

(17) RS485 connection diagram 17)



*1 Pin No. of control equipment differs depending on the model. Refer to the following table

Signal name	Model of control equipment				
	SDC45/46	CMS CMF015	MQV MPC	MVF	RX
	Pin No.	Pin No.	Pin No.	Pin No.	Pin No.
DA	C10	5	7	1	1
DB	C11	6	8	2	2
SG	C12	10	9	7	3

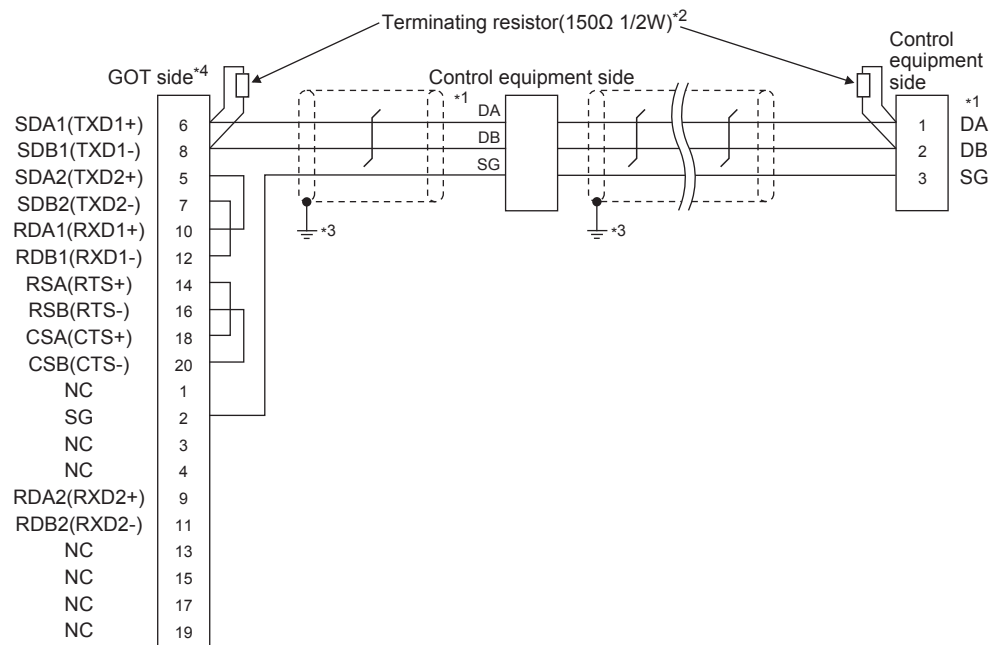
*2 Terminating resistor should be provided for an Interface converter and a control equipment which will be terminals.

*3 Connect FG grounding to the single-sided end of a cable shield line.

*4 Since the Interface converter has a built-in terminating resistor, set the terminating resistor of GOT to "Enable".
For details of terminating resistor settings, refer to the following.

➡ 3.5.5 Connecting to CMC10L

(18) RS485 connection diagram 18)



*1 Pin No. of control equipment differs depending on the model. Refer to the following table

Signal name	Model of control equipment				
	SDC45/46	CMS CMF015	MQV MPC	MVF	RX
	Pin No.	Pin No.	Pin No.	Pin No.	Pin No.
DA	C10	5	7	1	1
DB	C11	6	8	2	2
SG	C12	10	9	7	3

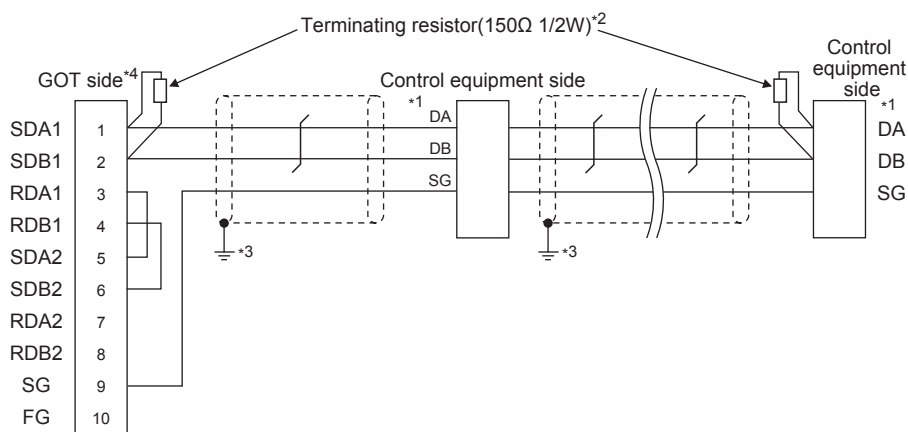
*2 Terminating resistor should be provided for an Interface converter and a control equipment which will be terminals.

*3 Connect FG grounding to the single-sided end of a cable shield line.

*4 Set the terminating resistor of GOT as follows.
Set the terminating resistor setting switch of the GOT main unit to "Disable".

➡ ■ 3. Connecting terminating resistors

(19) RS485 connection diagram 19)



*1 Pin No. of control equipment differs depending on the model. Refer to the following table

Signal name	Model of control equipment				
	SDC45/46	CMS CMF015	MQV MPC	MVF	RX
	Pin No.	Pin No.	Pin No.	Pin No.	Pin No.
DA	C10	5	7	1	1
DB	C11	6	8	2	2
SG	C12	10	9	7	3

*2 Terminating resistor should be provided for an Interface converter and a control equipment which will be terminals.

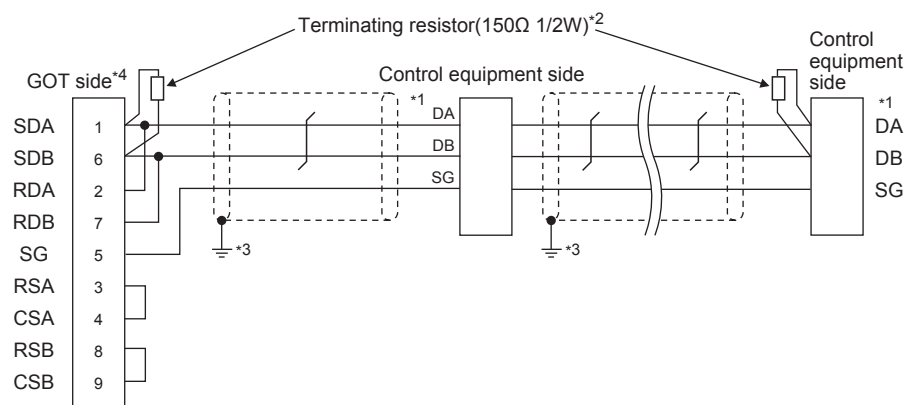
*3 Connect FG grounding to the single-sided end of a cable shield line.

*4 Set the terminating resistor of GOT as follows.

Set the terminating resistor setting switch of the GOT main unit to "Disable".

➡ ■ 3. Connecting terminating resistors

(20) RS485 connection diagram 20)



*1 Pin No. of control equipment differs depending on the model. Refer to the following table

Signal name	Model of control equipment				
	SDC45/46	CMS CMF015	MQV MPC	MVF	RX
	Pin No.	Pin No.	Pin No.	Pin No.	Pin No.
DA	C10	5	7	1	1
DB	C11	6	8	2	2
SG	C12	10	9	7	3

*2 Terminating resistor should be provided for an Interface converter and a control equipment which will be terminals.

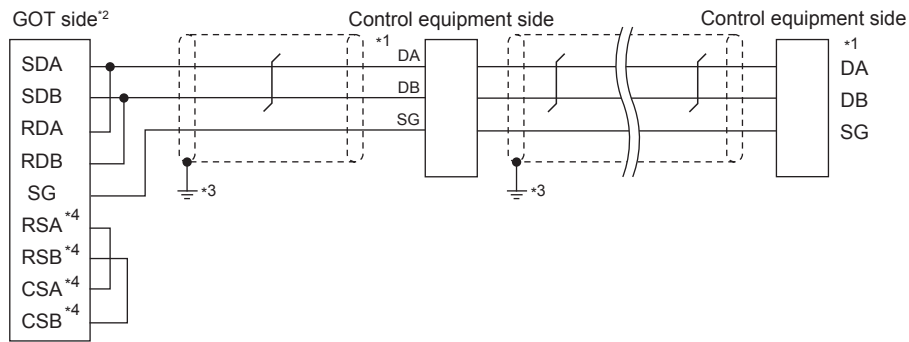
*3 Connect FG grounding to the single-sided end of a cable shield line.

*4 Set the terminating resistor of GOT as follows.

Set the terminating resistor setting switch of the GOT main unit to "Disable".

➡ ■ 3. Connecting terminating resistors

(21) RS485 connection diagram 21)




*1 Pin No. of control equipment differs depending on the model. Refer to the following table.

Signal name	Model of control equipment			
	DMC10	SDC15	SDC25/26 SDC35/36	AUR350C AUR450C
	Pin No.	Pin No.	Pin No.	Pin No.
DA	4	16	22	DA
DB	5	17	23	DB
SG	6	18	24	SG

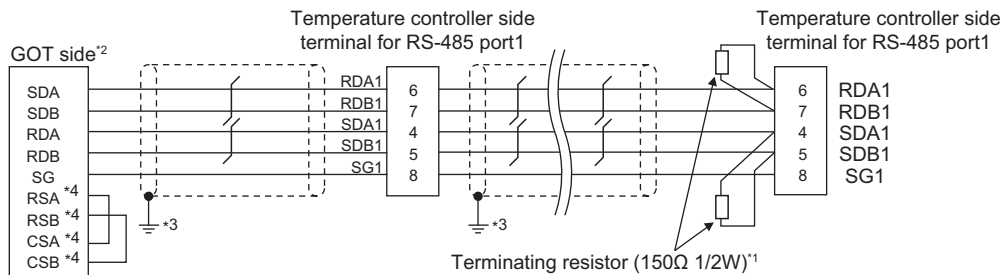
*2 Set the terminating resistor setting switch of the GOT main unit to "110Ω".

➡ ■ 3. Connecting terminating resistors

*3 Connect FG grounding to the single-sided end of a cable shield line.

*4 The signals RSA, RSB, CSA, and CSB are not provided for . Return connection is not required.

(22) RS485 connection diagram 22)




*1 Terminating resistor should be provided for a temperature controller which will be a terminal.

*2 Set the terminating resistor of GOT as follows.

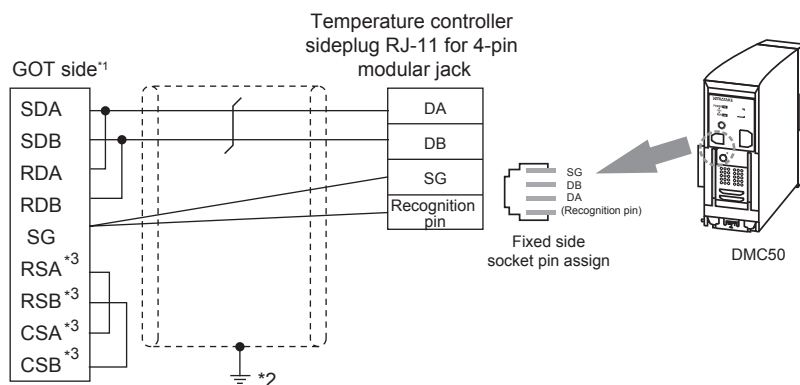
Set the terminating resistor setting switch of the GOT main unit to "330Ω".

➡ ■ 3. Connecting terminating resistors

*3 Connect FG grounding to the single-sided end of a cable shield line.

*4 The signals RSA, RSB, CSA, and CSB are not provided for . Return connection is not required.


(23) RS485 connection diagram 23)



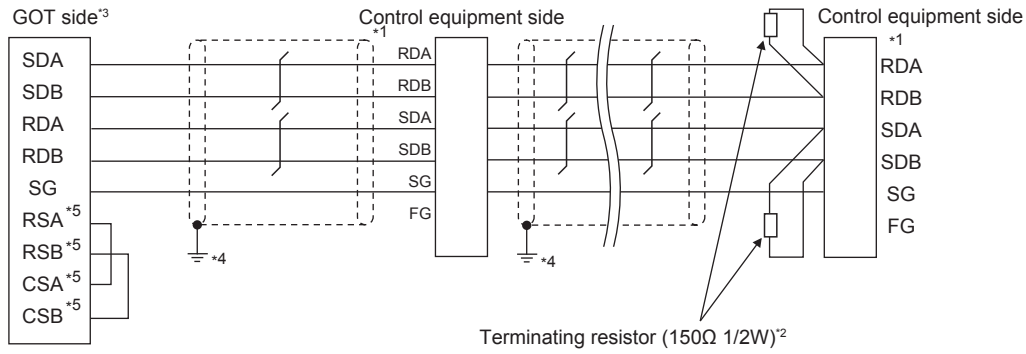
*1 Set the terminating resistor setting switch of the GOT main unit to "110Ω".

➡ **3. Connecting terminating resistors**

*2 Connect FG grounding to the single-sided end of a cable shield line.

*3 The signals RSA, RSB, CSA, and CSB are not provided for . Return connection is not required.

(24) RS485 connection diagram 24)



*1 Pin No. of control equipment differs depending on model and optional function model.

Refer to the following table. The numbers in () of the following table correspond to optional function models.

Signal name	Model of control equipment						
	SDC20		SDC21	SDC30	SDC31		SDC40A/40B/40G
	(02, 04)	(09)	(03, 06, 08)	(040, 041)	(045)	(446, 546)	
	Pin No.	Pin No.	Pin No.	Pin No.	Pin No.	Pin No.	
RDA	17	18	27	18	18	27	59
RDB	18	19	28	19	19	28	60
SDA	15	16	25	16	16	25	57
SDB	16	17	26	17	17	26	58
SG	5	5	29	5	5	29	61
FG	3, 4	3, 4	3, 4	3, 4	3, 4	3, 4	3

Signal name	Model of control equipment			
	CMF050 CML	PBC201-VN2	CMC10B	AHC2001
	Pin No.	Pin No.	Pin No.	Pin No.
RDA	9	12	11	3
RDB	10	13	12	2
SDA	7	14	13	5
SDB	8	15	14	4
SG	12	16	15	1
FG	19	3	-	-


*2 Terminating resistor should be provided for a control equipment which will be a terminal.

*3 Set the terminating resistor of GOT as follows.

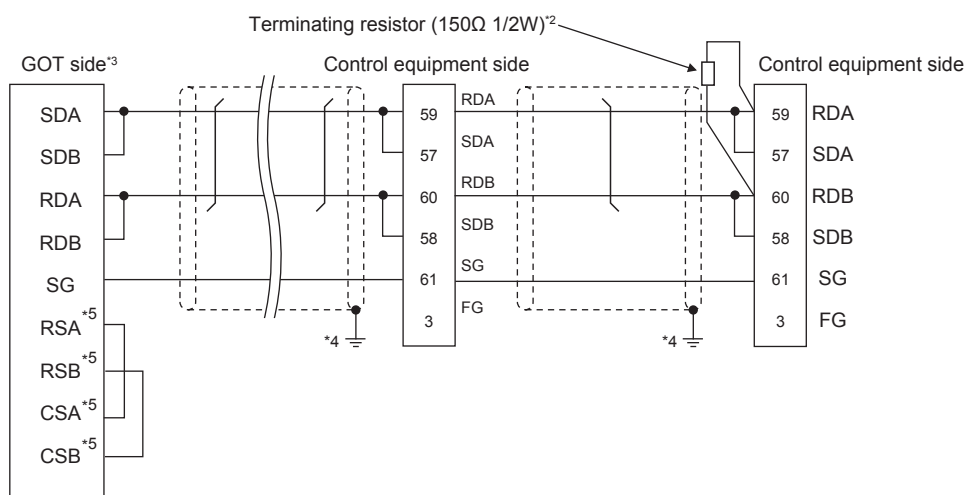
Set the terminating resistor setting switch of the GOT main unit to "330Ω".

➡ **3. Connecting terminating resistors**

*4 Connect FG grounding to the single-sided end of a cable shield line.

*5 The signals RSA, RSB, CSA, and CSB are not provided for . Return connection is not required.

(25) RS485 connection diagram 25)



*1 Pin No. of control equipment differs depending on the model. Refer to the following table.

Signal name	Model of control equipment			
	SDC20		SDC21	SDC40A/40B/40G
	(02, 04)	(09)	(03, 06, 08)	
	Pin No.	Pin No.	Pin No.	Pin No.
RDA	17	18	27	59
RDB	18	19	28	60
SDA	15	16	25	57
SDB	16	17	26	58
SG	5	5	29	61
FG	3, 4	3, 4	3, 4	3


Signal name	Model of control equipment			
	CMF050 CML	PBC201-VN2	CMC10B	AHC2001
	Pin No.	Pin No.	Pin No.	Pin No.
RDA	9	12	11	3
RDB	10	13	12	2
SDA	7	14	13	5
SDB	8	15	14	4
SG	12	16	15	1
FG	19	3	-	-

*2 Terminating resistor should be provided for a control equipment which will be a terminal.

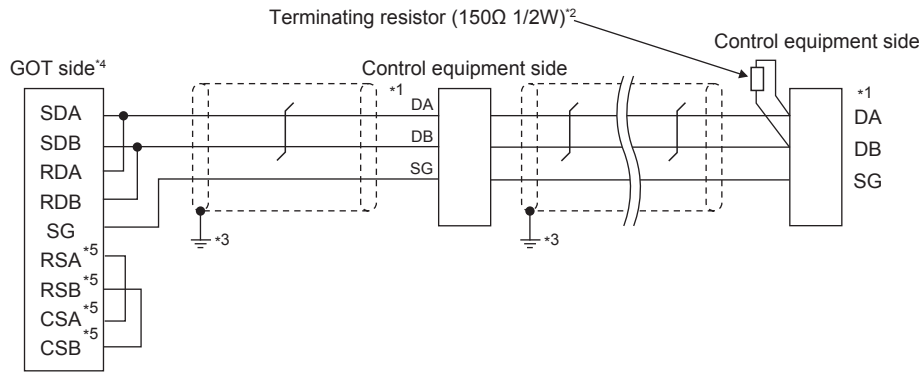
*3 Set the terminating resistor setting switch of the GOT main unit to "110Ω".

■ 3. Connecting terminating resistors

*4 Connect FG grounding to the single-sided end of a cable shield line.

*5 The signals RSA, RSB, CSA, and CSB are not provided for . Return connection is not required.

(26) RS485 connection diagram 26)



*1 Pin No. of control equipment differs depending on the model. Refer to the following table.

Signal name	Model of control equipment				
	SDC45/46	CMS CMF015	MQV MPC	MVF	RX
	Pin No.	Pin No.	Pin No.	Pin No.	Pin No.
DA	C10	5	7	1	1
DB	C11	6	8	2	2
SG	C12	10	9	7	3


*2 Terminating resistor should be provided for an Interface converter and a control equipment which will be terminals.

*3 Connect FG grounding to the single-sided end of a cable shield line.

*4 Set the terminating resistor of GOT as follows.

Set the terminating resistor setting switch of the GOT main unit to "110Ω".

➡ **3. Connecting terminating resistors**

*5 The signals RSA, RSB, CSA, and CSB are not provided for . Return connection is not required.

2. Precautions when preparing a cable

(1) Cable length

The length of the RS-485 cable must be 500m or less.

(2) GOT side connector

For the GOT side connector, refer to the following.

➡ 1.4.1 GOT connector specifications

(3) AZBIL control equipment side connector

Use the connector compatible with the AZBIL control equipment side module.

For details, refer to the user's manual of the AZBIL control equipment.

3. Connecting terminating resistors

(1) GOT side

Set the terminating resistor by operating the terminating resistor setting switch.

For the procedure to set the terminating resistor, refer to the following.

➡ 1.4.3 Terminating resistors of GOT

(2) AZBIL control equipment side

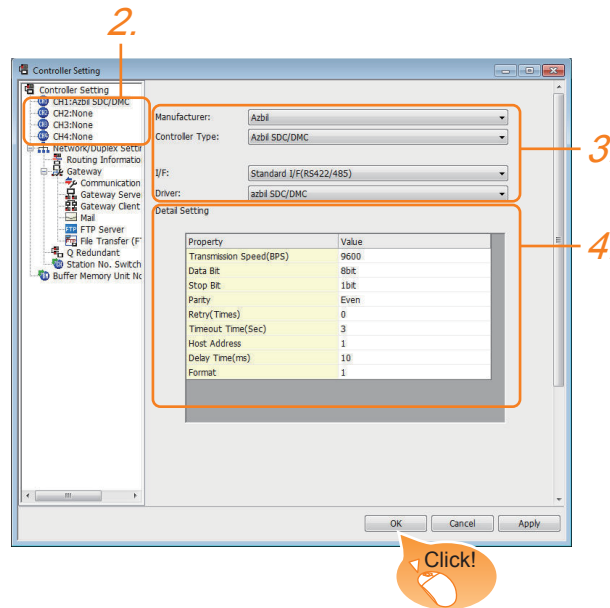
When connecting a AZBIL control equipment to the GOT, a terminating resistor must be connected.

➡ 3.5 Control Equipment Side Setting

3.4 GOT Side Settings

3.4.1 Setting communication interface (Communication settings)

Set the channel of the connected equipment.



Step 1. Select [Common] → [Controller Setting] from the menu.

Step 2. The Controller Setting window is displayed. Select the channel to be used from the list menu.

Step 3. Set the following items.

- Manufacturer: Azbil
- Controller Type: Set either of the followings.
 <Connecting to DMC50 and AHC2001>
 Azbil DMC50
 <Connecting to a module other than above>
 Azbil SDC/DMC
- I/F: Interface to be used
- Driver: Azbil SDC/DMC

Step 4. The detailed setting is displayed after Manufacturer, Controller Type, I/F, and Driver are set. Make the settings according to the usage environment.

⇒ 3.4.2 Communication detail settings

Click the [OK] button when settings are completed.

POINT

The settings of connecting equipment can be confirmed in [I/F Communication Setting]. For details, refer to the following.

⇒ 1.1.2 I/F communication setting

3.4.2 Communication detail settings

Property	Value
Transmission Speed(BPS)	9600
Data Bit	8 bit
Stop Bit	1 bit
Parity	Even
Retry(Times)	0
Timeout Time(Sec)	3
Host Address	1
Delay Time(ms)	10
Format	1

Item	Description	Range
Transmission Speed	Set this item when change the transmission speed used for communication with the connected equipment. (Default: 9600bps)	9600bps, 19200bps, 38400bps, 57600bps, 115200bps
Data Bit	Set this item when change the data length used for communication with the connected equipment. (Default: 8bits)	7bits/8bits
Stop Bit	Specify the stop bit length for communications. (Default: 1bit)	1bit/2bits
Parity	Specify whether or not to perform a parity check, and how it is performed during communication. (Default: Even)	None Even Odd
Retry	Set the number of retries to be performed when a communication error occurs. (Default: 0time)	0 to 5times
Timeout Time	Set the time period for a communication to time out. (Default: 3sec)	1 to 30sec
Host Address ^{*3*4}	Specify the host address (station No. of the GOT to which the temperature controller is connected) in the connected network. (Default: 1)	1 to 15
Delay Time	Set this item to adjust the transmission timing of the communication request from the GOT.*1 (Default: 1ms)	0 to 300ms
Format ^{*2}	Select the communication format. (Default: 1) format 1: only continuous access format 2: continuous and random access	1/2

*1 Do not specify "0".

*2 Format is ignored when connecting to DMC50.

*3 Host Address is ignored when connecting to DMC10 or SDC.

*4 Host Address is valid when connecting to DMC50.

Devices to be the target of Host Address setting differ depending on the system configuration.

<When connecting to the temperature controller via COM module>

Specify the station No. of the COM module.

<When connecting to the temperature controller directly>

Specify the station No. of the temperature controller.

POINT

Format setting

The compatible format of control equipment differs depending on model.

Model name	Compatible format
SDC20/21, SDC30/31, SDC40A/40B/40G, CMS, CMF, CML, MQV, MPC, MVF, PBC201-VN2, RX	Format 1 only
DMC10, SDC15, SDC25/26, SDC35/36, SDC45/46, AUR350C, AUR450C, CMC10B	Format 1 or Format 2
DMC50, AHC2001	The format setting is invalid.

For the continuous access and random access of the control equipment, refer to the following manual.

- ⇒ User's Manual of the AZBIL control equipment

POINT

(1) Communication interface setting by the Utility

The communication interface setting can be changed on the Utility's [Communication setting] after writing [Communication Settings] of project data.
For details on the Utility, refer to the following manual.

- ⇒ GOT2000 Series User's Manual (Utility)

(2) Precedence in communication settings

When settings are made by GT Designer3 or the Utility, the latest setting is effective.

3.5 Control Equipment Side Setting

POINT

AZBIL control equipment

For details of AZBIL control equipment, refer to the following manual.

➡ User's Manual of the AZBIL control equipment

Model name		Refer to
Control equipment	DMC10	3.5.1
	SDC15, SDC25/26, SDC35/36	3.5.3
	SDC20/21	3.5.4
	SDC30/31	3.5.4
	SDC40A/40B/40G	3.5.2
	DMC50	3.5.6
	SDC45/46	3.5.7
	CMS, CMF015	3.5.8
	CML, CMF050	3.5.9
	MQV	3.5.10
	MPC	3.5.11
	PBC201-VN2	3.5.12
	MVF	3.5.13
	AUR350C, AUR450C	3.5.14
	RX	3.5.15
	CMC10B	3.5.16
	AHC2001 CPU	3.5.17
	AHC2001 SCU	3.5.18
Interface converter	CMC10L	3.5.5

3.5.1 Connecting to DMC10

1. Communication settings

Make the communication settings by operating the Smart Loader Package (SLP-D10) of the temperature controller.

Item	Set value
Transmission speed ^{*1}	9600bps, 19200bps
Communication mode ^{*2}	CPL
Data bit	8bits
Parity bit ^{*1}	Even, none
Stop bit	2bits
Communication minimum response time	1ms, 10ms, 100ms, 200ms
Station address ^{*3*4}	0 to F

*1 Adjust the settings with GOT settings.

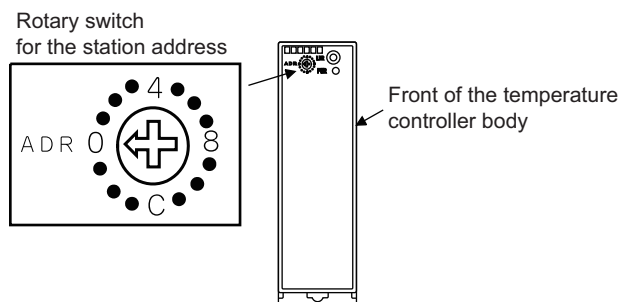
*2 Set to CPL.

*3 Do not set to "0".

*4 Select the station address without overlapping with that of other units.

2. Station address setting

Set the station address using the rotary switch for the station address.



3.5.2 Connecting to SDC40A/40B/40G

1. Communication settings

Make the communication settings by operating the key of the temperature controller.

Item	Set value
Transmission speed ^{*1}	9600bps
Data Bit	8bits
Parity bit ^{*1}	Even, none
Stop bit	1bit, 2bits
Station address ^{*2*3}	0 to 127

^{*1} The transmission speed setting must be consistent with that of the GOT side.

^{*2} Do not set to "0".

^{*3} Select the station address without overlapping with that of other units.

3.5.3 Connecting to SDC15, SDC25/26 or SDC35/36

1. Communication settings

Make the communication settings by operating the key or Smart Loader Package (SLP-C35) of the temperature controller.

Item	Set value
Transmission speed ^{*1}	9600bps, 19200bps
Communication mode ^{*2}	CPL
Data bit ^{*1}	7bits, 8bits
Parity bit ^{*1}	Odd, even, none
Stop bit ^{*1}	1bit, 2bits
Communication minimum response time	1 to 250ms
Station address ^{*3*4}	0 to 127

^{*1} The transmission speed setting must be consistent with that of the GOT side.

^{*2} Set to CPL.

^{*3} Do not set to "0".

^{*4} Select the station address without overlapping with that of other units.

3.5.4 Connecting to SDC20/21, SDC30/31

1. Communication settings

Make the communication settings by operating the key of the temperature controller.

Item	Set value
Transmission speed ^{*1}	9600bps
Data bit	8bits
Parity bit	Disable
Stop bit	2bits
Station address ^{*2*3}	0 to 127

*1 The transmission speed setting must be consistent with that of the GOT side.

*2 Do not set to "0".

*3 Select the station address without overlapping with that of other units.

3.5.5 Connecting to CMC10L

1. Communication settings

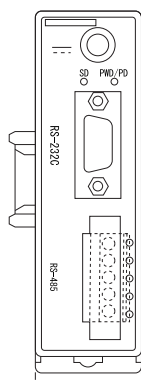
Make the communication settings by operating the DIP switch of the Interface converter

Item	Set value
Transmission speed ^{*1}	9600bps, 19200bps, 38400bps
Frame length ^{*2}	9 to 15bits

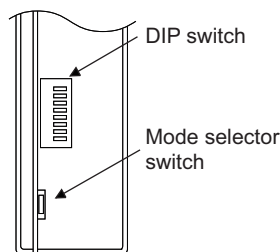
*1 The transmission speed setting must be consistent with that of the GOT side.

*2 The sum of data length, parity bit and stop bit

2. Settings by switch



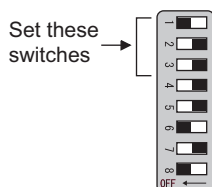
Front view of CMC10L body



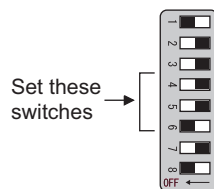
Rear view of CMC10L body

(1) Setting DIP switches

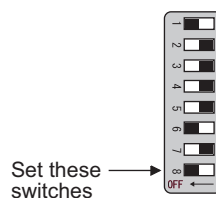
(a) Transmission speed settings



Transmission speed (bps)	Switch No.		
	1	2	3
9600	ON	OFF	ON
19200	OFF	ON	ON
38400	ON	ON	ON

(b) Frame length settings

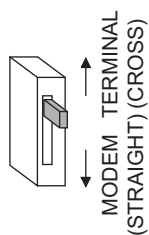
Frame length	Switch No.		
	4	5	6
8bits	OFF	OFF	OFF
9bits	ON	OFF	OFF
10bits	OFF	ON	OFF
11bits	ON	ON	OFF
12bits	OFF	OFF	ON
13bits	ON	OFF	ON
14bits	OFF	ON	ON
15bits	ON	ON	ON

(c) Connecting terminating resistors

Terminating resistor	Switch No.
	8
Enable	ON
Disable	OFF

(2) Mode selector switch settings

Set the switch to "TERMINAL".



3.5.6 Connecting to DMC50

1. Communication settings

Make the communication settings by operating the Smart Loader Package (SLP-D50/SLP-H21) of the temperature controller.

Item	Set value
Transmission speed ^{*1}	9600bps, 19200bps, 38400bps
Communication mode	CPL
Data bit	8bits (fixed)
Parity bit	Even (fixed)
Stop bit	1bit (fixed)
Module address ^{*2*3*4}	0 to F

*1 Adjust the settings with GOT settings.

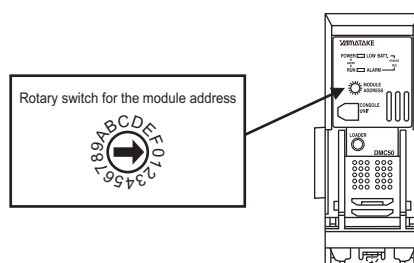
*2 Set the module address using the rotary switch for module address.

*3 Do not set to "0".

*4 Select the module address without overlapping with that of other units.

2. Module address setting

Set the module address using the rotary switch for module address.



3.5.7 Connecting to SDC45/46

1. Communication settings

Make the communication settings by operating the Smart Loader Package (SLP-C45) of the temperature controller.

Item	Set value
Transmission speed ^{*1}	9600bps, 19200bps, 38400bps
Communication mode ^{*2}	CPL
Data bit	7bits, 8bits
Parity bit ^{*1}	Odd, even, none
Stop bit	1bit, 2bits
Communication minimum response time ^{*5}	1 to 250ms
Station address ^{*3*4}	0 to 120

*1 Adjust the settings with GOT settings.

*2 Set to CPL.

*3 Do not set to "0".

*4 Select the station address without overlapping with that of other units.

*5 When using the interface converter CMC10L, set the communication minimum response time to 3ms or more.

3.5.8 Connecting to CMS, CMF015

■1. Communication settings

Make the communication settings by operating the key of the control equipment.

Item	Set value
Transmission speed ^{*1}	9600bps
Communication condition selection	0: 8-bit data length, Even parity, Stop bit 1
	1: 8-bit data length, Non parity, Stop bit 2
Station address ^{*2*3}	0 to 99

*1 Adjust the settings with GOT settings.

*2 Do not set to "0".

*3 Select the station address without overlapping with that of other units.

3.5.9 Connecting to CML, CMF050

■1. Communication settings

Make the communication settings by operating the key of the control equipment.

Item	Set value
Transmission speed ^{*1}	9600bps
Communication condition selection ^{*1}	00: 8-bit data length, Even parity, Stop bit 1
	01: 8-bit data length, Non parity, Stop bit 2
Station address ^{*2*3}	0 to 7F

*1 Adjust the settings with GOT settings.

*2 Do not set to "0".

*3 Select the station address without overlapping with that of other units.

3.5.10 Connecting to MQV

■1. Communication settings

Make the communication settings by operating the key of the control equipment.

Item	Set value
Transmission speed ^{*1}	9600bps, 19200bps, 38400bps
Communication condition selection ^{*1}	00: 8-bit data length, Even parity, Stop bit 1
	01: 8-bit data length, Non parity, Stop bit 2
Station address ^{*2*3}	0 to 127

*1 Adjust the settings with GOT settings.

*2 Do not set to "0".

*3 Select the station address without overlapping with that of other units.

3.5.11 Connecting to MPC

■ 1. Communication settings

Make the communication settings by operating the key of the control equipment.

Item	Set value
Transmission speed ^{*1}	9600bps, 19200bps, 38400bps
Communication condition selection ^{*1}	0: 8-bit data length, Even parity, Stop bit 1
	1: 8-bit data length, Non parity, Stop bit 2
Station address ^{*2*3}	0 to 127

*1 Adjust the settings with GOT settings.

*2 Do not set to "0".

*3 Select the station address without overlapping with that of other units.

3.5.12 Connecting to PBC201-VN2

■ 1. Communication settings

Make the communication settings by operating the key of the control equipment.

Item	Set value
Communication protocol	CPL
Transmission speed ^{*1}	9600bps, 19200bps, 38400bps, 115200bps
Communication condition selection ^{*1} (Fixed 8-bit data length)	0:Even parity, Stop bit 1
	1:Odd parity, Stop bit 1
	2:Non parity, Stop bit 2
Station address ^{*2*3}	0 to 126

*1 Adjust the settings with GOT settings.

*2 Do not set to "0".

*3 Select the station address without overlapping with that of other units.

3.5.13 Connecting to MVF

■ 1. Communication settings

Make the communication settings by operating the switch of the control equipment.

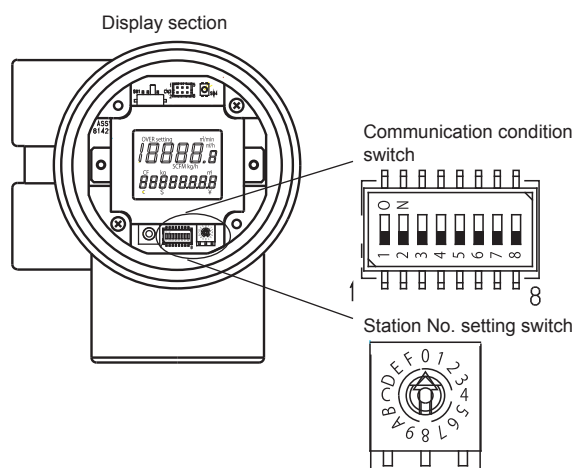
Item	Set value
Transmission speed ^{*1}	9600bps, 19200bps
Communication condition selection ^{*1}	8-bit data length, Even parity, Stop bit 1
	8-bit data length, Non parity, Stop bit 2
Station address ^{*2*3}	0 to F

*1 Adjust the settings with GOT settings.

*2 Do not set to "0".

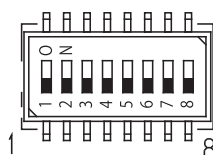
*3 Select the station address without overlapping with that of other units.

2. Settings by switch



(1) Transmission speed settings

Set the communication condition switch.



Transmission speed (bps)	Switch No.		
	1	2	3
9600	ON	ON	OFF
19200	ON	OFF	OFF

(2) Communication condition selection

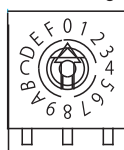
Set the communication condition switch.

Communication condition	Switch No.
	4
8-bit data length, Even parity, Stop bit 1	OFF
8-bit data length, Non parity, Stop bit 2	ON

(3) Station address setting

Set the station address switch.

Station No. setting switch



3.5.14 Connecting to AUR350C, AUR450C

1. Communication settings

Make the communication settings by operating the Smart Loader Package (SLP-A35, SLP-A45) of the control equipment.

Item	Set value
Transmission speed ^{*1}	9600bps, 19200bps
Communication condition selection ^{*1}	8-bit data length, Even parity, Stop bit 1
	8-bit data length, Non parity, Stop bit 2
Station address ^{*2*3}	0 to F

*1 Adjust the settings with GOT settings.

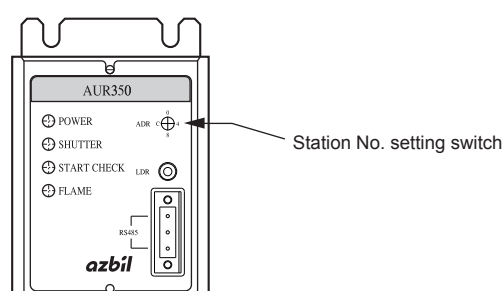
*2 Do not set to "0".

*3 Select the station address without overlapping with that of other units.

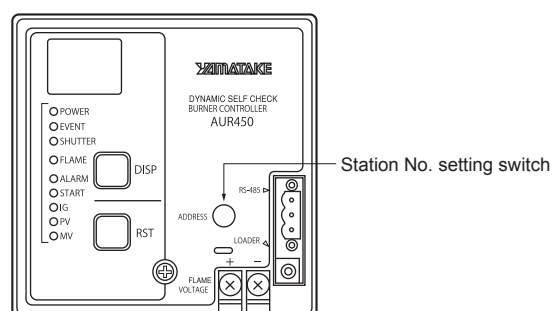
2. Station address setting

Set the station address switch.

(1) For AUR350C



(2) For AUR450C



3.5.15 Connecting to RX

1. Communication settings

Make the communication settings by operating the Smart Loader Package (SLP-RX) of the control equipment.

Item	Set value
Transmission speed ^{*1}	9600bps, 19200bps, 38400bps
Communication condition selection ^{*1}	Even parity stop 1 (8-bit data length, Even parity, Stop bit 1)
	Even parity stop 2 (8-bit data length, Even parity, Stop bit 2)
	Odd parity stop 1 (8-bit data length, Odd parity, Stop bit 1)
	Odd parity stop 2 (8-bit data length, Odd parity, Stop bit 2)
Station address ^{*2*3}	1 to 32

*1 Adjust the settings with GOT settings.

*2 Do not set to "0".

*3 Select the station address without overlapping with that of other units.

3.5.16 Connecting to CMC10B

1. Communication settings

Make the communication settings by operating the Smart Loader Package (SLP-CM1) of the control equipment.

Item	Set value
Transmission speed ^{*1}	9600bps, 19200bps
Communication format ^{*1}	0:8-bit data length, Even parity, Stop bit 1
	1:8-bit data length, Non parity, Stop bit 2
Station address ^{*2*3}	0 to 99

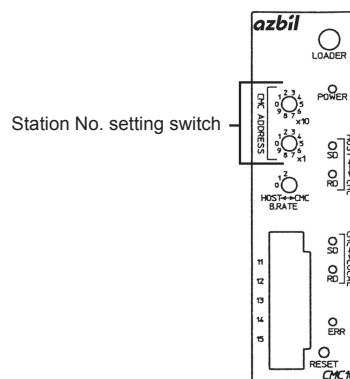
*1 Adjust the settings with GOT settings.

*2 Do not set to "0".

*3 Select the station address without overlapping with that of other units.

2. Station address setting

Set the station address switch.



3.5.17 Connecting to AHC2001 CPU

■ 1. Communication settings

Make the communication settings by operating the Smart Loader Package (SLP-D50/SLP-H21) of the temperature controller.

Item	Set value
Transmission speed ^{*1}	9600bps, 19200bps, 38400bps, 57600bps
Communication mode ^{*2}	0: MODBUS 1: CPL
Data bit	8bits (fixed)
Parity bit	Even (fixed)
Stop bit	1bit (fixed)
Station address ^{*3}	1 to 15 ^{*4}

*1 Adjust the settings with GOT settings.

*2 Set this item to 1: CPL.

*3 Select the station address without overlapping with that of other units.

*4 The station address for AHC2001 ranges from 1 to 127. However, use station address from 1 to 15, which are the range for DMC50.

3.5.18 Connecting to AHC2001 SCU

■ 1. Communication settings

Make the communication settings by operating the Smart Loader Package (SLP-D50/SLP-H21) of the temperature controller.

Item	Set value
Transmission speed ^{*1}	9600bps, 19200bps, 38400bps
Data bit ^{*1}	7bits, 8bits
Parity bit ^{*1}	0: None, 1: Even, 2: Odd
Stop bit ^{*1}	1bit, 2bits
Half duplex/Full duplex ^{*2}	0: Half duplex, 1: Full duplex
Space sending	0 (fixed)
Protocol setup ^{*3}	1 to 30

*1 Adjust the settings with GOT settings.

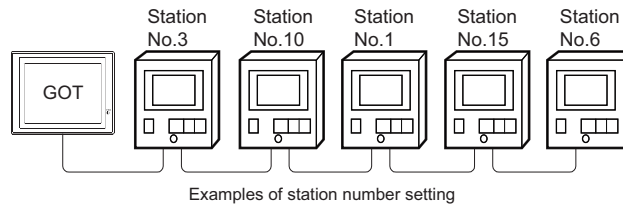
*2 Set this item to 0: Half duplex.

*3 Set this item to 2: CPL.

3.5.19 Station number setting

Set each station number so that no station number overlaps.

The station number can be set without regard to the cable connection order. There is no problem even if station numbers are not consecutive.



1. Direct specification

When setting the device, specify the station number of the control equipment of which data is to be changed.

Model name	Specification range
SDC40A/40B/40G, SDC15, SDC25/26, SDC35/36, SDC20/21, SDC30/31 CML, CMF050, MQV, MPC	1 to 127
PBC201-VN2	1 to 126
SDC45/46	1 to 120
CMS, CMF015, CMC10B	1 to 99
RX	1 to 32
DMC10, DMC50, MVF, AUR350C, AUR450C, AHC2001 ^{*1}	1 to 15

^{*1} The station number for AHC2001 ranges from 1 to 127. However, use station numbers from 1 to 15, which are the range for DMC50.

2. Indirect specification

When setting the device, indirectly specify the station number of the inverter of which data is to be changed using the 16-bit GOT internal data register (GD10 to GD25).

When specifying the station No. from the following table on GT Designer3, the value of GD10 to GD25 compatible to the station No. specification will be the station No. of the control equipment.

Specification station No.		Compatible device	Setting range
DMC50 AHC2001	Other than DMC50		
100	200	GD10	1 to 127: For SDC40A/40B/40G, SDC15, SDC25/26, SDC35/36, SDC20/21, SDC30/31, CML, CMF050, MQV, MPC 1 to 126: PBC201-VN2 1 to 120: SDC45/46 1 to 99: CMS, CMF015, CMC10B 1 to 32: RX 1 to 15: DMC10, DMC50, MVF, AUR350C, AUR450C, AHC2001 ^{*1} For the setting other than the above, error (dedicated device is out of range) will occur.
101	201	GD11	
102	202	GD12	
103	203	GD13	
104	204	GD14	
105	205	GD15	
106	206	GD16	
107	207	GD17	
108	208	GD18	
109	209	GD19	
110	210	GD20	
111	211	GD21	
112	212	GD22	
113	213	GD23	
114	214	GD24	
115	215	GD25	

^{*1} The station number for AHC2001 ranges from 1 to 127. However, use station numbers from 1 to 15, which are the range for DMC50.

3.6 Device Range that Can Be Set

The device ranges of controller that can be used for GOT are as follows.

Note that the device ranges in the following tables are the maximum values that can be set in GT Designer3.

The device specifications of controllers may differ depending on the models, even though belonging to the same series.

Please make the setting according to the specifications of the controller actually used.

When a non-existent device or a device number outside the range is set, other objects with correct device settings may not be monitored.

1. Setting item

For Azbil SDC/DMC Series

For Azbil DMC50

Item	Description	
Device	Set the device name, device number, and bit number. The bit number can be set only when specifying the bit of word device.	
Information	Displays the device type and setting range which are selected in [Device].	
Network	Set the monitor target of the set device.	
	Station	To monitor the control equipment of the specified station No. <ul style="list-style-type: none"> When Azbil SDC/DMC Series is used. 0 to 127 :To monitor the control equipment of the specified station No. 200 to 215 :To specify the station No. of the control equipment to be monitored by the value of GOT data register (GD).^{*1} When Azbil DMC50 is used. 1 to 15: To specify the station No. of the COM module or control equipment to be monitored. 100 to 115: To specify the station No. of the COM module or control equipment to be monitored, and the Sub Station of the control equipment by the value of GOT data register (GD).^{*2}
	Sub Station	Specify the sub station number of the control equipment connected to the COM module specified in [Station] to monitor it. (0 to 15)If the specified [SubStation] is 0, the COM module/control equipment specified in [Station] is monitored. For AHC2001, the sub station number is ignored.
Switch to the device define dialog	Device definition can be checked.	

^{*1} The following shows the relation between station numbers of the control equipment and the GOT data register.

Station No.	GOT data register (GD)	Setting range
200	GD10	0 to 127 (If setting a value outside the range above, a device range error occurs.)
201	GD11	
:	:	
214	GD24	
215	GD25	

- *2 From the value of GD10 to 25, the upper 8bits are set for station No., and the lower 8bits for the Sub Station.
In this case, the setting of [Sub Station] is invalid.
The following shows the relation between station numbers of the control equipment and the GOT data register.

Station No.	GOT data register (GD)	Setting range
100	GD10	0x0000 to 0xFFFF
101	GD11	
:	:	
114	GD24	
115	GD25	

Example: When [Station No.] is set to 100
 When [Station No.] is set to 100, the monitoring target is set based on the GD10 value.
 GD10 = 0x010A
 (Upper 8bits) 0x01 → Station No.: 1
 (Lower 8bits) 0x0A → Sub Station: 10

POINT

Station No. and Sub Station of AZBIL DMC50
 The station No. and Sub Station set when using AZBIL DMC50 correspond to NW No. and Station number of MITSUBISHI PLC, respectively.

3.6.1 AZBIL SDC/DMC Series

Device name		Setting range	Device No. representation
Bit device	The bit specification of the word device	Setting range of each word device	—
Word device	Data (..)*1	..273 to ..31243	Decimal

*1 Only 16-bit (1-word) designation is allowed.

3.6.2 AZBIL DMC50/AHC2001

Device name		Setting range	Device No. representation
Double word device	Network Addresses (NA)*1	0000 to FFFF	Hexadecimal
	Parameter Addresses (PA)*1	00000 to FFFFF	Hexadecimal

*1 Only 32-bit (2-word) designation is allowed.

1. Network Addresses (NA)

The following shows the network address settings and definitions.

Network Addresses	Definition
0000	Network Addresses

■ 2. Parameter Address (PA)

The following shows the parameter address settings and definitions.

Parameter Address	Definition
001	H/W Information
002	Date and Time Setup
021	AI Setup (High resolution type:standard inputs)
022	AI Setup (Special type)
023	AI Setup (High resolution type:option inputs)
041	AUX-IN Setup
045	AO Setup
061	DO Setup
071	TP Setup
0A1	MR20X Communication Setup
0A2	
0A3	
0C1	System Status
0C5	AI Alarm Log
0C3	Date and Time Display
0C4	System Alarm Log
0C6	AUX-IN Alarm Log
0E1	AI Status
0E2	AUX-IN Status
0E3	AO Status
0E5	DI Status
0E6	DO Status
0E7	TP Status
0E8	Zener Barrier Adjustment Counts
0F1	Present MR20X Communication Setup
0F2	
0F3	
103	Memory Usage Monitor
201	PID_A Options Control Action
202	PID_A Constants Proportional Band
203	PID_A Monitor SP
211	PID_CAS Options Control Action
212	PID_CAS Constants (master) Proportional Band
213	PID_CAS Constants (slave) Proportional Band
214	PID_CAS Monitor M_SP
234	Ra_PID Options Ra-PID Mode
235	Ra_PID Constants Proportional Band
236	Ra_PID Monitor SP
241	UP_PID Options Control Action
242	UP_PID Constants Proportional Band
243	UP_PID Monitor U_SP(Use SP)
301	TBL/TBR Setup Contact Point X1
C00	Pattern Setup
C01 to C63	Segment Setup
CF1	Pattern FB Monitor
801 to 9FF	Type label defined by the user

3.7 Precautions

■1. Station number setting of the temperature controller system

- When connecting to DMC10 or SDC
Make sure to establish temperature controller system with No.1 station.
- When connecting to DMC50 or AHC2001
A COM module or temperature controller with the station number set with the host address must be included.

⇒ 3.4.2 Communication detail settings

■2. GOT clock control

Since the control equipment does not have a clock function, the settings of "time adjusting" or "time broad cast" by GOT clock control will be disabled.

■3. Disconnecting some of multiple connected equipment

The GOT can disconnect some of multiple connected equipment by setting GOT internal device. For example, the faulty station where a communication timeout error occurs can be disconnected from connected equipment. For details of GOT internal device setting, refer to the following manual.

⇒ GT Designer3 (GOT2000) Screen Design Manual

■4. When DMC50/AHC2001 and DMC10/SDC are mixed

GOT does not support connections with DMC50/AHC2001 and DMC10/SDC mixed.

■5. Station number range for AHC2001

The station number for AHC2001 ranges from 1 to 127. However, use station numbers from 1 to 15, which are the range for DMC50.

■6. Device range for AHC2001

The GOT only supports some devices for the AHC2001.
Use the devices within the device range for the DMC50.










4. CONNECTION TO OMRON PLC

4.1	Connectable Model List	4 - 2
4.2	Serial Connection	4 - 4
4.3	Ethernet Connection	4 - 48
4.4	Device Range that Can Be Set.	4 - 58

4. CONNECTION TO OMRON PLC

4.1 Connectable Model List

The following table shows the connectable models.

Series	Model name	Clock	Communication Type	Connectable GOT	Refer to
SYSMAC CPM	CPM1	×	RS-232		➡ 4.2.1
	CPM1A	×			
	CPM2A	○			
	CPM2C	○ ^{*3}			
SYSMAC CQM1	CQM1 ^{*1}	○ ^{*4}	RS-232		➡ 4.2.1
SYSMAC CQM1H	CQM1H	○ ^{*4*5}	RS-232 RS-422		➡ 4.2.2
SYSMAC CJ1	CJ1H	○	RS-232 RS-422		➡ 4.2.3
	CJ1G				
	CJ1M				
SYSMAC CJ2	CJ2H	○	RS-232 RS-422		➡ 4.2.3
	CJ2M ^{*9}				
SYSMAC CP1	CP1H	○	RS-232 RS-422		➡ 4.2.4
	CP1L				
	CP1E (N type) ^{*8}				
SYSMAC C200HS	C200HS	○	RS-232 RS-422		➡ 4.2.5
SYSMAC C200H	C200H	○ ^{*6}			
SYSMAC α	C200HX	○	RS-232 RS-422		➡ 4.2.5
	C200HG				
	C200HE ^{*2}	○ ^{*7}			
SYSMAC CS1	CS1H	○	RS-232 RS-422		➡

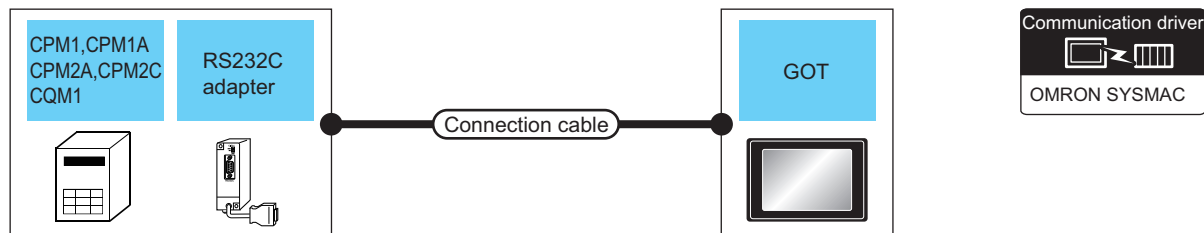
Series	Model name	Clock	Communication Type	Connectable GOT	Refer to
SYSMAC CJ1	CJ1H	○	Ethernet	<div> <div>GT</div> <div>27</div> </div> <div> <div>GT</div> <div>25</div> </div> <div> <div>GT</div> <div>23</div> </div> <div> <div>GT</div> <div>21</div> </div> <div> <div>GS</div> <div>*1</div> </div>	➡ 4.3.1
	CJ1G				
	CJ1M				
SYSMAC CJ2	CJ2H				
	CJ2M				
SYSMAC CS1	CS1H				
	CS1G				
	CS1D				

*1 Not compatible with the redundant Ethernet.







4.2 Serial Connection

4.2.1 System Configuration for connecting to CPM1, CPM1A, CPM2A, CPM2C or CQM1

■ 1. When connecting to PLC or RS-232C



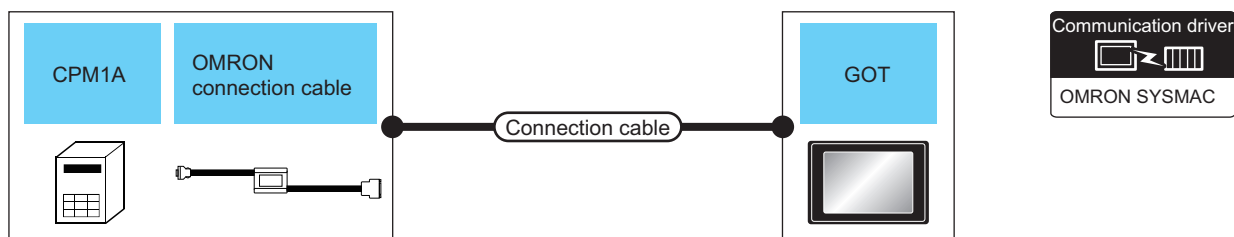
PLC			Connection cable		GOT		Number of connectable equipment
Model name	RS-232C adapter ^{*1}	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model	
CPM2A CQM1	-	RS-232	GT09-C30R20101-9P(3m) or RS-232 connection diagram 1)	15m	- (Built into GOT)		1 GOT for 1 PLC
					GT15-RS2-9P		
					GT10-C02H-6PT9P ^{*2}		
			RS-232 connection diagram 4)	15m	- (Built into GOT)		
CPM1 CPM1A CPM2A CPM2C	CPM1-CIF01	RS-232	GT09-C30R20101-9P(3m) or RS-232 connection diagram 1)	15m	- (Built into GOT)		1 GOT for 1 RS-232C adapter
					GT15-RS2-9P		
					GT10-C02H-6PT9P ^{*2}		
			RS-232 connection diagram 4)	15m	- (Built into GOT)		

PLC			Connection cable		GOT		Number of connectable equipment
Model name	RS-232C adapter ^{*1}	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model	
CPM2C	CPM2C-CIF01-V1	RS-232	GT09-C30R20101-9P(3m) or  RS-232 connection diagram 1)	15m	- (Built into GOT)		1 GOT for 1 RS-232C adapter
					GT15-RS2-9P		
					GT10-C02H-6PT9P ^{*2}		
			 RS-232 connection diagram 4)	15m	- (Built into GOT)		

^{*1} Product manufactured by OMRON Corporation. For details on the product, contact OMRON Corporation.

^{*2} When a GT10-C02H-6PT9P unit of the sub version A or B is used, do not ground the case of the D-sub (9-pin) connector.

■2. When connecting to OMRON connection cable



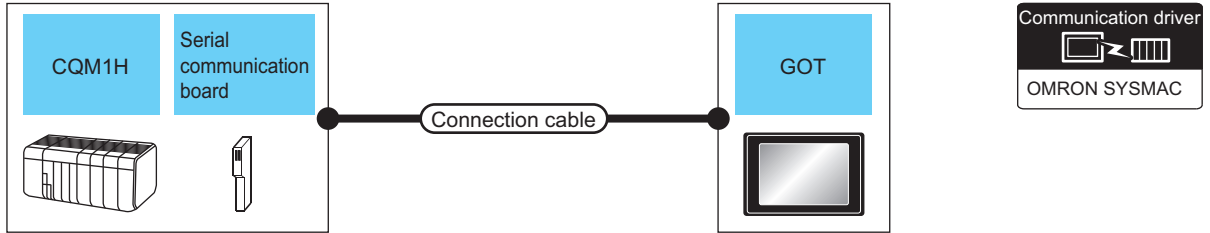
PLC			Connection cable		GOT		Number of connectable equipment
Model name	OMRON connection cable*1	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model	
CPM1A	CQM1-CIF01	RS-232	GT09-C30R20102-25S(3m) or RS-232 connection diagram 2)	15m	- (Built into GOT)		1 GOT for 1 PLC
					GT15-RS2-9P		
					GT10-C02H-6PT9P*2		
			RS-232 connection diagram 5)	15m	- (Built into GOT)		
CPM2C	CPM2C-CN111	RS-232	GT09-C30R20101-9P(3m) or RS-232 connection diagram 1)	15m	- (Built into GOT)		1 GOT for 1 PLC
					GT15-RS2-9P		
					GT10-C02H-6PT9P*2		
			RS-232 connection diagram 4)	15m	- (Built into GOT)		

*1 Product manufactured by OMRON Corporation. For details on the product, contact OMRON Corporation.







*2 When a GT10-C02H-6PT9P unit of the sub version A or B is used, do not ground the case of the D-sub (9-pin) connector.

4.2.2 System Configuration for connecting to CQM1H

■ 1. When connecting to PLC or serial communication board



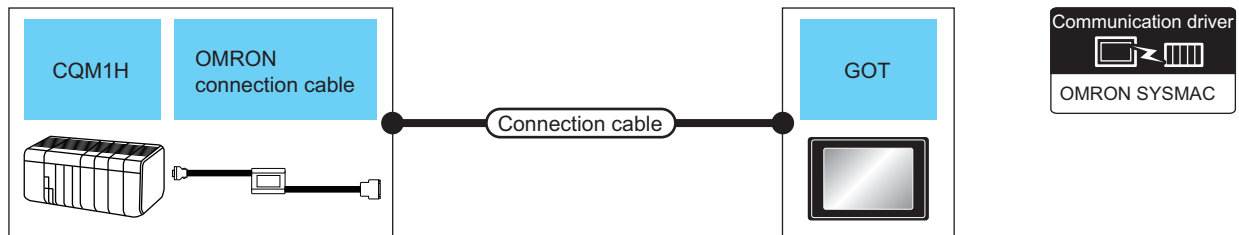
PLC			Connection cable		GOT		Number of connectable equipment
Model name	Serial communication board*1	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model	
CQM 1H	-	RS-232	GT09-C30R20101-9P(3m) or RS-232 connection diagram 1)	15m	-(Built into GOT)		1 GOT for 1 PLC
					GT15-RS2-9P		
					GT10-C02H-6PT9P*2		
			RS-232 connection diagram 4)	15m	-(Built into GOT)		
	CQM1-SCB41	RS-232	GT09-C30R20101-9P(3m) or RS-232 connection diagram 1)	15m	-(Built into GOT)		
					GT15-RS2-9P		
					GT10-C02H-6PT9P*2		
			RS-232 connection diagram 4)	15m	-(Built into GOT)		





PLC			Connection cable		GOT		Number of connectable equipment
Model name	Serial communication board*1	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model	
CQM 1H	CQM1-SCB41	RS-422	GT09-C30R40101-9P(3m) GT09-C100R40101-9P(10m) GT09-C200R40101-9P(20m) GT09-C300R40101-9P(30m) or  RS-422 connection diagram 3)	200m	- (Built into GOT)		1 GOT for 1 serial communication board
					GT15-RS4-9S		
					GT10-C02H-9SC		
			 RS-422 connection diagram 7)	200m	- (Built into GOT)		

*1 Product manufactured by OMRON Corporation. For details on the product, contact OMRON Corporation.

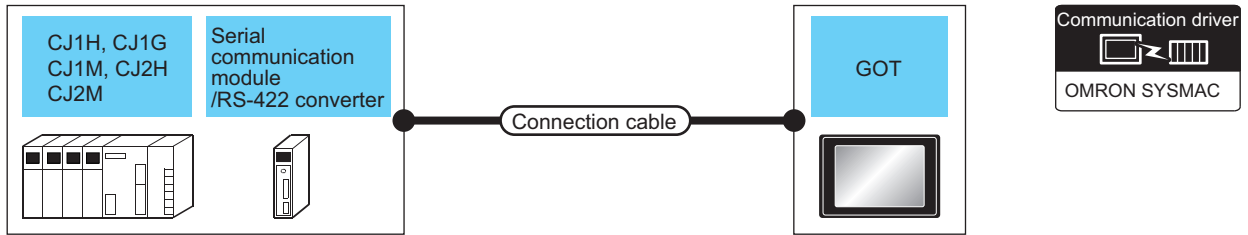
*2 When a GT10-C02H-6PT9P unit of the sub version A or B is used, do not ground the case of the D-sub (9-pin) connector.

■ 2. When connecting to OMRON connection cable
































PLC			Connection cable		GOT		Number of connectable equipment
Model name	OMRON connection cable*1	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model	
CQM 1H	CQM1-CIF02	RS-232	GT09-C30R20101-9P(3m) or  RS-232 connection diagram 1)	15m	- (Built into GOT)		1 GOT for 1 PLC
					GT15-RS2-9P		
					GT10-C02H-6PT9P*2		

4.2.3 System Configuration for connecting to CJ1H, CJ1G, CJ1M, CJ2H, or CJ2M



PLC			Connection cable		GOT		Number of connectable equipment
Model name	Serial communication module/RS-422A converter ^{*1}	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model	
CJ1H CJ1G CJ1M CJ2H	-	RS-232	GT09-C30R20101-9P(3m) or RS-232 connection diagram 1)	15m	- (Built into GOT)		1 GOT for 1 PLC
					GT15-RS2-9P		
					GT10-C02H-6PT9P ^{*2}		
			RS-232 connection diagram 4)	15m	- (Built into GOT)		
	CJ1W-SCU21-V1 CJ1W-SCU41-V1	RS-232	GT09-C30R20101-9P(3m) or RS-232 connection diagram 1)	15m	- (Built into GOT)		
					GT15-RS2-9P		
					GT10-C02H-6PT9P ^{*2}		
			RS-232 connection diagram 4)	15m	- (Built into GOT)		

PLC			Connection cable		GOT		Number of connectable equipment
Model name	Serial communication module/RS-422A converter*1	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model	
CJ1H CJ1G CJ1M CJ2H	CJ1W-SCU31-V1 CJ1W-SCU41-V1	RS-422	GT09-C30R40101-9P(3m) GT09-C100R40101-9P(10m) GT09-C200R40101-9P(20m) GT09-C300R40101-9P(30m) or  RS-422 connection diagram 3)	200m	- (Built into GOT)		1 GOT for 1 PLC
					GT15-RS4-9S		
					GT10-C02H-9SC		
			 RS-422 connection diagram 7)	200m	- (Built into GOT)		
	CJ1W-CIF11	RS-422	GT09-C30R40103-5T(3m) GT09-C100R40103-5T(10m) GT09-C200R40103-5T(20m) GT09-C300R40103-5T(30m) or  RS-422 connection diagram 4)	50m	- (Built into GOT)		1 GOT for 1 RS-422A converter
					GT15-RS4-9S		
					GT10-C02H-9SC		
			 RS-422 connection diagram 8)	50m	- (Built into GOT)		
CJ1H CJ1G CJ1M	CJ1W-SCU21 CJ1W-SCU41	RS-232	GT09-C30R20101-9P(3m) or  RS-232 connection diagram 1)	15m	- (Built into GOT)		1 GOT for each port of a serial communication module
					GT15-RS2-9P		
					GT10-C02H-6PT9P*2		

PLC			Connection cable		GOT		Number of connectable equipment
Model name	Serial communication module/RS-422A converter*1	Communication Type	Cable model Connection diagram number	Max. distance	Option device	Model	
CJ1H CJ1G CJ1M	CJ1W-SCU41	RS-422	GT09-C30R40101-9P(3m) GT09-C100R40101-9P(10m) GT09-C200R40101-9P(20m) GT09-C300R40101-9P(30m) or  RS-422 connection diagram 3)	200m	- (Built into GOT)		1 GOT for each port of a serial communication module
					GT15-RS4-9S		
					GT10-C02H-9SC		
			 RS-422 connection diagram 7)	200m	- (Built into GOT)		
CJ2M-CPU1□	-	RS-232	GT09-C30R20101-9P(3m) or  RS-232 connection diagram 1)	15m	- (Built into GOT)		1 GOT for 1 PLC
					GT15-RS2-9P		
					GT10-C02H-6PT9P*2		
			 RS-232 connection diagram 4)	15m	- (Built into GOT)		
	CJ1W-CIF11	RS-422	GT09-C30R40103-5T(3m) GT09-C100R40103-5T(10m) GT09-C200R40103-5T(20m) GT09-C300R40103-5T(30m) or  RS-422 connection diagram 4)	50m	- (Built into GOT)		1 GOT for 1 RS-422A converter
					GT15-RS4-9S		

